# Newest vertex bisection method

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## 1 Introduction

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  - Completion of subdivision
- Galerkin approximations
- Adaptive approximation
  - Adaptive approximation in  $H^1(\Omega)$ -norm
  - Adaptive approximation in  $H^{-1}(\Omega)$ -norm

# Introduction

- Adaptive FEM for elliptic equations ⇒ Convergence shown by Dörfler and Morin, Nochetto, Siebert
- No rates of convergence in terms of degrees of freedom or number of computations

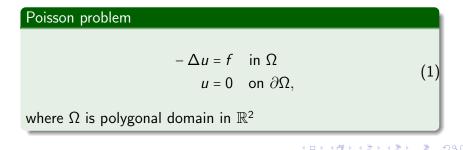
### Goal

Give AFEM and prove convergence rates

- Algorithm similar to existing adaptive methods based on chasing of a-posteriori error estimators
- Main difference: Coarsening strategy
- Analysis rely non-linear approximation by piecewise polynomials

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- Complications of AFEM analysis:
  - Need of graded meshes
  - Hanging nodes
  - Analysis of a-posteriori error estimator



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# Newest vertex bisection and completion

• Consider only approximations of *u* by piecewise linear elements using newest vertex bisection

### Notations

$$\Omega = \bigcup_{\Delta \in P} \Delta$$
  
For any  $\Delta, \Delta' \in P$ , meas $(\Delta \cap \Delta') = 0$   
 $S_P = \{S \in C(\Omega) : S|_{\Delta} \in P_1(\Delta) \text{ and } S|_{\partial\Omega} = 0\} \subset H_0^1(\Omega)$ 

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## Notations

- $\mathcal{E}_P$  ... set of edges of P $\dot{\mathcal{E}}_P$  ... interior edges  $\mathcal{V}_P$  ... set of vertices of P $\dot{\mathcal{V}}_P$  ... interior vertices
- 2 conditions on P:
  - Minimal angle condition for all  $\Delta \in P$  for some  $a_0 > 0$
  - P is conforming

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### Definition

A family of partitions  $\mathcal{P}$  is called admissible, if all elements are conforming which satisfy the minimal angle condition with common constant  $a_0 > 0$ .

• Minimal angle condition implies shape regularity,

$$\exists \hat{C} = \hat{C}(\mathcal{P}) : 1 \leq \frac{\mathsf{diam}(\Delta)^2}{|\Delta|} \leq \hat{C} \quad \text{for all } \Delta \in P, P \in \mathcal{P}$$

• Moreover,

$$\exists G_0 = G_0(\mathcal{P}) : \mathsf{diam}(\Delta) \le G_0\mathsf{diam}(\Delta')$$

for all  $\Delta, \Delta' \in P$  with  $\Delta \cap \Delta' \neq \emptyset$ 

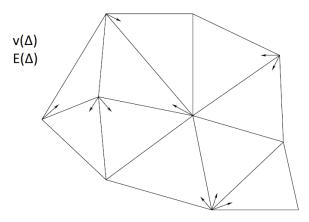
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- Typical AFEM generates sequence of partitions  $P_0, P_1, ..., P_n$  by subdividing triangles
- Given  $P_k$ :
  - Mark certain cells  $\Delta \in P_k$  for subdivision,  $\mathcal{M}_k$
  - Subdivide marked cells which can create hanging nodes
  - Mark additional cells  $\mathcal{M}_k'$  for subdividing such that  $P_{k+1}$  is admissible

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## Newest vertex bisection



## **Fig. 1.** Assignment of newest vertices in $P_0$

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- The partitions satisfy the uniform minimal angle condition
- If P is created by Newest vertex bisection and has no hanging nodes ⇒ P is conforming ⇒ P is admissible
- Completion step provides partition without hanging nodes
- Bound number of additional subdivisions necessary to remove hanging nodes

- Present newest vertex bisection subdivision by an infinite binary tree  $T_{\star}$
- *T*<sub>\*</sub> consists off all triangular cells which can be obtained by sequence of subdivisions
- Roots: triangular cells of  $P_0$
- Important fact: Newest vertex of cells are unique and only depend on initial assignment in P<sub>0</sub>
- This means, children does not depend on preceding sequence of subdivisions

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# Completion of subdivision

- Begin with  $P_0$  and mark cells for subdivision  $\Rightarrow P'_1$
- $P'_1$  not necessarily admissible, therefore make additional subdivision to get admissible  $P_1$
- We will see that
  - Completion process does not inflate the number of triangular cells in  $P_n$
  - Number of created triangles through completion proportional to number of cells marked in refinement, i.e.

$$\#(P_n) - \#(P_0) \leq C_2(\#(\mathcal{M}_0) + \ldots + \#(\mathcal{M}_{n-1}))$$

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### Definition

Suppose *P* is admissible with #(P) > 2. For  $\Delta \in P$  define

$$F(\Delta) = \begin{cases} \varnothing & \text{if } E(\Delta) \text{ is a boundary edge,} \\ \Delta' & \text{if } E(\Delta) \text{ is a edge of } \Delta'. \end{cases}$$

A chain  $C(\Delta)$  (with starting cell  $\Delta$ ) in P is a sequence  $\Delta, F(\Delta), ..., F^m(\Delta)$  with no repetition and with  $F^{m+1}(\Delta) = F^k(\Delta)$  for k = 0, ..., m-1 or  $F^{m+1}(\Delta) = \emptyset$ .

