

Variational Inequalities in Elastoplasticity

Seminar – Numerical Analysis of Variational Inequalities

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Notation

- ▶ With \cdot we denote the scalar product of two vector valued quantifiers

$$u \cdot v = u^T v .$$

- ▶ With $:$ we denote the scalar product of two matrix valued quantifiers

$$A : B = \sum_{i,j} a_{ij} b_{ij} .$$

- ▶ With $\|\cdot\|_F$ we denote Frobenius' norm of respectively a matrix or vector valued quantifier, i. e.,

$$\|M\|_F = (M : M)^{1/2} \quad \text{and} \quad \|v\|_F = (v \cdot v)^{1/2} .$$

Linear Elasticity – Classical Formulation

Balance of Momentum	$-\operatorname{div} \boldsymbol{\sigma} = f \quad \text{in } \Omega$
B. Angular Momentum	$\boldsymbol{\sigma} = \boldsymbol{\sigma}^T$
Hook's Law	$\boldsymbol{\sigma} = \mathbb{C} \boldsymbol{\varepsilon}$
Linearized Strain	$\boldsymbol{\varepsilon}(u) = \frac{1}{2} (\nabla u + (\nabla u)^T)$
Boundary Conditions	$u = u_D \quad \text{on } \Gamma_D \quad \text{and} \quad \boldsymbol{\sigma} n = g \quad \text{on } \Gamma_N$

What is Different in Elastoplasticity?

An elastoplastic problem is time dependent, i. e.,

$$u = u(x,t), \sigma = \sigma(x,t), f = f(x,t), \text{ etc. for } (x,t) \in \Omega \times [0, \mathbf{T}].$$

The balance of momentum would then read

$$\rho \ddot{u} - \operatorname{div} \sigma = f \quad \text{in } \Omega \times [0, \mathbf{T}].$$

Accelerations \ddot{u} are considered to be very small, such that they can be neglected and we have to solve

$$-\operatorname{div} \sigma = f \quad \text{in } \Omega \times [0, \mathbf{T}].$$

A problem of such kind is said to be *quasistatic*.

What Else is Different in Elastoplasticity?

The strain ε is additively split into parts

$$\varepsilon = e + p.$$

We denote e the *elastic strain*, and p the *plastic strain*. Only the elastic strain is associated with the stress tensor by Hook's law

$$\sigma = \mathbb{C}e = \mathbb{C}(\varepsilon - p).$$

We further prescribe the initial conditions

$$u(x, 0) = u_0(x) \quad \text{and} \quad \sigma(x, 0) = \sigma_0(x).$$

Elastoplasticity – Classical Formulation

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Initial Conditions	$u(x, 0) = u_0(x) \quad \text{and} \quad \boldsymbol{\sigma}(x, 0) = \boldsymbol{\sigma}_0(x)$

Missing Conditions

- ▶ unknowns: displacement u , plastic strain p .
- ▶ We need more prescriptions to determine the plastic strain p .
- ▶ Physics: $\sigma = \mathbb{C}(\varepsilon - p)$ must satisfy an **admissibility condition**.
- ▶ Physics: Time development of p given by the **plastic flow law**.

Admissibility Condition for the Stress σ

We introduce a convex mapping ϕ into \mathbb{R} , which steers by the relation

$$\phi(\sigma) \leq 0,$$

if a stress σ is allowed or not. The zero-level set of ϕ ,

$$K = \{(\Sigma) : \phi(\Sigma) \leq 0\},$$

is called the *set of admissible states*.

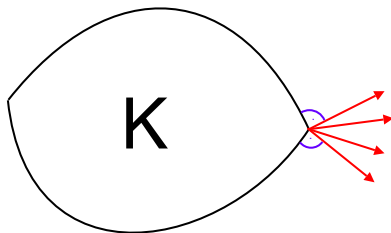
Plastic Flow Law for the Plastic Strain p

The plastic flow law states, that

$$\dot{\Pi} = (\dot{p}, \dot{\xi}) \in \mathcal{N}_K(\Sigma),$$

where $\mathcal{N}_K(\Sigma)$ denotes the normal cone of K in (Σ) :

$$\mathcal{N}_K(\Sigma) = \{n : \langle n, \Theta - \Sigma \rangle \leq 0 \quad \forall \Theta \in K\}.$$



