

# ÜBUNGEN ZU NUMERIK ZEITABHÄNGIGER PROBLEME

für den 28.1.2008

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60. Show that the initial value problem

$$\begin{aligned}Bu'(t) + Au(t) &= f(t), \\ u(0) &= u_0\end{aligned}$$

has at most one solution if  $A + \lambda B$  is a regular matrix stencil.

Hint: Consider the homogeneous problem.

61. Show that the initial value problem

$$\begin{aligned}Bu'(t) + Au(t) &= 0, \\ u(0) &= 0\end{aligned}$$

has infinitely many different solutions if  $A + \lambda B$  is not a regular matrix stencil.

Hint: Construct solutions of the form  $u(t) = \sum_i \alpha_i e^{\lambda_i t} v_i$  with distinct values  $\lambda_i$  and vectors  $v_i \neq 0$  satisfying  $(A + \lambda_i B)v_i = 0$ .

62. Let  $N \in \mathbb{R}^{n \times n}$  and  $\nu \in \mathbb{N}$  with  $N^\nu = 0$ . Show:

$$(I - N)^{-1} = \sum_{i=0}^{\nu-1} N^i.$$

63. Consider the following formulation of a constrained mechanical system:

$$\begin{aligned}q' &= u \\ M(q)u' &= f(q, u) - G(q)^T \lambda \\ 0 &= g(q)\end{aligned} \tag{1}$$

with a symmetric positive definite matrix  $M(q) \in \mathbb{R}^{n \times n}$ ,  $G(q) = (\partial g / \partial q)(q) \in \mathbb{R}^{m \times n}$  with full rank  $m \leq n$ . Show that this system is equivalent to the GGL formulation:

$$\begin{aligned}q' &= u - G(q)^T \mu \\ M(q)u' &= f(q, u) - G(q)^T \lambda \\ 0 &= g(q) \\ 0 &= G(q)u.\end{aligned}$$

That means: If  $q(t)$ ,  $u(t)$ ,  $\lambda(t)$  satisfy (1), then  $q(t)$ ,  $u(t)$ ,  $\lambda(t)$ , and  $\mu(t) = 0$  satisfy the GGL formulation. If  $q(t)$ ,  $u(t)$ ,  $\lambda(t)$ , and  $\mu(t)$  satisfy the GGL formulation, then  $q(t)$ ,  $u(t)$ ,  $\lambda(t)$  satisfy (1).

Hint for the second part: Multiply the first equation by  $G(q)$ , compare with the differentiated third equation and the fourth equation and conclude  $\mu(t) = 0$ .

64. Rewrite the GGL formulation as a Hessenberg index 2 system:

$$\begin{aligned}x_1'(t) &= f_1(t, x_1(t), x_2(t)), \\ 0 &= f_2(t, x_1(t))\end{aligned}$$

with a nonsingular matrix

$$\frac{\partial f_2}{\partial x_1}(t, x_1) \frac{\partial f_1}{\partial x_2}(t, x_1, x_2).$$

65. Consider the following optimal control problem for the unknowns  $y$ ,  $p$  and  $u$ :

$$\begin{aligned}y'(t) &= Ay(t) + Bu(t) + f(t), \quad y(0) = y_0, \\ p'(t) &= -A^T p(t) - Cy(t), \quad p(1) = 0, \\ 0 &= B^T p(t) + Du(t)\end{aligned}$$

with positive semi-definite matrices  $C$  and  $D$ . Show:

- (a) If  $D$  is positive definite, then the optimal control problem has index 1.
- (b) If  $D = 0$  and  $B^T C B$  is positive definite, then the optimal control problem has index 3.