

Programming.

In this tutorial we will calculate the stiffness matrix and load vector corresponding to the pure Neumann problem with homogeneous boundary conditions (see Exercise [16](#)) and an arbitrary mesh of $(0, 1)$:

$$\mathcal{T}_h = \{T_1, \dots, T_{n_h}\} \quad \text{where} \quad T_k = (x_{k-1}, x_k), \\ 0 = x_0 < x_1 < \dots < x_{n_h-1} < x_{n_h} = 1.$$

[19](#) Write a function

```
void ElementStiffnessMatrix (double xa, double xb, Mat22& elMat);
```

which for given nodes $\mathbf{xa}=x_{k-1}$ and $\mathbf{xb}=x_k$ returns the element stiffness matrix $\mathbf{elMat}=K_h^{(k)}$ of the element T_k .

[20](#) Write a function

```
void ElementLoadVector (RealFunction f, double xa, double xb,
                        Vec2& elVec);
```

which for a given function $\mathbf{f}=f \in C[0, 1]$ and the nodes $\mathbf{xa}=x_{k-1}$ and $\mathbf{xb}=x_k$ returns the approximated 2-dimensional element load vector $\mathbf{elVec} \approx f_h^{(k)}$ on the element T_k . Use the trapezoidal rule to approximate the involved integrals.

[21](#) Design a data type **Mesh** to store the mesh information that you need later on to assemble of the stiffness matrix. Make sure that your data type allows

- initializing (e.g. with an equidistant mesh with a certain number of nodes)
- asking for the number of nodes
- asking for the “coordinate” of an arbitrary node

[22](#) Design an *efficient* data type **SMatrix** to store the stiffness matrix later on. Make sure that your data type allows

- initializing (with a certain number of rows=columns and zero entries)
- asking for any entry in the diagonal and the two off-diagonals
- adding a value to a certain entry

[23](#) Write a function

```
void AssembleStiffnessMatrix (const Mesh& mesh, SMatrix& mat);
```

that assembles the $(n_h + 1) \times (n_h + 1)$ stiffness matrix $\mathbf{mat}=K_h$ (see Exercise [16](#)) for a given mesh $\mathbf{mesh}=\mathcal{T}_h$ of $(0, 1)$.

Hint: Set $K_h = 0$, then loop over all elements. For each element, call **ElementStiffnessMatrix** and add the entries of $K_h^{(k)}$ at the correct positions of K_h .

24 Write a function

```
void AssembleLoadVector (RealFunction f, const Mesh& mesh,
                        Vector& vec);
```

that assembles the load vector $\mathbf{vec} = \underline{f}_h$ for the given function $\mathbf{f} = f \in C[0, 1]$ and the given mesh.

Here **Vector** is your favourite vector type (you can for instance use that from `vectors.cc` on the tutorial website).

Hint: Set $\underline{f}_h = 0$, then loop over all elements. For each element, call `ElementLoadVector` and add the entries of the element load vector to the right places.

Test all your functions for

$$f(x) = 2x + 1$$

and at least an equidistant mesh with 20 elements. To see if your functions are correct it might be good to add a *print* function for `SMatrix` that prints the entries to the screen.