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Initial Condition	$u(x, 0) = 0, \quad \boldsymbol{\sigma}(x, 0) = 0$
Constitution	$\boldsymbol{\chi} = -\mathbb{H} \boldsymbol{\xi}$
Admissibility	$\phi(\boldsymbol{\sigma}, \boldsymbol{\chi}) \leq 0$
Plastic Flow	$\langle (\dot{p}, \dot{\boldsymbol{\xi}}), (\boldsymbol{\theta}, \boldsymbol{\rho}) - (\boldsymbol{\sigma}, \boldsymbol{\chi}) \rangle \leq 0 \quad \forall \boldsymbol{\theta}, \boldsymbol{\rho}$

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Admissibility $\phi(\boldsymbol{\sigma}, \boldsymbol{\chi}) \leq 0$

Plastic Flow $\langle (\dot{p}, -\mathbb{H}^{-1} \dot{\boldsymbol{\chi}}), (\boldsymbol{\theta}, \boldsymbol{\rho}) - (\boldsymbol{\sigma}, \boldsymbol{\chi}) \rangle \leq 0 \quad \forall \boldsymbol{\theta}, \boldsymbol{\rho}$

Equivalent Subgradient Condition

- ▶ We define the *dissipation functional* D_ϕ by

$$D_\phi(\Sigma) = \begin{cases} 0 & \text{if } \phi(\Sigma) \leq 0, \\ +\infty & \text{else,} \end{cases}$$

- ▶ and the *subgradient* of a function f as the set

$$\partial f(x) = \{g : f(y) \geq f(x) + \langle g, y - x \rangle \quad \forall y\}.$$

Then, one can show:

$$\underbrace{[\dot{\Pi} \in \mathcal{N}_K(\Sigma)] \wedge [\phi(\Sigma) \leq 0]}_{\text{dual formulation}} \Leftrightarrow \underbrace{\dot{\Pi} \in \partial D_\phi(\Sigma)}_{\text{primal formulation}} .$$

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Primal $\langle (\dot{p}, -\mathbb{H}^{-1}\dot{\chi}), (\theta, \rho) - (\boldsymbol{\sigma}, \boldsymbol{\chi}) \rangle + D_\phi(\boldsymbol{\sigma}, \boldsymbol{\chi}) \leq D_\phi(\theta, \rho) \quad \forall \theta, \rho$

Dual $[(\boldsymbol{\sigma}, \boldsymbol{\chi}) \in K] \wedge [\langle (\dot{p}, -\mathbb{H}^{-1}\dot{\chi}), (\theta, \rho) - (\boldsymbol{\sigma}, \boldsymbol{\chi}) \rangle \leq 0 \quad \forall (\theta, \rho) \in K]$

Conjugate Function

Definition (Conjugate Function)

Let X be a Banach space, X^* its topological dual, and $f \in X^*$. Then, the function $f^* : H^* \rightarrow \mathbb{R}$ is said to be *conjugate* to f if for all $x^* \in X^*$ there holds

