

### 3.3. Properties of the System $K_h u_h = \underline{f}_h$ of Finite Element Equations

- 1d: see Lectures on NuPDEs by Prof. Zulehner
- The system of FE eqns  $K_h u_h = \underline{f}_h$  resp. the stiffness matrix  $K_h$  have the following properties:

1. Large-scale:  $\Omega \subset \mathbb{R}^d$  (2d:  $d=2$ ; 3d:  $d=3$ )

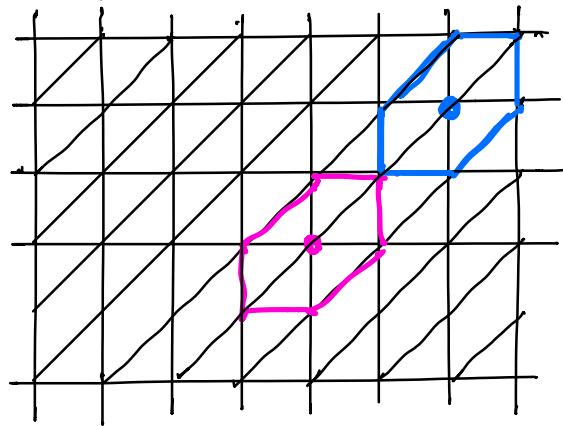
$N = N_h = |\omega_h| = \text{number of unknowns} = \text{DOF} = O(h^{-d})$ ,  
 where  $h = N^{-1/d}$  - discretization (mesh) parameter:  
 → in practice:  $N = 10^5 - 10^7 - 10^9$  and beyond  
super computing

2. sparse:

$$K_{ij} = 0 \quad \forall i, j \in \omega_h : \text{supp}(p^{(i)}) \cap \text{supp}(p^{(j)}) = \emptyset, \text{ i.e.}$$

$$B_{ij} := B_i \cap B_j = \emptyset$$

$$\bigcup_{r \in B_i} \bar{\delta}_r = \text{supp}(p^{(i)})$$

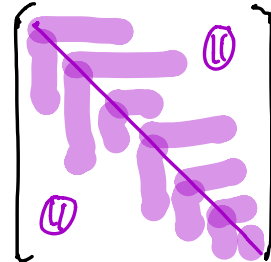
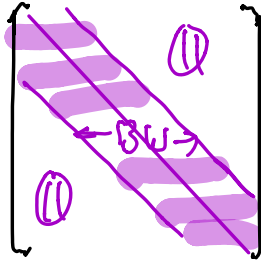


$NNE(i) = \text{Number of Non-zero Elements (NNE)}$   
 in the  $i$ -th row =  $|\{j \in \omega_h : x^{(j)} \in \bigcup_{r \in B_i} \bar{\delta}_r\}| = O(1)$

$$NNE = \sum_{i \in \omega_h} NNE(i) = NNE \text{ of } K_h = O(h^{-d}) \quad \begin{matrix} \uparrow \\ \text{res. mesh} \end{matrix}$$

L 14-02

### 3. Band-Width (BW) resp. Profile (SL = $5K_3$ Line):



→ depend on the global numbering of the nodes!

→ in general:  $BW = BW(K_h) = O(h^{-(d-1)})$   
 $SL = SL(K_h) = O(h^{-2d+1})$

Order estimates cannot be improved!

→ minimization algorithms for BW resp. SL,  
i.e. find node numbering s.t. BW resp. SL  $\rightarrow$  min  
= NP-hard!

→ see literature, e.g. [JL, 2013: pp. 462-476]  
for heuristic algorithms:

Alg. 5.16: Cuthill-McKee

Alg. 5.17: Reverse Cuthill-McKee

Alg. 5.18: Minimum degree

### 4. Inheritance Relation:

In general, the properties of the bilinear form  $a(\cdot, \cdot)$   
carry over to the stiffness matrix  $K_h$ : (mms)

(7)

$$(K_h u_h, v_h) = a(u_h, v_h) \quad \forall u_h, v_h \xleftrightarrow[\text{iso}]{\text{FE}} u_h, v_h \in \mathcal{V}_{0h}$$

