

Basic Principles of Virtual Element Methods

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November 20, 2018

Continuous Problem

Consider simple Laplace problem:

$$-\Delta u = f \quad \text{in } \Omega$$

$$u = 0 \quad \text{on } \Gamma = \partial\Omega$$

Find $u \in V := H_0^1(\Omega)$, such that

$$a(u, v) = (f, v) \quad \forall v \in V,$$

with $a(u, v) = (\nabla u, \nabla v)$.

✓ Lax-Milgram: Existence & Uniqueness

Discrete Problem: Abstract Framework

- ▶ $\{\mathcal{T}_h\}_h$... decomposition of Ω into elements K
- ▶ \mathcal{E}_h ... set of edges e of \mathcal{T}_h
- ▶ h ... maximum of diameters of elements in \mathcal{T}_h

Assumption: A0.1

\mathcal{T}_h is made of a finite number of **simple polygons**.

More precise:

Open simply connected sets with non-intersecting boundaries made of a finite number of straight line segments.

Discrete Problem: Definitions

- ▶ $a(u, v) = \sum_{K \in \mathcal{T}_h} a^K(u, v) \quad \forall u, v \in V$
- ▶ $|v|_1^2 = \sum_K |v|_{1,K}^2 \quad \forall v \in V$
- ▶ $|v|_{h,1}^2 := \sum_K |\nabla v|_{0,K}^2 \quad \forall v \in H^1(\mathcal{T}_h) := \prod_K H^1(K)$

Discrete Problem: Assumptions

Assumption: A1

For each h , we have:

- ▶ $V_h \subset V$
- ▶ $a_h : V_h \times V_h \rightarrow \mathbb{R}$, symmetric bilinear form
- ▶ $a_h(u_h, v_h) = \sum_K a_h^K(u_h, v_h) \quad \forall u_h, v_h \in V_h$
with a_h^K a bilinear form on $V_{h|K} \times V_{h|K}$
- ▶ $f_h \in V_h'$

Discrete Problem: More Assumptions

Assumption: A2

There exists $k \geq 1$ such that for all h and $K \in \mathcal{T}_h$

▶ $\mathbb{P}_k(K) \subset V_{h|K}$

▶ k -consistency:

$$a_h^K(p, v_h) = a^K(p, v_h) \quad \forall p \in \mathbb{P}_k(K), v_h \in V_{h|K}$$

▶ Stability:

$$\alpha_* a^K(v_h, v_h) \leq a_h^K(v_h, v_h) \leq \alpha^* a^K(v_h, v_h) \quad \forall v_h \in V_{h|K}$$

Implies continuity of a_h with constant α^* .

Discrete Problem: Error Estimate

Theorem

Under Assumptions **A1-A2**, the discrete problem: Find $u_h \in V_h$ such that

$$a_h(u_h, v_h) = \langle f_h, v_h \rangle \quad \forall v_h \in V_h,$$

has a unique solution.

For every approximation $u_I \in V_h$ and $u_\pi \in \mathbb{P}_k$ piecewise, we have

$$|u - u_h|_1 \leq C (|u - u_I|_1 + |u - u_\pi|_{h,1} + \mathcal{F}_h),$$

with $\mathcal{F}_h := \|f - f_h\|_{V_h'}$.

Discretization: Discrete Spaces

- ▶ K ... simple polygon with n edges
- ▶ x_K ... barycenter of K
- ▶ h_K ... diameter of K

$$\mathbb{B}_k(\partial K) := \{v \in C^0(\partial K) : v|_e \in \mathbb{P}_k(e) \quad \forall e \subset \partial K\}$$

$$\dim = n + n(k - 1) = nk$$

$$V^{K,k} := \{v \in H^1(K) : v|_{\partial K} \in \mathbb{B}_k(\partial K), \Delta v|_K \in \mathbb{P}_{k-2}(K)\}$$

$$\dim = nk + k(k - 1)/2 =: N^K$$

Discretization: Degrees of Freedom

For $V^{K,k}$ we can choose the following degrees of freedom:

