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## 3.4. A priori Discretization Error Estimates

### 3.4.1. Road Map for the Error Analysis

#### Starting Point

= Cea's theorem (Lemma) [see NuPDE]

with  $V = H^1(\Omega) = W_2^1(\Omega)$ ,  $\|\cdot\| = \|\cdot\|_1 = \|\cdot\|_{H^1(\Omega)}$ , i.e.  
for scalar 2nd order PDEs:

$$(15) \quad \underbrace{\|u - u_h\|_1}_{(1) \quad (1)_h} \leq \frac{\mu_2}{\mu_1} \underbrace{\inf_{v_h \in \bar{V}_{gh}} \|u - v_h\|_1}_u$$

discretization error                      approximation error

Proof is based on the so-called Galerkin orthogonality:

$$\begin{aligned} (1) \quad u \in \bar{V}_g &: a(u, w_h) = \langle F, w_h \rangle \quad \forall w_h \in V_{oh} \subset \bar{V}_0 \\ - \quad u_h \in \bar{V}_{gh} &: a(u_h, w_h) = \langle F, w_h \rangle \quad \forall w_h \in V_{oh} \end{aligned}$$

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**GO**                       $a(u - u_h, w_h) = 0 \quad \forall w_h \in V_{oh}$

Choose  $w_h = u - u_h - (u - v_h) = v_h - u_h \in V_{oh} \quad \forall v_h \in \bar{V}_{gh}$

$$\mu_1 \|u - u_h\|_1^2 \leq a(u - u_h, u - u_h) = a(u - u_h, u - v_h) \leq \mu_2 \|u - u_h\|_1 \|u - v_h\|_1$$

$$\Rightarrow \|u - u_h\|_1 \leq \frac{\mu_2}{\mu_1} \|u - v_h\|_1 \quad \forall v_h \in \bar{V}_{gh}. \quad \text{q.e.d.}$$



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$$\begin{aligned} \|\bullet\|_{1,\Omega}^2 &= \sum_r \|\bullet\|_{1,\delta_r}^2 = \sum_r \int_{\delta_r} [\dots] dx = \\ &\stackrel{x=x_{\delta_r}(\xi)}{\cong} \sum_r \int_{\Delta} [\dots] |J_{\delta_r}| d\xi \\ &\leq \sum_r c h^2 \|\bullet\|_{1,\Delta}^2 \leq \dots \leq h^2 \end{aligned}$$

estimation of the interpolation error on the master element  $\Delta$  with the help of the BRAMBLE-HILBERT Lemma 2.17!

- Result  $\approx$  a priori discretization error estimate w.r.t. the  $\|\bullet\|_1$ -norm ( $H^1$ -norm), see Subsections 3.4.2 and 3.4.3!

■ A priori error estimates with respect to (w.r.t.) other norms are also interesting:

- $L_2$ -norm  $\|\bullet\|_{L_2(\Omega)} = \|\bullet\|_{0,\Omega} \rightarrow 3.4.4.$
- $L_\infty$ -norm  $\|\bullet\|_{L_\infty(\Omega)} = \|\bullet\|_{0,\infty,\Omega} \rightarrow 3.4.5.$
- $W_\infty^1$ -norm  $\|\bullet\|_{W_\infty^1(\Omega)} = \|\bullet\|_{1,\infty,\Omega} \rightarrow 3.4.5.$
- $L_p$ -norm  $\|\bullet\|_{L_p(\Omega)} = \|\bullet\|_{0,p,\Omega} \rightarrow$  literature
- $W_p^1$ -norm  $\|\bullet\|_{W_p^1(\Omega)} = \|\bullet\|_{1,p,\Omega} \rightarrow$  literature
- $\vdots$

- Goal-oriented estimates:  $l \in V_0^*$  or  $l \in (V_0 \cap H^2)^*$   
 $|l(u) - l(u_h)| = |l(u - u_h)| \leq h^2$  (a priori!).  
 See also Section 3.6: a posteriori error estimates!

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### 3.4.2. The Approximation Theorem

#### ■ Theorem 3.6: (approximation theorem)

Ass.: 1. Let the bounded Lipschitz domain  $\Omega \subset \mathbb{R}^d$  be provided with a regular triangulation in the sense of Def. 3.3, i.e.

$$\forall h \in \mathcal{H}: \bar{\Omega} = \bigcup_{r \in \mathbb{R}_h} \delta_r, \quad \delta_r \xrightleftharpoons[\xi = \xi_{\delta_r}(x)]{x = x_{\delta_r}(\xi)} \Delta \quad \forall r \in \mathbb{R}_h:$$

$h \rightsquigarrow h_r$   
Shape reg.