L14-03

For instance:

- $a(\cdot, \cdot)$  symmetric  $\Rightarrow K_h = K_h^T$ , since
 
$$(K_h \underline{u}_h, \underline{v}_h) \stackrel{(\ddagger)}{=} a(\underline{u}_h, \underline{v}_h) = a(\underline{v}_h, \underline{u}_h) \stackrel{(\ddagger)}{=} (K_h \underline{v}_h, \underline{u}_h) = (\underline{u}_h, K_h \underline{v}_h)$$
  - $a(\cdot, \cdot)$   $\tilde{V}_0$ -positive  $\Rightarrow K_h$  positive definite, since
 
$$(K_h \underline{u}_h, \underline{u}_h) \stackrel{(\ddagger)}{=} a(\underline{u}_h, \underline{u}_h) > 0 \quad \forall \underline{u}_h \in \tilde{V}_{0h} : \underline{u}_h \neq \mathbf{0}$$
- $\rightarrow K_h$  is SPD!

- Here and in the following, we suppose that the triangulation is **regular** (see (4) in Subsection 3.2.2). The following definition of a **regular triangulation** is more general than (4):

### Def. 3.3: (regular triangulation)

A family  $\{\mathcal{T}_h\}_{h \in \mathbb{H}}$  of triangulations  $\mathcal{T}_h = \{\delta_r : r \in \mathbb{R}_h\}$  is called **regular**, if there exists positive,  $h$ -independent constants  $c_1, \bar{c}_1, c_2, c_3 = \text{const} > 0$  such that

$$(8) \quad c_1 h^d \leq |\mathcal{J}_{\delta_r}| := |\det \mathcal{J}_{\delta_r}| \leq \bar{c}_1 h^d, \quad \forall \xi \in \bar{\Delta} \quad \forall r \in \mathbb{R}_h \quad \forall h \in \mathbb{H},$$

$$(9) \quad \|\mathcal{J}_{\delta_r}\| := \sqrt{\lambda_{\max}(\mathcal{J}_{\delta_r}^T \mathcal{J}_{\delta_r})} \leq c_2 h, \quad \forall \xi \in \bar{\Delta} \quad \forall r \in \mathbb{R}_h \quad \forall h \in \mathbb{H},$$

$$(10) \quad \|\mathcal{J}_{\delta_r}^{-T}\| := \sqrt{\lambda_{\max}(\mathcal{J}_{\delta_r}^{-1} \mathcal{J}_{\delta_r}^{-T})} \leq c_3 h^{-1}, \quad \forall x \in \delta_r \quad \forall r \in \mathbb{R}_h \quad \forall h \in \mathbb{H},$$

where  $\mathcal{J}_{\delta_r} = \frac{\partial x_{\delta_r}}{\partial \xi}$  and  $\mathcal{J}_{\delta_r}^{-1} = \frac{\partial \xi_{\delta_r}}{\partial x}$ ,  $\delta_r \stackrel{\xi = \xi_{\delta_r}(x)}{x = x_{\delta_r}(\xi)} \Delta$ .

■ Theorem 3.4: (eigenvalue and condition number estimates)

Ass.: 1.  $a(\cdot, \cdot) : V \times V \rightarrow \mathbb{R}^1$ -bilinear form,  $V = H^1(\Omega)$ ,  $\|\cdot\| = \|\cdot\|_1$ :

a)  $V_0$ -elliptic:  $a(v, v) \geq \mu_1 \|v\|_1^2 \quad \forall v \in V_0$ ,

b)  $V_0$ -bounded:  $|a(u, v)| \leq \mu_2 \|u\|_1 \|v\|_1 \quad \forall u, v \in V_0$

c)  $V_0$ -symmetric:  $a(u, v) = a(v, u) \quad \forall u, v \in V_0$

2. Regular triangulation  $\{\mathcal{T}_h\}_{h \in \mathcal{O}}$  of  $\Omega \subset \mathbb{R}^d$  in the sense of Def. 3.3: (8) - (10).

