

T U T O R I A L

“Computational Mechanics”

to the lecture

“Numerical Methods in Continuum Mechanics 1”

Tutorial 13

Friday, Jun 27, 2008 (Time : 8³⁰ – 9¹⁵ Room : SR T 1010)

5.2 The Hellinger-Reisner Principle

- 44** Let $\bar{u} \in H^{1/2}(\Gamma_u)$ and $\sigma_t \in H(\text{div}, \Omega)$ be given vector and tensor functions. Show, that the functional F defined by the identity

$$\langle F, \tau \rangle := (D^{-1}\sigma_t, \tau)_0 + \int_{\Gamma_u} (\tau n) \cdot \bar{u} \, ds$$

belongs to X_0^* , where $X_0 := \{\sigma \in H(\text{div}, \Omega) \mid \sigma n = 0 \text{ on } \Gamma_t\}$.

- 45** Let $v \in L_2(\Omega)$ be a given vector function. Let $u \in H_{0,\Gamma_u}^1(\Omega)$ such that

$$(\varepsilon(u), \varepsilon(w))_0 = -(v, w)_0 \quad \forall w \in H_{0,\Gamma_u}^1(\Omega)$$

Show, that $\tau := \varepsilon(u)$ is in $X = H(\text{div}, \Omega)$, and that $\text{div } \tau = v$.

- 46*** Consider the definitions in Example **45**. Show, that $\tau_n (= \tau n) = 0$ on Γ_t in the sense

$$\langle \tau n, w \rangle_{H^{-1/2}(\Gamma_t) \times H^{1/2}(\Gamma_t)} = 0 \quad \forall w \in H_{0,\Gamma_u}^1(\Omega).$$