

The Hitchhikers Guide to VEM

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Overview

- ▶ Last time in the NUMA-Seminar
- ▶ Stiffness matrix revisited
- ▶ Yet another projection
- ▶ Mass matrix

Last Time in the NUMA-Seminar

- ▶ VEM for Poisson problem
- ▶ Very general decomposition

$$V^{K,k} := \{v \in H^1(K) : v|_{\partial K} \in \mathbb{B}_k(\partial K), \Delta v|_K \in \mathbb{P}_{k-2}(K)\}$$

- ▶ $\mathcal{V}^{K,k}$: v_h at **vertices**
- ▶ $\mathcal{E}^{K,k}$: v_h at $k - 1$ uniformly spaced points on **edges** e
- ▶ $\mathcal{P}^{K,k}$: **moments** $\frac{1}{|K|} \int_K m(x) v_h(x) dx \quad \forall m \in \mathcal{M}_{k-2}(K)$

Assembling: Stiffness Matrix Revisited

▶ $\Pi_K^\nabla : V^{K,k} \rightarrow \mathbb{P}_k(K) \subset V^{K,k}$

$$\begin{cases} a^K(\Pi_K^\nabla v_h, q) = a^K(v_h, q_k) & \forall q_k \in \mathbb{P}_k(K) \\ P_0 \Pi_K^\nabla v_h = P_0 v_h \end{cases} \quad (1)$$

▶ \mathcal{M}_k spans \mathbb{P}_k

$$\Pi_K^\nabla v_h = \sum_{\beta=1}^{n_k} s^\beta m_\beta$$

▶ Rewrite (1)

$$\sum_{\beta=1}^{n_k} s^\beta (\nabla m_\alpha, \nabla m_\beta)_{0,K} = (\nabla m_\alpha, \nabla v_h) \quad (2)$$

$$\sum_{\beta=1}^{n_k} s^\beta P_0 m_\beta = P_0 v_h \quad (3)$$

Assembling: Stiffness Matrix Revisited

- ▶ Linear system for s^β

$$\begin{bmatrix} P_0 m_1 & P_0 m_2 & \dots & P_0 m_{n_k} \\ 0 & (\nabla m_2, \nabla m_2) & \dots & (\nabla m_2, \nabla m_{n_k}) \\ \vdots & \vdots & \ddots & \vdots \\ 0 & (\nabla m_{n_k}, \nabla m_2) & \dots & (\nabla m_{n_k}, \nabla m_{n_k}) \end{bmatrix} \begin{bmatrix} s^1 \\ s^2 \\ \vdots \\ s^{n_k} \end{bmatrix} = \begin{bmatrix} P_0 v_h \\ (\nabla m_2, \nabla v_h) \\ \vdots \\ (\nabla m_{n_k}, \nabla v_h) \end{bmatrix} \quad (4)$$

- ▶ $\underline{\mathbf{G}} \underline{\mathbf{s}} = \underline{\mathbf{b}}$
- ✓ $\underline{\mathbf{G}}$ computable
- ✓ $\underline{\mathbf{b}}$ computable (shown last time)

Assembling: Stiffness Matrix Revisited

- ▶ Applied to basis functions φ_i

$$\Pi_K^\nabla \varphi_i = \sum_{\alpha=1}^{n_k} s_i^\alpha m_\alpha$$

- ▶ $\underline{s}^{(i)} = G^{-1} \underline{b}^{(i)}$

$$\mathbf{B} := \left[\underline{b}^{(1)} \quad \underline{b}^{(2)} \quad \dots \quad \underline{b}^{(N^{dof})} \right] \quad (5)$$

- ▶ Matrix representation Π_*^∇ of $\Pi^\nabla : V_k(K) \rightarrow \mathbb{P}_k(K)$ in the basis \mathcal{M}_k

$$\Pi_*^\nabla = \mathbf{G}^{-1} \mathbf{B}$$

Assembling: Stiffness Matrix Revisited

- ▶ Canonical basis

$$\Pi^\nabla \varphi_i = \sum_{j=1}^{N^{dof}} \pi_i^j \varphi_j$$

with $\pi_i^j = dof_j(\Pi^\nabla \varphi_i)$

$$\Pi^\nabla \varphi_i = \sum_{\alpha=1}^{n_k} s_i^\alpha m_\alpha = \sum_{\alpha=1}^{n_k} s_i^\alpha \sum_{j=1}^{N^{dof}} dof_j(m_\alpha) \varphi_j$$

- ▶ $\pi_i^j = \sum_{\alpha=1}^{n_k} s_i^\alpha dof_j(m_\alpha)$

Assembling: Stiffness Matrix Revisited

▶ $\mathbf{D}_{i\alpha} := \text{dof}_i(m_\alpha)$

▶ Hence:

$$\pi_i^j = \sum_{\alpha=1}^{n_k} (G^{-1}B)_{\alpha i} D_{j\alpha} = (DG^{-1}B)_{ji}$$

