

### • Example 2.20:

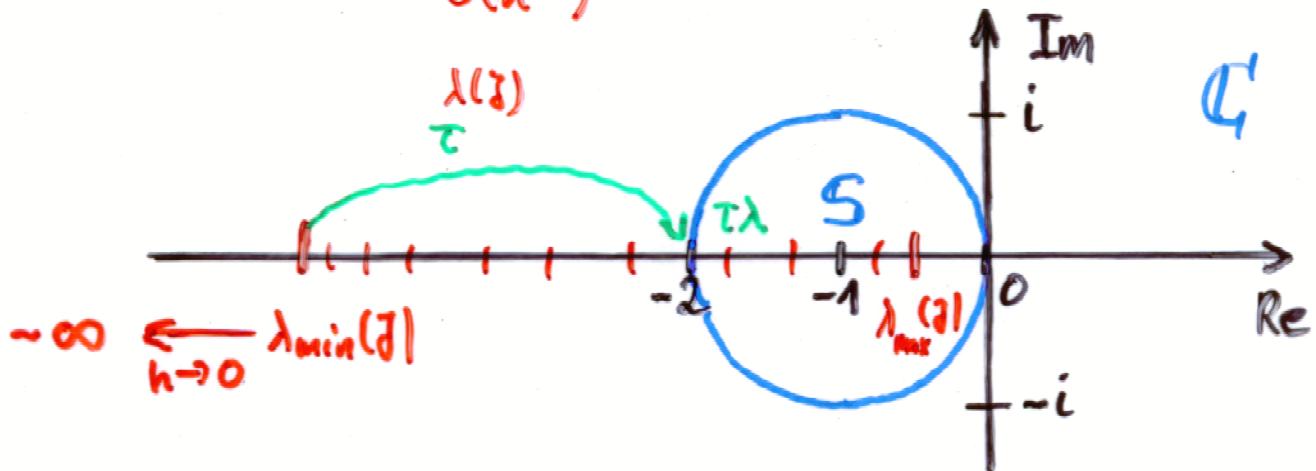
The VML applied to our model problem (5) leads to

$$(6)_h \quad \mathbf{u}'_h(t) = \mathbf{J} \mathbf{u}_h(t) + \mathbf{M}_h^{-1} \mathbf{f}_h(t) \quad \text{with} \quad \mathbf{J} = -\mathbf{M}_h^{-1} \mathbf{K}_h.$$

$\mathbf{K}_h$  and  $\mathbf{M}_h$  are SPD, i.e.  $\sigma(\mathbf{J}) \subset \mathbb{R}^+$ ;

$$-\infty \xleftarrow[h \rightarrow 0]{} \lambda_{\min}(\mathbf{J}) = -\lambda_{\max}(\mathbf{M}_h^{-1} \mathbf{K}_h) \leq \dots \leq \lambda_{\max}(\mathbf{J}) = -\lambda_{\min}(\mathbf{M}_h^{-1} \mathbf{K}_h) < 0$$

$O(h^{-2})$



Stability domain for the explicit Euler method:

$$S = \{z \in \mathbb{C} : |z - (-1)| \leq 1\} = \text{disk centered at } -1 \text{ with radius 1}$$

Thus,  $\tau \lambda \in S \nsubseteq \sigma(\mathbf{J})$  means

$$\tau \lambda_{\min}(\mathbf{J}) = -\tau \lambda_{\max}(\mathbf{M}_h^{-1} \mathbf{K}_h) \geq -2$$

$$(44)$$

$$\tau \leq \frac{2}{\lambda_{\max}(\mathbf{M}_h^{-1} \mathbf{K}_h)}$$

Since  $\lambda_{\max}(\mathbf{M}_h^{-1} \mathbf{K}_h) \leq 12 h^{-2}$  (see (28)), condition (43) is satisfied if

$$\tau \leq h^2 / 6.$$

This is a strong restriction on the time step size  $\tau$ , in particular, if the spatial step size  $h$  is small!