$$f^*(x^*) = \sup_{x \in X} (\langle x^*, x \rangle - f(x)).$$

Theorem

Let some assumptions be satisfied. Then there holds

$$x^* \in \partial f(x) \Leftrightarrow x \in \partial f^*(x^*).$$

Equivalent Primal Formulation

$$\begin{aligned}
\langle (\dot{p}, -\mathbb{H}^{-1}\dot{\chi}), (\theta, \rho) - (\sigma, \chi) \rangle + D_\phi(\sigma, \chi) &\leq D_\phi(\theta, \rho) \quad \forall \theta, \rho \\
\Leftrightarrow (\dot{p}, -\mathbb{H}^{-1}\dot{\chi}) &\in \partial D_\phi(\sigma, \chi) \\
\Leftrightarrow (\sigma, \chi) &\in \partial D_\phi^*(\dot{p}, -\mathbb{H}^{-1}\dot{\chi}) \\
\Leftrightarrow \langle (\sigma, \chi), (q, \rho) - (\dot{p}, -\mathbb{H}^{-1}\dot{\chi}) \rangle + D_\phi^*(\dot{p}, -\mathbb{H}^{-1}\dot{\chi}) &\leq D_\phi^*(q, \rho) \quad \forall q, \rho \\
\Leftrightarrow \langle (\sigma, -\mathbb{H}\xi), (q, \rho) - (\dot{p}, \dot{\xi}) \rangle + D_\phi^*(\dot{p}, \dot{\xi}) &\leq D_\phi^*(q, \rho) \quad \forall q, \rho \\
\Leftrightarrow \sigma : (q - \dot{p}) - \mathbb{H}\xi \cdot (\rho - \dot{\xi}) + D_\phi^*(\dot{p}, \dot{\xi}) &\leq D_\phi^*(q, \rho) \quad \forall q, \rho
\end{aligned}$$

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Initial Condition	$u(x, 0) = 0, \quad \boldsymbol{\sigma}(x, 0) = 0$

$$\text{Primal} \quad \boldsymbol{\sigma} : (q - \dot{p}) - \mathbb{H} \boldsymbol{\xi} \cdot (\boldsymbol{\rho} - \dot{\boldsymbol{\xi}}) + D_\phi^*(\dot{p}, \dot{\boldsymbol{\xi}}) \leq D_\phi^*(q, \boldsymbol{\rho}) \quad \forall q, \boldsymbol{\rho}$$

$$\text{Dual} \quad [(\boldsymbol{\sigma}, \boldsymbol{\chi}) \in K] \wedge [\langle (\dot{p}, -\mathbb{H} \dot{\boldsymbol{\chi}}), (\boldsymbol{\theta}, \boldsymbol{\rho}) - (\boldsymbol{\sigma}, \boldsymbol{\chi}) \rangle \leq 0 \quad \forall (\boldsymbol{\theta}, \boldsymbol{\rho}) \in K]$$

Function Spaces

- ▶ $V = [H^1(\Omega)]^3$
- ▶ $V_D = \{v \in V : v = u_D \text{ on } \Gamma_D\}$
- ▶ $V_0 = \{v \in V : v = 0 \text{ on } \Gamma_D\}$
- ▶ $Q = [L_2(\Omega)]_{\text{sym}}^{3 \times 3}$
- ▶ $u \in V_D; \quad \dot{u} \in V_0; \quad p, \sigma \in Q; \quad \chi, \xi \in [L_2(\Omega)]^m$

Primal Variational Formulation

The unknowns are (u, p, ξ) . Integration of the primal condition yields

$$\begin{aligned} \int_{\Omega} D_{\phi}^*(\dot{p}, \dot{\xi}) \, dx + \int_{\Omega} \left[\mathbb{C}(\varepsilon(u) - p) : (q - \dot{p}) - \mathbb{H}\xi \cdot (\rho - \dot{\xi}) \right] \, dx \\ \leq \int_{\Omega} D_{\phi}^*(q, \rho) \, dx \quad \forall (q, \rho) \in Q \times L_2(\Omega). \end{aligned}$$

Next we multiply the balance law with $v - \dot{u}$, where $v \in V_D$, combine it with $\sigma = \mathbb{C}(\varepsilon(u) - p)$ and integrate by parts:

$$\begin{aligned} \int_{\Omega} \mathbb{C}(\varepsilon(u) - p) : (\varepsilon(v) - \varepsilon(\dot{u})) \, dx = \int_{\Omega} f \cdot (v - \dot{u}) \, dx + \int_{\Gamma_N} g \cdot (v - \dot{u}) \, ds \\ \forall v \in V_D. \end{aligned}$$

Abstract Primal Variational Formulation

We define

- ▶ $w = (u, p, \xi) \in V_D \times Q \times L_2(\Omega)$
- ▶ $z = (v, q, \rho) \in V_0 \times Q \times L_2(\Omega)$
- ▶ $a_1(w, z) = \int_{\Omega} [\mathbb{C}(\varepsilon(u) - p) : q - \mathbb{H}\xi \cdot \rho] \, dx$
- ▶ $a_2(w, z) = \int_{\Omega} \mathbb{C}(\varepsilon(u) - p) : \varepsilon(v) \, dx$
- ▶ $a(w, z) = a_1(w, z) + a_2(w, z)$
- ▶ $j(z) = \int_{\Omega} D_{\phi}^*(q, \rho) \, dx$
- ▶ $l(z) = \int_{\Omega} f \cdot v \, dx + \int_{\Gamma_N} g \cdot v \, ds$