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- - 1) Each cell  $\Delta' = F^k(\Delta)$  is subdivided by newest vertex bisection
  - 2) Subdivide children with hanging nodes Hanging nodes occur inside cell  $\Delta' = F^k(\Delta)$ , if  $E(F^{k-1}(\Delta)) \neq E(F^k(\Delta))$ 
    - Connect midpoint of these two edges

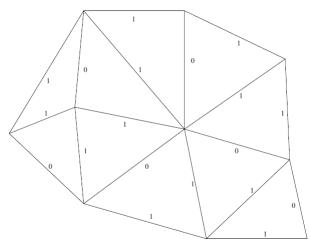
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# Labelling

- Use labelling of edges to observe structure of  $\bar{C}(\Delta)$
- Label edges in  $P_0, P_1, ..., P_n$  by non-negative integers
- Given  $\Delta \in P_k$ , sides are labelled by (i + 1, i + 1, i) where  $i = g(\Delta)$  and lowest labelled side is  $E(\Delta)$
- For admissible partitions, labelling is independent of triangles provided we start with suitable labelling of *P*<sub>0</sub>

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**Fig. 2.** Assignment of newest vertices in  $P_0$ 

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### Theorem 1

For any  $P_0$  there is a labelling of the edges in  $P_0$  such that each edge is given a label of either 0 or 1 and whenever a triangle  $\Delta \in P_0$  then exactly two of its edges are labelled with 1 and the other is labelled with 0.

- Existence is guaranteed by Petersen's Theorem
- Construction of labelling scheme as in Theorem 1: Suppose, we can find  $Q \subset P_0$  such that
  - (i) All triangles in  $P_0 \backslash Q$  have at least one edge on  $\partial \Omega$
  - (ii)  $\Omega_Q$  can be decomposed into an essentially disjoint union of quadrilaterals formed by pairs of adjacent triangles

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- For each pair of triangles in Q whose union forms one quadrilateral, assign common edge to 0 and others to 1
- By (i) we missed at most edges on  $\partial \Omega$ 
  - If  $E \in \partial \Omega$ , and the other sides are interior, then label by 0
  - If  $E \in \partial \Omega$  with another boundary edge, label one by 0 and other by 1
- Label problem reduces to:
   Find Q ⊂ P<sub>0</sub> such that (i) and (ii) are satisfied

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Construction of Q: Subdivide each Δ ∈ P<sub>0</sub> into 4 triangles such that new partition P'<sub>0</sub> = Q satisfies (i) and (ii)

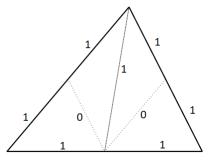


Fig. 3. Refinement for labelling

• Do this  $\forall \Delta \in P_0$ , resulting  $P'_0$  has no hanging nodes

- Given the labelling of P<sub>0</sub> by Theorem 1, define newest vertex of Δ ∈ P<sub>0</sub> to be opposite of side with label 0
- Assume, initial labelling of P<sub>0</sub> according Theorem 1
- Any chain in  $P_0$  has at most 2 cells
- Subdivision of cells gives admissible partition

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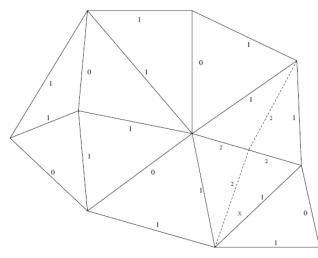


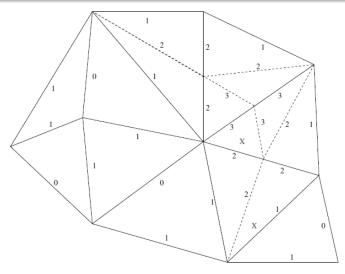
Fig. 4. Labelling of new edges

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지수요 지수는 지수 문제

- Labelling for edges that arise from subdivision completion (2 properties)
  - i. Each cell have sides labelled by (i, i, i-1) for  $i \in \mathbb{N}$
  - ii. Newest vertex is opposite lowest label
- If a cell has label (i + 1, i + 1, i), then it is of generation i,
   i.e. so many subdivisions are needed to get the cell

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## Fig. 5. Labelling in the completion process

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### Lemma 1

Suppose  $P_0$  is an arbitrary partition and its edges and newest vertices are labelled in accordance with Theorem 1. Suppose that  $P_1, ..., P_n$  are partitions generated by newest vertex bisection from  $P_0$ . Then there holds for each k = 0, 1, ..., n:

(i) each edge in  $P_k$  has a unique label independent of the two triangles which share this edge.