$$(8) \quad c_1 h_r^d \leq |\delta_r| \leq \bar{c}_1 h_r^d \quad \forall \xi \in \bar{\Delta} \quad \forall r \in \mathbb{R}_h,$$

$$(9) \quad \|\delta_r\| := (\lambda_{\max}(\delta_r^T \delta_r))^{1/2} \leq c_2 h_r \quad -||- \quad |$$

$$(10) \quad \|\delta_r^{-T}\| = \|\delta_r^{-1}\| \leq c_3 h_r^{-1} \quad -||- \quad |$$

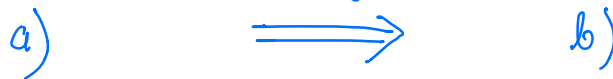
where, for the time being,  $x_{\delta_r}(\cdot) \in \mathcal{P}_1(\Delta)$ , i.e.

an affine linear mapping (see Remark 3.7 for generalizations).

$A \rightsquigarrow A_r$   
 $s \rightsquigarrow s_r$

2.  $S(\Delta) = \text{span}\{p^{(\alpha)} : \alpha \in A\} \supset \mathcal{P}_k(\Delta)$ ,

3.  $u \in W_2^{k+1}(\Omega)$ , or more general,  $u \in W_2^{k+1}(\delta_r) \quad \forall r \in \mathbb{R}_h \quad \forall h \in \mathcal{H}$ .



St.:  $\exists \tilde{a}_{s, k+1} = \text{const} > 0$  (independent of  $h$  and  $u$ ):

$$(18) \quad \inf_{v_h \in \tilde{V}_h} |u - v_h|_{s, \Omega} \stackrel{b)}{\leq} \tilde{a}_{s, k+1} \left[ \sum_{r \in \mathbb{R}_h} h_r^{2(k+1-s)} |u|_{k+1, \delta_r}^2 \right]^{1/2} \stackrel{b)}{\leq} a_{s, k+1} \left[ \sum_{r \in \mathbb{R}_h} h_r^{2(k+1-s)} |u|_{k+1, \delta_r}^2 \right]^{1/2} \stackrel{a)}{=} a_{s, k+1} h^{k+1-s} |u|_{k+1, \Omega}, \quad a)$$

where  $s = 0, 1$ , or  $s \in [0, 1]$  (interpolation theory).

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Proof: Without loss of generality (WLOG), we prove the theorem for the case:

$d=2, k=1, \Delta = \mathbb{T}$ , i.e.  $S(\Delta) = \mathbb{P}_1, s=1$  ( $s=0$ : mms), i.e.

$$(18)_{d,2} \quad \inf_{v_h \in \mathcal{V}_h} \|u - v_h\|_{1,\Omega} \leq \alpha_{d,2} h \|u\|_{2,\Omega}. \quad a)$$

• Thus, let  $u \in W_2^2(\Omega) = H^2(\Omega)$  and  $\Omega \subset \mathbb{R}^2 \neq \emptyset, \partial\Omega \in C^{0,1}$ .

It follows from Sobolev's embedding Theorem 2.26 that

$$W_p^{k+1}(\Omega) \hookrightarrow C^0(\bar{\Omega}) \text{ if } (k+1)p > d,$$

i.e., for  $p=2$ , we always have

$$(k+1) \cdot 2 \geq 4 > d=1,2,3 \text{ for } k=1,2,\dots$$

Therefore:  $W_2^2(\Omega) = H^2(\Omega) \hookrightarrow C^0(\bar{\Omega})$ , i.e.,

in particular,  $\exists C_E = C_E(\Omega) = \text{const} > 0$ :

$$(19)_{\Omega} \quad \boxed{\max_{x \in \bar{\Omega}} |u(x)| \leq C_E \|u\|_{2,\Omega} \quad \forall u \in W_2^2(\Omega)}$$

• Now the proof consists of 4 steps:

1. Insert the interpolant

$$v_h(x) = \text{int}_{\mathcal{V}_h}(u)(x) := \sum_{i \in \bar{\omega}_h} u(x^{(i)}) p^{(i)}(x) \in \mathcal{V}_h$$

into the infimum (18):

$$\stackrel{s=1}{\Rightarrow} \underbrace{\inf_{v_h \in \mathcal{V}_h} \|u - v_h\|_{1,\Omega}}_{\text{approximation error}} \leq \underbrace{\|u - \text{int}_{\mathcal{V}_h}(u)\|_{1,\Omega}}_{\text{interpolation error}}$$

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2. Mapping:  $\delta_r \rightarrow \Delta$

$$\underbrace{\|u - \text{int}_{V_n}(u)\|_{1,\Omega}^2}_{=: e_n} = \sum_{r \in \mathbb{R}_h} \int_{\delta_r} |\nabla_x e_n(x)|^2 dx$$

$$\nabla_x = J_{\delta_r}^{-T} \nabla_\xi \quad (\text{see Subsect. 3.2.4})$$

$$= \sum_{r \in \mathbb{R}_h} \int_{\Delta} |J_{\delta_r}^{-T} \nabla_\xi e_n(x_{\delta_r}(\xi))|^2 |J_{\delta_r}| d\xi$$

