

T U T O R I A L

“Numerical Methods for Solving Partial Differential Equations”

to the Lectures on NuPDE

T VII

Monday, 10 December 2007 (Time: 08:30 – 10:00, Room: T 212)

1.9 Conjugate Gradient Method

Let K be a symmetric and positive definite matrix, and let $u^{(n)}$ be an approximation of the exact solution u of the linear system

$$K u = f, \quad (1.25)$$

obtained by the iterative method

$$u^{(n+1)} = u^{(n)} + \alpha^{(n)} p^{(n)} \quad (1.26)$$

where $p^{(n)}$ is a search direction and $\alpha^{(n)} \in \mathbb{R}$.

- [38] Determine the parameter $\alpha^{(n)}$ such that (1.26) satisfies the condition

$$\|f - K u^{(n+1)}\|_{\ell_2} = \min_{v \in u^{(n)} + \text{span}(p^{(n)})} \|f - K v\|_{\ell_2}.$$

- [39] Given $p^{(n-1)}$ and the residual $r^{(n)} = f - K u^{(n)}$, determine the parameter $\beta^{(n-1)} \in \mathbb{R}$, such that the search direction $p^{(n)}$ given by

$$p^{(n)} = r^{(n)} + \beta^{(n-1)} p^{(n-1)}$$

satisfies the condition

$$(K p^{(n)}, K p^{(n-1)})_{\ell_2} = 0.$$

- [40] We consider the so-called *conjugate residual (CR) method*. Given $u^{(n)}$, compute the residual $r^{(0)} = f - K u^{(0)}$. Then, for $n \geq 0$,

$$\begin{aligned} p^{(n)} &= \begin{cases} r^{(0)} & \text{for } n = 0, \\ r^{(n)} + \beta^{(n-1)} p^{(n-1)} & \text{for } n \geq 1, \end{cases} \\ u^{(n+1)} &= u^{(n)} + \alpha^{(n)} p^{(n)}, \\ r^{(n+1)} &= r^{(n)} - \alpha^{(n)} K p^{(n)}. \end{aligned}$$

The parameters $\beta^{(n-1)}$ and $\alpha^{(n)}$ are chosen such that

$$(K p^{(n)}, K p^{(n-1)})_{\ell_2} = 0$$

and

$$\|f - K u^{(n+1)}\|_{\ell_2} = \min_{v \in u^{(n)} + \text{span}(p^{(n)})} \|f - K v\|_{\ell_2}.$$

Prove that

$$(K r^{(n+1)}, p^{(n)})_{\ell_2} = 0 \quad \text{and} \quad (K r^{(n+1)}, r^{(n)})_{\ell_2} = 0.$$

- 41 Write down the conjugate gradient (CG) method to solve equation (1.25) but use the scalar product

$$(w, v)_K := (K w, v)_{\ell_2}$$

instead of the Euclidean scalar product $(w, v)_{\ell_2}$. Show that this special CG method coincides with the CR method.

- 42 Write a function `CG(↓A, ↑x, ↓b, ↓M, ↑max_iter, ↑tol)` to solve the linear system

$$A \underline{x} = \underline{b}$$

by the preconditioned CG method with a preconditioner M and the stopping criterion

$$\|\underline{r}^{(n)}\|_{\ell_2} = \|\underline{b} - A \underline{x}^{(n)}\|_{\ell_2} \leq \varepsilon \|\underline{b}\|_{\ell_2},$$

where $A=A$, $M=M$, $\mathbf{x}=\underline{x}^{(0)}$ in input and $\mathbf{x}=\underline{x}^{(n)}$ in output, $\mathbf{b}=\underline{b}$, $C=C$ and $\text{tol}=\varepsilon$. In input, `max_iter` is the maximal number of iterations. In output, `max_iter`= n returns the number of iterations needed to satisfy the stopping criterion.

Hint: use the template `cg.hpp` and rewrite it for your own purposes.

- 43 Test your CG with the Jacobi preconditioner for the problem in Exercise 29, i.e.,

$$\begin{aligned} -u''(x) &= f(x) & x \in \Omega \\ u(x) &= g_D(x) & x \in \Gamma_D \\ \frac{\partial u}{\partial n}(x) &= 0 & x \in \Gamma_N \end{aligned}$$

with the data $f(x) = 8$, $\Omega = (0, 1)$, $\Gamma_D = \{0\}$, $g_D(x) = -1$, $\Gamma_N = \{1\}$, or a comparable problem of your choice.

cg.hpp

```
// Iterative template routine -- CG
//
// RICHARDSON solves the symmetric positive definite linear
// system Ax=b using the preconditioned conjugate gradient methd.
// The returned value indicates convergence within
// max_iter iterations (return value 0)
// or no convergence within max_iter iterations (return value 1)
// Upon successful return (0), the output arguments have the
// following values:
//      x: computed solution
// mat_iter: number of iterations to satisfy the stopping criterion
//      tol: residual after the final iteration

template <class MATRIX, class VECTOR, class PRECONDITIONER, class REAL>
int
CG (const MATRIX & A, VECTOR & x, const VECTOR & b,
    const PRECONDITIONER & M, int & max_iter, REAL & tol)
{
    REAL resid;
    VECTOR p(b.size ());
    VECTOR z(b.size ());
    VECTOR q(b.size ());
    REAL alpha, beta, rho, rho_1;
```

```

REAL normb = norm (b);
VECTOR r = b - A * x;

if (normb == 0.0) normb = 1;
resid = norm (r) / normb;

if (resid <= tol)
{
    tol = resid;
    max_iter = 0;
    return 0;
}

for (int i=1; i<=max_iter; i++)
{
    z = M.solve (r);
    rho = dot (r, z);

    if (i==1)
    {
        p = z;
    }
    else
    {
        beta = rho / rho_1;
        p = z + beta * p;
    }

    q = A * p;
    alpha = rho / dot (p, q);

    x += alpha * p;
    r -= alpha * q;

    resid = norm(r) / normb;

    if (resid <= tol)
    {
        tol = resid;
        max_iter = i;
        return 0;
    }

    rho_1 = rho;
}

tol = resid;
return 1;
}

```