(ii) If Δ ∈ P<sub>k</sub> of generation g(Δ) = i, i.e. the edge with label i is the side shared by Δ and F(Δ), then g(F(Δ)) ∈ {i, i − 1}.
If g(F(Δ)) = i, the flow ends at F(Δ).

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#### Lemma 1 cont.

(iii) For any  $\Delta \in P_k$  of generation  $g(\Delta) = i$ , the cells in its chain  $C(\Delta) = \{\Delta, F(\Delta), ..., F^m(\Delta)\}$  have the property that  $g(F^j(\Delta)) = i - j, j = 0, ..., m - 1$  and  $F^m(\Delta)$  for this chain is either of generation i - m + 1 or it is a boundary cell with lowest labelled edge an edge of the boundary.

• All admissible partitions, generated by newest vertex bisection with *P*<sub>0</sub> according to Theorem 1, are graded

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### Theorem 2

Let  $P_0, ..., P_n$  be a sequence of partitions generated as described above. Then, there is a constant  $C_2 > 0$  depending only on  $P_0$ , such that

$$\#(P_n) \le \#(P_0) + C_2(\#(\mathcal{M}_0) + \dots + \#(\mathcal{M}_{n-1})).$$
(2)

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- Given P and P' partition of P, then m(P|P') is number of needed markings
- Thus, (9) can be rewritten as

$$\#(P_n) \le \#(P_0) + C_2 \sum_{k=1}^n m(P_k | P_{k-1})$$
(3)

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# Galerkin approximations

• Weak formulation of Poisson problem (1): Find  $u \in H_0^1(\Omega)$  such that

$$a(u,w) = (f,w), \quad w \in H^1_0(\Omega)$$

• Notation:

$$|||w|||^2 = a(w, w) = ||\nabla w||^2_{L_2(\Omega)}$$

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- Given admissible P, denote Galerkin solution by  $u_P$
- $u_P$  is unique element in  $\mathcal{S}_P \subset H^1_0(\Omega)$  which satisfies

$$a(u_P,w)=(f,w), \quad w\in \mathcal{S}_P$$

- Replace f by an approximation
- $u_P$  is best approximation to u from  $\mathcal{S}_P$  in energy norm

$$|||u - u_P||| = \inf_{S \in S_P} |||u - S|||$$

• Can't calculate  $u_P$  exactly, therefore use numerical scheme

## GAL

• Input: admissible partition P, error tolerance  $\mu$ , initial approximation  $\overline{u}_P \in S_P$  to  $u_P$ , that satisfies

$$|||u - \bar{u}_P||| \le A'\mu, \quad A' = const \tag{4}$$

 Apply a preconditioned conjugate gradient scheme with initial guess ū<sub>P</sub> to obtain approximation û<sub>P</sub> = GAL(P, μ, ū<sub>P</sub>) to u<sub>P</sub> that satisfies

$$|||u_P - \hat{u}_P||| \le \delta \mu, \quad \delta \in (0, 1)$$
(5)

### Remark

- Needed number of iterations of CG-scheme to achieve (13) depends only on  $A'/\delta$
- Since each iteration requires at most C#(P) computations, it follows that number of computations

$$N(\mathsf{GAL}, P, \mu, \bar{u}_P) \le C_3(\frac{A'}{\delta}) \#(P) \tag{6}$$

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where  $C_3: t \rightarrow C_3(t)$  increases as a function of t

Adaptive approximation in  $H^1(\Omega)$ -norm Adaptive approximation in  $H^{-1}(\Omega)$ -norm

# Adaptive approximation

- Discuss adaptive approximation of a known function *w* for which local polynomial approximations are computable
- w is the best we can expect in terms of approximating u
- Use methods which approximate *f* and execute coarsening step
- Use adaptive method based on newest vertex subdivision rule starting with  $P_0$  and labelling as in Theorem 1

Adaptive approximation in  $H^1(\Omega)$ -norm Adaptive approximation in  $H^{-1}(\Omega)$ -norm

# Adaptive approximation in $H^1(\Omega)$ -norm

• Given  $w \in H_0^1(\Omega)$  and P, we define

$$E(w, \mathcal{S}_P)_{H^1(\Omega)} = \inf_{S \in \mathcal{S}_P} \|w - S\|_{H^1(\Omega)}$$
(7)