St.: Then the following estimates are valid:

1.  $\exists c_E, \bar{c}_E = \text{const} > 0 : c_E \neq c_E(h)$  and

$$(11) \quad \underline{\delta} = c_E h^d \leq \lambda(K_h) \leq \bar{c}_E h^{d-2} = \bar{\delta},$$

SPD eigenvalues of  $K_h$

2.  $\kappa(K_h) = \text{cond}_2(K_h) := \|K_h\|_2 \|K_h^{-1}\|_2$

spectral condition number  $\xrightarrow{\text{SPD}}$

$$\kappa(K_h) \leq \frac{\bar{c}_E}{c_E} h^{-2}.$$

Proof:

- Starting point for the eigenvalue (EV) estimates = Rayleigh-quotient representation:

$$(11) \quad \underline{\delta} \leq \lambda_{\min}(K_h) = \min_{\substack{u_h \in \mathbb{R}^{N_h} \\ u_h \neq 0}} \frac{(K_h u_h, u_h)}{(u_h, u_h)} \leq \lambda(K_h) \leq \max_{\substack{u_h \in \mathbb{R}^{N_h} \\ u_h \neq 0}} \frac{(K_h u_h, u_h)}{(u_h, u_h)} \leq \lambda_{\max}(K_h) \leq \bar{\delta}$$



which is equivalent to the so-called spectral equivalence inequalities

$$(11)' \quad \underline{\delta} (u_h, u_h) \leq (K_h u_h, u_h) \leq \bar{\delta} (u_h, u_h) \quad \forall u_h \in \mathbb{R}^{N_h}$$

where  $(\cdot, \cdot)$  denotes the Euclidean inner product in  $\mathbb{R}^{N_h}$ .



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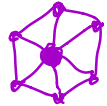
•  $(K_h \underline{u}_h, \underline{u}_h) = a(u_h, u_h) \geq \mu_1 \|u_h\|_1^2 = \textcircled{1} \geq ?$   
 $\leq \mu_2 \|u_h\|_1^2 = \textcircled{2} \leq ?$   
 $\forall \underline{u}_h \in \mathbb{R}^{N_h}, \underline{u}_h \xrightarrow[\text{iso}]{\text{FE}} u_h \in \bar{V}_{0h}$  independent of the BVP!

$\textcircled{1} \|u_h\|_1^2 = \int_{\Omega} (|\nabla_x u_h|^2 + u_h^2) dx = \sum_{r \in \mathbb{R}_h} \int_{\delta_r} (|\nabla_x u_h|^2 + u_h^2) dx$   
 mapping  $\delta_r \leftrightarrow \Delta$   $\bar{\Omega} = \cup \delta_r$   
 $\downarrow$   
 $(12) \quad \sum_{r \in \mathbb{R}_h} \int_{\Delta} (|\mathbb{F}_{\delta_r}^{-T} \nabla_{\xi} u_h(x_{\delta_r}(\xi))|^2 + u_h^2(x_{\delta_r}(\xi))) |\mathbb{F}_{\delta_r}| d\xi$   
 $\uparrow$   
 (↑) (mass)  $\nabla_x = \mathbb{F}_{\delta_r}^{-T} \nabla_{\xi} \geq 0$

$\geq c_1 h^d \sum_{r \in \mathbb{R}_h} \int_{\Delta} \left( \sum_{\alpha \in A_r} u_h(x_{\delta_r}(\xi)) p^{(\alpha)}(\xi) \right)^2 d\xi$   
 $= c_1 h^d \sum_{r \in \mathbb{R}_h} \sum_{\alpha, \beta \in A_r \subseteq A = \{1,2,3\} \text{ c.s.}} u^{(r,\alpha)} u^{(r,\beta)} \int_{\Delta} p^{(\alpha)}(\xi) p^{(\beta)}(\xi) d\xi$   
 $= c_1 h^d \sum_{r \in \mathbb{R}_h} \left( G_0^{(r)} \underline{u}^{(r)}, \underline{u}^{(r)} \right)_{\mathbb{R}^{|A_r|}}$

$\underline{u}^{(r)} = [u^{(r,\alpha)}]_{\alpha \in A_r}, G_0^{(r)} = \left[ \int_{\Delta} p^{(\alpha)} p^{(\beta)} d\xi \right]_{\alpha, \beta \in A_r}, G_0 = \left[ \int_{\Delta} p^{(\alpha)} p^{(\beta)} d\xi \right]_{\alpha, \beta \in A}$   
 mass matrix of the master elem.