▶ Matrix representation $\mathbf{\Pi}^\nabla$ of $\Pi^\nabla : V_k(K) \rightarrow V_k(K)$ in the canonical basis

$$\mathbf{\Pi}^\nabla = \mathbf{D}\mathbf{G}^{-1}\mathbf{B} = \mathbf{D}\mathbf{\Pi}_*^\nabla$$

▶ Can show $\mathbf{G} = \mathbf{B}\mathbf{D}$

Assembling: Stiffness Matrix Revisited

- ▶ Split $\varphi_i = \Pi^\nabla \varphi_i + (I - \Pi^\nabla) \varphi_i$
- ▶ Obtain:

$$(K_K)_{ij} = (\nabla \Pi^\nabla \varphi_i, \nabla \Pi^\nabla \varphi_j) + ((I - \Pi^\nabla) \varphi_i, (I - \Pi^\nabla) \varphi_j)$$

- ▶ Approximate:

$$((I - \Pi^\nabla) \varphi_i, (I - \Pi^\nabla) \varphi_j) \approx \sum_{r=1}^{N^{dof}} \text{dof}_r(\varphi_i - \Pi_k^K \varphi_i) \text{dof}_r(\varphi_j - \Pi_k^K \varphi_j)$$

Assembling: Stiffness Matrix Revisited

- ▶ Obtain:

$$\mathbf{K}_K^h = (\mathbf{n}_*^\nabla)^T \tilde{\mathbf{G}} \mathbf{n}_*^\nabla + (\mathbf{I} - \mathbf{n}^\nabla)^T (\mathbf{I} - \mathbf{n}^\nabla)$$

- ▶ $\tilde{\mathbf{G}} = \mathbf{G}$ with first row set to 0
- ▶ $\mathbf{B}, \mathbf{D}, \mathbf{G}$ depend only on the shape of the polygon K and not on its size
- ▶ \mathbf{K}_K^h is (in general) not close to \mathbf{K}_K

Assembling: Stiffness Matrix Revisited

Summary (Stiffness matrix)

- ▶ Compute \mathbf{B} , \mathbf{D} , \mathbf{G}
- ▶ Compute $\mathbf{\Pi}_*^\nabla = \mathbf{G}^{-1}\mathbf{B}$ and $\mathbf{\Pi}^\nabla = \mathbf{D}\mathbf{\Pi}_*^\nabla$
- ▶ Compute $\mathbf{K}_K^h = (\mathbf{\Pi}_*^\nabla)^T \tilde{\mathbf{G}} \mathbf{\Pi}_*^\nabla + (\mathbf{I} - \mathbf{\Pi}^\nabla)^T (\mathbf{I} - \mathbf{\Pi}^\nabla)$

Assembling: Mass Matrix

- ▶ $\mathbf{M}_{Kij} := \int_K \varphi_i \varphi_j dx$
- ▶ Not possible with the current dofs

→ L^2 -projector

Assembling: Mass Matrix

- ▶ Split $\varphi_i = \Pi^0 \varphi_i + (I - \Pi^0) \varphi_i$
- ▶ Obtain:

$$(M_K)_{ij} = (\Pi^0 \varphi_i, \Pi^0 \varphi_j) + ((I - \Pi^0) \varphi_i, (I - \Pi^0) \varphi_j)$$

- ▶ Approximate:

$$((I - \Pi^0) \varphi_i, (I - \Pi^0) \varphi_j) \approx |K| \sum_{r=1}^{N^{dof}} \text{dof}_r(\varphi_i - \Pi^0 \varphi_i) \text{dof}_r(\varphi_j - \Pi^0 \varphi_j)$$

$$\mathbf{M}_K^h = \mathbf{C}^T \mathbf{H}^{-1} \mathbf{C} + |K| (\mathbf{I} - \mathbf{\Pi}^0)^T (\mathbf{I} - \mathbf{\Pi}^0)$$

Yet Another Projection

- ▶ L^2 -projection: Find $\Pi^0 v_h \in \mathbb{P}_k(K)$ such that

$$(p_k, \Pi^0 v_h) = (p_k, v_h) \quad \forall p_k \in \mathbb{P}_k(K)$$

- ▶ $\mathbf{H}_{\alpha\beta} := (m_\alpha, m_\beta)$
- ▶ $\Pi^0 v_h = \sum_{\alpha=1}^{n_k} t^\alpha m_\alpha$
- ▶ $c^\alpha := (m_\alpha, v_h)$

- ▶ Similar to before

$$\mathbf{H}\underline{t} = \underline{c}$$

Yet Another Projection

- ▶ Similar to before

$$\underline{t} = \mathbf{H}^{-1} \underline{c}$$

- ✓ \mathbf{H} computable
- ✗ \underline{c} computable (no moments for $|\alpha| = k - 1, k$)

Yet Another Projection

- ▶ Can compute $\Pi^\nabla v_h$
- ▶ For $v_h \in V_k(K)$: $v_h \sim \Pi^\nabla v_h$ and $v_h \sim \Pi^0 v_h$
- ▶ Hence: $\Pi^0 \sim \Pi^\nabla$

Idea Replace $c^\alpha := (m_\alpha, v_h)$ for $|\alpha| = k - 1, k$ by

$$c^\alpha := (m_\alpha, \Pi^\nabla v_h)$$

✓ c computable

? Error ?