(8)  $\tilde{c}_1 h_r^d \leq |J_{\delta_r}| \leq \bar{c}_1 h_r^d$   
 (10)  $\|J_{\delta_r}^{-T}\| \leq \tilde{c}_3 h_r^{-1}$   
 $\alpha_0 h \leq h_r \leq h \leq \frac{\alpha_0}{\alpha_1} h^{-1}$   
 $h_r^{-1} \leq \frac{1}{\alpha_0} h^{-1} = \tilde{c}_3$

$$\leq \bar{c}_1 \tilde{c}_3^2 \sum_{r \in \mathbb{R}_h} h^{d-2} \underbrace{\int_{\Delta} |\nabla_\xi e_n(x_{\delta_r}(\xi))|^2 d\xi}_{=: |e_n(x_{\delta_r}(\xi))|_{1,\Delta}^2} \leq$$

3. Application of Bramble-Hilbert's Lemma 2.17  
on the master (= reference) element  $\Delta$ :

(20)  $|e_n(x_{\delta_r}(\xi))|_{1,\Delta} \leq c_B |u(x_{\delta_r}(\xi))|_{2,\Delta}^{k+1,\Delta} \quad (\downarrow) \quad L16$

$$\leq \bar{c}_1 \tilde{c}_3^2 c_B^2 \sum_{r \in \mathbb{R}_h} h_r^{d-2} \int_{\Delta} \sum_{|\alpha|=2}^{k+1} |\partial_\xi^\alpha u(x_{\delta_r}(\xi))|^2 d\xi =$$

$d=2:$   $= \int_{\Delta} \left\{ \left(\frac{\partial^2 u}{\partial \xi_1^2}\right)^2 + 2 \left(\frac{\partial^2 u}{\partial \xi_1 \partial \xi_2}\right)^2 + \left(\frac{\partial^2 u}{\partial \xi_2^2}\right)^2 \right\} d\xi_1 d\xi_2$

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4. Return mapping:  $\Delta \rightarrow \delta_r$

$$= \bar{c}_1 \tilde{c}_3^2 c_B^2 \sum_{r \in \mathbb{R}_h} h_r^{d-2} \int_{\delta_r} \sum_{|\alpha|=2}^{k+1} |\partial_x^\alpha u(x)|^2 \underbrace{|\mathcal{J}_{\delta_r}^{-1}|}_{= 1/|\mathcal{J}_{\delta_r}|} dx$$

$$\nabla_x^T \otimes \nabla_x = \begin{pmatrix} \frac{\partial^2}{\partial x_1^2} \\ \frac{\partial^2}{\partial x_1 \partial x_2} \\ \frac{\partial^2}{\partial x_2 \partial x_1} \\ \frac{\partial^2}{\partial x_2^2} \end{pmatrix}$$

$$\begin{aligned} \sum_{|\alpha|=2}^{k+1} |\partial_x^\alpha u(x)|^2 &= |\nabla_x^T \otimes \nabla_x u|^2 = |\mathcal{J}_{\delta_r}^T \nabla_x \otimes \mathcal{J}_{\delta_r}^T \nabla_x u|^2 \\ (21) \quad &\stackrel{2(k+1)}{\leq} \|\mathcal{J}_{\delta_r}^T\|^4 \|\nabla_x \otimes \nabla_x u\|^2 = \|\mathcal{J}_{\delta_r}\|^4 \sum_{|\alpha|=2} |\partial_x^\alpha u|^2 \end{aligned}$$

$$\leq \bar{c}_1 \tilde{c}_3^2 c_B^2 \sum_{r \in \mathbb{R}_h} h_r^{d-2} \tilde{c}_1^{-1} h_r^{-d} c_2^4 h_r^4 \int_{\delta_r} \sum_{|\alpha|=2} |\partial_x^\alpha u(x)|^2 dx$$

$$= \underbrace{\frac{\bar{c}_1}{\tilde{c}_1} \tilde{c}_3^2 c_B^2 c_4^4}_{\tilde{a}_{1,2}^2} \sum_{r \in \mathbb{R}_h} h_r^2 \int_{\delta_r} \sum_{|\alpha|=2} |\partial_x^\alpha u|^2 dx$$

$$\stackrel{a)}{\leq} a_{1,2}^2 h^2 \|u\|_{2,\Omega}^2$$

(q.e.d.)

But it remains to prove estimate (20)  $\|e_h\|_{1,\Delta} \leq c_B \|u\|_{2,\Delta}$  see next Lecture 16!