$\geq c_1 \lambda_{\min}(G_0) h^d \sum_{r \in \mathbb{R}_h} \sum_{\alpha \in A_r} (u^{(r,\alpha)})^2 \geq$   
 $\geq c_1 \lambda_{\min}(G_0) h^d (\underline{u}_h, \underline{u}_h), \text{ i.e.}$



(13)  $\underline{\alpha} = c_E h^d, \text{ with } c_E = \mu_1 c_1 \lambda_{\min}(G_0)$

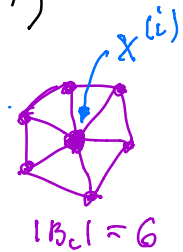
(12) L14-06

$$\begin{aligned}
 \textcircled{2} \quad \|u_h\|_1^2 &= \sum_{r \in \mathcal{R}_h} \int_{\Delta} (|\mathcal{J}_{\delta_r}^{-T} \nabla_{\xi} u_h(x_{\delta_r}(\xi))|^2 + u_h^2(x_{\delta_r}(\xi))) |\mathcal{J}_{\delta_r}| d\xi \\
 &\stackrel{(8)}{\leq} \bar{c}_1 h^d \sum_{r \in \mathcal{R}_h} \int_{\Delta} (\nabla_{\xi}^T u_h \cdot \mathcal{J}_{\delta_r}^{-1} \mathcal{J}_{\delta_r}^{-T} \nabla_{\xi} u_h + u_h^2) d\xi \\
 &\leq \bar{c}_1 h^d \sum_{r \in \mathcal{R}_h} \int_{\Delta} (\lambda_{\max}(\mathcal{J}_{\delta_r}^{-1} \mathcal{J}_{\delta_r}^{-T}) |\nabla_{\xi} u_h|^2 + u_h^2(x_{\delta_r}(\xi))) d\xi \\
 &\stackrel{(10)}{\leq} \bar{c}_1 c_3^2 h^{-2} \sum_{r \in \mathcal{R}_h} \sum_{\alpha, \beta \in A_r} u^{(r, \alpha)} u^{(r, \beta)} \int_{\Delta} (\nabla_{\xi}^T p^{(\alpha)} \cdot \nabla_{\xi} p^{(\beta)} + p^{(\alpha)} p^{(\beta)}) d\xi \\
 &= \bar{c}_1 c_3^2 h^{d-2} \sum_{r \in \mathcal{R}_h} (G_1^{(r)} \underline{u}^{(r)}, \underline{u}^{(r)})
 \end{aligned}$$

master element stiffness matrix for  $-\Delta_{\xi} + I$ :  $G_1^{(r)} = [G_1^{(\alpha, \beta)}]_{\alpha, \beta \in A_r}$ ,  $G_1 = [G_1^{(\alpha, \beta)}]_{\alpha, \beta \in A}$

$$\leq \bar{c}_1 c_3^2 \lambda_{\max}(G_1) h^{d-2} \sum_{r \in \mathcal{R}_h} \sum_{\alpha \in A_r} (u^{(r, \alpha)})^2$$

regular triangulation:  $c_4 = \sup_{h \in \Theta} \max_{i \in \mathcal{E}_h} |B_i|$



$$\leq \bar{c}_1 c_3^2 c_4 \lambda_{\max}(G_1) h^{d-2} (\underline{u}_h, \underline{u}_h)$$

$$\begin{aligned}
 (14) \quad \bar{\gamma} &= \underbrace{\mu_2 \bar{c}_1 c_3^2 c_4 \lambda_{\max}(G_1)}_{= \bar{c}_E} h^{d-2} \\
 &= \bar{c}_E
 \end{aligned}$$

q.e.d.

**E 3.5**

Ex 3.5.