A Virtual Space for Virtual Elements

Introduce new space $W_k(K)$ with the good properties of $V_k(K)$

- ▶ polynomials on edges
- ▶ $\mathbb{P}_k(K) \subset W_k(K)$
- ▶ same dofs

Additionally:

- ▶ For $|\alpha| = k - 1, k$ and $w_h \in W_k(K)$

$$\int_K w_h m_\alpha = \int_K \Pi^\nabla w_h m_\alpha$$

A Virtual Space for Virtual Elements

- ▶ if space exists, previous computations hold unchanged
- ▶ $dofs(v_h) = dofs(w_h) \implies \Pi^\nabla v_h = \Pi^\nabla w_h$

Summary (L^2 -projector)

- ▶ Compute \mathbf{H}
- ▶ Compute $\Pi^\nabla v_h \equiv \Pi^\nabla w_h$ using only dofs
- ▶ Compute \underline{c}
- ▶ Solve $\underline{t} = \mathbf{H}^{-1}\underline{c}$
- ▶ Compute $\Pi^0 w_h = \sum_{\alpha=1}^{n_k} t^\alpha m_\alpha = \sum_{\alpha=1}^{n_k} t^\alpha \sum_{i=1}^{N^{dof}} D_{\alpha i} \varphi_i$

Matrix Representation

- ▶ Monomial basis:

$$(\boldsymbol{\Pi}_*^0)_{\alpha i} := t^\alpha(\varphi_i) = (\mathbf{H}^{-1}\mathbf{C})_{\alpha i}$$

with

$$\mathbf{C}_{\alpha i} := (m_\alpha, \varphi_i) = \begin{cases} (m_\alpha, \varphi_i) & 1 \leq \alpha \leq n_{k-2} \\ (m_\alpha, \Pi^\nabla \varphi_i) & n_{k-2} + 1 \leq \alpha \leq n_k \end{cases}$$

- ▶ VEM-basis:

$$(\boldsymbol{\Pi}^0)_{ji} := (\mathbf{D}\mathbf{H}^{-1}\mathbf{C})_{ji}$$

Assembling: Mass Matrix

- ▶ Split $\varphi_i = \Pi^0 \varphi_i + (I - \Pi^0) \varphi_i$
- ▶ Obtain:

$$(M_K)_{ij} = (\Pi^0 \varphi_i, \Pi^0 \varphi_j) + ((I - \Pi^0) \varphi_i, (I - \Pi^0) \varphi_j)$$

- ▶ Approximate:

$$((I - \Pi^0) \varphi_i, (I - \Pi^0) \varphi_j) \approx |K| \sum_{r=1}^{N^{dof}} \text{dof}_r(\varphi_i - \Pi^0 \varphi_i) \text{dof}_r(\varphi_j - \Pi^0 \varphi_j)$$

$$\mathbf{M}_K^h = \mathbf{C}^T \mathbf{H}^{-1} \mathbf{C} + |K| (\mathbf{I} - \mathbf{\Pi}^0)^T (\mathbf{I} - \mathbf{\Pi}^0)$$

Summary

$$\mathbf{M}_K^h = \mathbf{C}^T \mathbf{H}^{-1} \mathbf{C} + |K| (\mathbf{I} - \boldsymbol{\pi}^0)^T (\mathbf{I} - \boldsymbol{\pi}^0)$$

$$\mathbf{K}_K^h = (\boldsymbol{\pi}_*^\nabla)^T \tilde{\mathbf{G}} \boldsymbol{\pi}_*^\nabla + (\mathbf{I} - \boldsymbol{\pi}^\nabla)^T (\mathbf{I} - \boldsymbol{\pi}^\nabla)$$

- ▶ Exact consistency term, approximation for stability term
- ▶ Optimal convergence rates in H^1 , L^2
- ▶ General bilinear forms possible
- ▶ 3d: similar, but more technical

Thank you.



Veiga, L. Beirao da, F. Brezzi, A. Cangiani, et al. (2013). "Basic Principles of Virtual Element Methods". In: *Mathematical Models and Methods in Applied Sciences* 23.01, pp. 199–214. DOI: 10.1142/S0218202512500492.



Veiga, L. Beirao da, F. Brezzi, L. D. Marini, et al. (2014). "The Hitchhiker's Guide to the Virtual Element Method". In: *Mathematical Models and Methods in Applied Sciences* 24.08, pp. 1541–1573.