Define error

$$\sigma_n(w) = \inf_{P \in \mathcal{P}_n} E(w, \mathcal{S}_P)_{H^1(\Omega)}$$
(8)

of best adaptive approximation

 Cannot expect, that any adaptive algorithm perform exactly the same as σ<sub>n</sub>(w)

- We may expect same asymptotic behavior
- We know (from NumEP) that

$$||u - v_h||_{H^1(\Omega)} \le ch|u|_{H^2(\Omega)} = Mh = Mn^{-1/2}$$

• Introduce class  $\mathcal{A}^{1/2} = \mathcal{A}^{1/2}(H_0^1(\Omega))$  of functions  $w \in H_0^1(\Omega)$ 

$$\sigma_n(w) \le M n^{-1/2}, \quad n = 1, 2, ...$$
 (9)

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Adaptive approximation in  $H^1(\Omega)$ -norm Adaptive approximation in  $H^{-1}(\Omega)$ -norm

• In general, for any s > 0 the class  $\mathcal{A}^s = \mathcal{A}^s(H_0^1(\Omega))$  of functions  $w \in H_0^1(\Omega)$ , such that

$$\sigma_n(w) \le M n^{-s}, \quad n = 1, 2, \dots \tag{10}$$

• Smallest M for which (14) is satisfied is the norm in  $\mathcal{A}^s$ 

$$\|w\|_{\mathcal{A}^s} = \sup_{n \ge 1} n^s \sigma_n(w) \tag{11}$$

Adaptive approximation in  $H^1(\Omega)$ -norm Adaptive approximation in  $H^{-1}(\Omega)$ -norm

Adaptive approximation in  $H^{-1}(\Omega)$ -norm

- Need approximation by piece-wise constants for f
- Approximation in  $H^{-1}(\Omega)$  with

$$\|g\|_{H^{-1}(\Omega)} = \sup_{\phi \in H^{-1}(\Omega)} \frac{\langle g, \phi \rangle}{|||\phi|||}$$

 Given P, we write S<sup>0</sup><sub>P</sub> as class of piecewise constants subordinate to P

Adaptive approximation in  $H^1(\Omega)$ -norm Adaptive approximation in  $H^{-1}(\Omega)$ -norm

• For  $f \in H^{-1}(\Omega)$ , define

$$E(f, \mathcal{S}_P^0)_{H^{-1}(\Omega)} = \inf_{S \in \mathcal{S}_P^0} \|f - S\|_{H^{-1}(\Omega)}$$

which is, best error of approximation for f

• Analogous, error of best non-linear approximation

$$\sigma_n(f)_{H^{-1}(\Omega)} = \inf_{P \in \mathcal{P}_n} E(f, \mathcal{S}_P^0)_{H^{-1}(\Omega)}$$

- Introduce for s > 0, A<sup>s</sup>(H<sup>-1</sup>(Ω)) approximation class as before
  - Except: Use  $\sigma_n(g)_{H^{-1}(\Omega)}$  in place of  $\sigma_n(w)$

Adaptive approximation in  $H^1(\Omega)$ -norm Adaptive approximation in  $H^{-1}(\Omega)$ -norm

- Suppose  $g \in L_2(\Omega)$ , then  $g \in H^{-1}(\Omega)$
- If P is any partition of  $\Omega$  and  $\Delta \in P$ , define

$$g_{\Delta} = \frac{1}{|\Delta|} \int_{\Delta} g$$

- $g_\Delta$  best approximation in  $L_2(\Delta)$  by constant functions
- Best L<sub>2</sub>(Ω) approximation by piecewise constants subordinate to P

$$S^0_P(g) = \sum_{\Delta \in P} g_\Delta \chi_\Delta$$

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Introduction Newest vertex bisection and completion Galerkin approximation Adaptive approximation in  $H^{1}(\Omega)$ -norm Adaptive approximation in  $H^{-1}(\Omega)$ -norm

• For admissible P, we have bound for approximation error

$$E(g, \mathcal{S}_{P}^{0})_{H^{-1}(\Omega)}^{2} \leq \|g - \mathcal{S}_{P}^{0}(g)\|_{H^{-1}(\Omega)}^{2} \leq C_{0}\bar{E}(g, P) \quad (12)$$

where

$$\bar{E}(g,P) = \sum_{\Delta \in P} |\Delta| \|g - g_{\Delta}\|_{L_2(\Omega)}^2$$

• Define another non-linear approximation error

$$\bar{\sigma}_n^2(g) = \inf_{P \in \mathcal{P}_n} \bar{E}(g, P)$$

### Theorem 3 (Petersen's Theorem)

## Any bridgeless cubic graph has a perfect matching.

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