Abstract Primal Variational Formulation

Then we have to solve:

Problem

Find $w \in V_D \times Q \times L_2(\Omega)$ with $w \in V_0 \times Q \times L_2(\Omega)$ such, that for all $z \in V_0 \times Q \times L_2(\Omega)$ there hold

$$\begin{aligned} a_1(w, \dot{w} - z) + j(\dot{w}) - j(z) &\leq 0 \quad \forall z, \\ a_2(w, \dot{w} - z) + l(\dot{w} - z) &= 0 \quad \forall z, \end{aligned}$$

or equivalently (elementary calculation)

$$a(w, \dot{w} - z) + j(\dot{w}) - j(z) + l(\dot{w} - z) \leq 0 \quad \forall z.$$

Problem to show unique solvability: **time derivatives**.

Time Discretization

- ▶ $[0, T] \rightsquigarrow \{0 = t_0, t_1, t_2, \dots, t_{n-1}, t_n = T\}$
- ▶ $t_i - t_{i-1} = k \quad \forall i \in 1, \dots, n$
- ▶ define $w_i(x) = w(x, t_i)$ and $z_i(x) = z(x, t_i)$ a.e.
- ▶ approximate $\dot{w}_i \approx \frac{w_i - w_{i-1}}{k}$
- ▶ define $z_i = z + w_{i-1} \in V_D!$
- ▶ redefine a_1, a_2, j and l properly

Problem

Find $w_i \in V_D \times Q \times L_2(\Omega)$ such, that for all $z \in V_D \times Q \times L_2(\Omega)$ there hold

$$a(w_i, w_i - z) + j(w_i) - j(z) + l(w_i - z) \leq 0 \quad \forall z \in V_D \times Q \times L_2(\Omega).$$

Dual Variational Formulation

In the classical formulation of the dual problem, we prescribed $(\sigma, \chi) \in K$ and

$$\langle (\dot{p}, -\mathbb{H}\dot{\chi}), (\theta, \rho) - (\sigma, \chi) \rangle \leq 0 \quad \forall (\theta, \rho) \in K.$$

The latter condition can be reformulated due to $\dot{p} = \dot{\varepsilon} - \mathbb{C}^{-1} \dot{\sigma}$,

$$\langle (\dot{\varepsilon} - \mathbb{C}^{-1} \dot{\sigma}, -\mathbb{H}\dot{\chi}), (\theta, \rho) - (\sigma, \chi) \rangle \leq 0 \quad \forall (\theta, \rho) \in K.$$

Thus, the unknown variables are (u, σ, χ) .

Dual Variational Formulation

We define

- ▶ $\mathcal{K} = \{(\theta, \rho) \in Q \times [L_2(\Omega)]^m : (\theta(x), \rho(x)) \in K \text{ a.e.}\}$
- ▶ $a(\sigma, \theta) = \int_{\Omega} \sigma : \mathbb{C}^{-1} \theta \, dx$
- ▶ $b(v, \theta) = - \int_{\Omega} \varepsilon(v) : \theta \, dx$
- ▶ $c(\chi, \rho) = \int_{\Omega} \chi \cdot \mathbb{H}^{-1} \rho \, dx$
- ▶ $l(v) = - \int_{\Omega} f \cdot v \, dx - \int_{\Gamma_N} g \cdot v \, ds$

and obtain

Problem

Find $(u, \sigma, \chi) \in V_D \times Q \times [L_2(\Omega)]^m$ such, that $(\sigma, \chi) \in \mathcal{K}$ and

$$b(v, \sigma) = l(v) \quad \forall v, \in V_0$$

$$a(\dot{\sigma}, \sigma - \theta) + c(\dot{\chi}, \chi - \rho) + b(\dot{u}, \sigma - \theta) \leq 0 \quad \forall (\theta, \rho) \in \mathcal{K} .$$

Thank you for your attention!