Ex. 3.3:

$$c_1 = \frac{1}{2} \alpha_0^2 \sin \theta_0$$

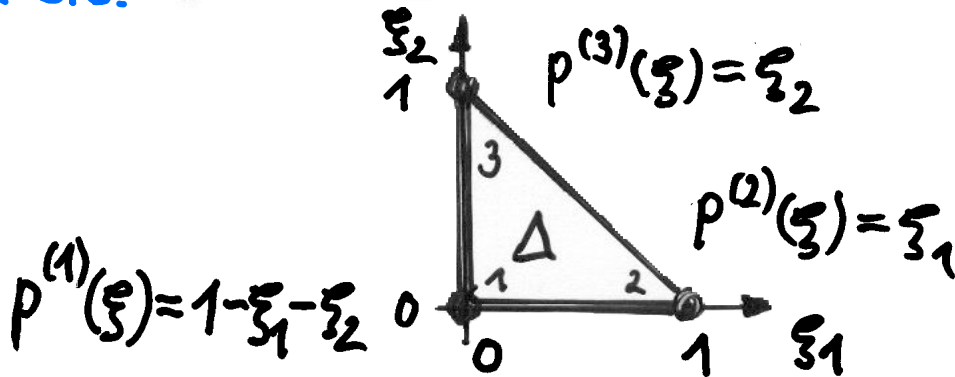
$$\bar{c}_1 = \sqrt{3}/2$$

Show that a regular family of triangular meshes in the sense of definition (4) is also a regular triangulation in the sense of Definition 3.3! Provide the constants  $c_1, \bar{c}_1, c_2$  and  $c_3$ !  $c_2 = ?$   
 $c_3 = ?$

**E 3.6**

Ex 3.6.

Compute  $\lambda_{\min}(G_0) = ?$  and  $\lambda_{\max}(G_1) = ?$  for Courant's element



and  $\underline{\delta} = ?$  and  $\bar{\gamma} = ?$  for our model problem (2) on a regular triangular mesh!  
Hint: Use the results of E 2.5!

**E 3.7**

Ex 3.7

Show that the Eigenvalue estimates (11) are sharp with respect to the  $h$ -order, i.e.  $\exists \underline{c}'_E, \bar{c}'_E = \text{const} > 0 : \underline{c}'_E, \bar{c}'_E \neq c(h)$  and  $\lambda_{\min}(K_h) \leq \underline{c}'_E h^d$  and  $\lambda_{\max}(K_h) \geq \bar{c}'_E h^{d-2}$ !  
Therefore:  $\lambda_{\min} = O(h^d), \lambda_{\max} = O(h^{d-2}), \kappa(K_h) = O(h^{-2})$ .

**E 3.8**

Ex 3.8

Show the spectral equivalence inequalities  $\underline{c}_M h^d (u_h, u_h) \leq (M_h u_h, u_h) = \|u_h\|_{L_2(\Omega)}^2 \leq \bar{c}_M h^d (u_h, u_h)$

$\forall u_h = [u^{(i)}]_{i \in \omega_h} \leftrightarrow u_h = \sum_{i \in \omega_h} u^{(i)} p^{(i)} \in \bar{V}_{0h}$ ,  
with the mass matrix  $M_h = \left[ \int_{\Omega} p^{(i)} p^{(j)} dx \right]_{i,j \in \omega_h}$ .

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- Remark: The properties of the stiffness matrix  $K_h$  are very important for evaluating the accuracy and efficiency of direct and iterative SOLVERS for the system

$$K_h \underline{u}_h = \underline{f}_h$$

of finite element equations.

### References:

[ZL:2013] Chapter 5

[Steinbach:2005] = [5] (NuEPDE-Website)

CISM Courses on Direct and Iterative Solvers  
by U. Langer and M. Neumüller (2017)

Direct Solvers	* = Part 1 Direct Solvers.pdf
Iterative Solvers	* = Part 2 Iterative Solvers.pdf
Preconditioners	* = Part 3 Preconditioners.pdf
Multigrid I	* = Part 4 Multigrid I.pdf
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[www.namu.uni-linz.ac.at/Teaching/LVA/2019w/NumOpt/\\*](http://www.namu.uni-linz.ac.at/Teaching/LVA/2019w/NumOpt/*)