- ▶ $\mathcal{V}^{K,k}$: v_h at **vertices**
- ▶ $\mathcal{E}^{K,k}$: v_h at $k - 1$ uniformly spaced points on **edges** e
- ▶ $\mathcal{P}^{K,k}$: **moments** $\frac{1}{|K|} \int_K m(x) v_h(x) dx \quad \forall m \in \mathcal{M}_{k-2}(K)$

$$\mathcal{M}^{k-2} := \left\{ \left(\frac{x-x_K}{h_K} \right)^s, |s| \leq k-2 \right\}, \quad \dim = (k^2 - k)/2$$

Discretization: Degrees of Freedom

Remark

- ▶ $\mathcal{V}^{K,k} + \mathcal{E}^{K,k} \Leftrightarrow$ prescribe v_h on ∂K
- ▶ $\mathcal{P}^{K,k} \Leftrightarrow$ prescribe $P_{k-2}^K v_h$ in K

$P_{k-2}^K := L^2(K)$ – projection onto $\mathbb{P}_{k-2}(K)$

Theorem

The degrees of freedom are **unisolvant** for $V^{K,k}$.

Discretization: Unisolvence

Theorem

The degrees of freedom are **unisolvant** for $V^{K,k}$.

1. Observe:

$$\text{unisolvence} \Leftrightarrow v_h = 0 \text{ on } \partial K, P_{k-2}^K = 0 \text{ in } K \implies v_h = 0 \text{ in } K$$

2. Show $P_{k-2}^K = 0 \implies \Delta v_h = 0$ in K

2.1 auxiliary problem, define R

2.2 show: R is an isomorphism

2.3 $\Delta v_h = 0$

3. \implies unisolvence

Discretization: Construction of the Discrete Space

$$V_h := \{v \in V : v|_{\partial K} \in \mathbb{B}_k(\partial K) \text{ and } \Delta v|_K \in \mathbb{P}_{k-2}(K) \quad \forall K \in \mathcal{T}_h\}$$
$$\dim = N_V + N_E(k-1) + N_P \frac{k(k-1)}{2} =: N^{tot}$$

- ▶ N_V, N_E, N_P ... number of **internal** vertices, edges and elements

For V_h we can choose the following degrees of freedom:

- ▶ \mathcal{V} : v_h at **internal vertices**
- ▶ \mathcal{E} : v_h at $k-1$ uniformly spaced points on **internal edges** e
- ▶ \mathcal{P} : **moments** $\frac{1}{|K|} \int_K q(x) v_h(x) dx \quad \forall q \in \mathcal{M}_{k-2}(K)$

Discretization: Projection Error

Assumption: A0.2

Assume there exists $\gamma > 0$ such that for all h , each $K \in \mathcal{T}_h$ is star-shaped with respect to a ball of radius $\geq \gamma h_K$.

Theorem: Scott-Dupont

A0.2 implies, that there is a constant $C(\gamma, k)$, such that for every $1 \leq s \leq k + 1$, $w \in H^s(K)$, there exists $w_\pi \in \mathbb{P}_k(K)$ such that

$$\|w - w_\pi\|_{0,K} + h_K |w - w_\pi|_{1,K} \leq Ch_K^s |w|_{s,K}.$$

Discretization: Interpolation Error

Theorem: Brenner-Scott

Assume A0.2. Then there is a constant $C(\gamma, k)$, such that for all $2 \leq s \leq k + 1$, $h, K \in \mathcal{T}_h$, $w \in H^s(K)$, there exists $w_I \in V^{K,k}$ such that

$$\|w - w_I\|_{0,K} + h_K |w - w_I|_{1,K} \leq Ch_K^s |w|_{s,K}.$$

Discretization: Construction of a_h

- ▶ Did not specify a_h so far!
- ▶ Only knowledge: has to satisfy A2 (consistency, stability)

For $p \in \mathbb{P}_k(K)$, $v \in V^{K,k}$, we observe:

$$a^K(p, v) = \int_K \nabla p \cdot \nabla v dx = - \int_K \Delta p v dx + \int_{\partial K} \frac{\partial p}{\partial n} v ds$$

- ▶ $\Delta p \in \mathbb{P}_{k-2}(K)$ and $\frac{\partial p}{\partial n} \in \mathbb{P}_{k-1}(e)$
- ▶ Can compute without knowing v in the interior of K !
(via moments and edge values)

Discretization: Construction of a_h

- ▶ $\bar{\varphi} := \frac{1}{n} \sum_{i=1}^n \varphi(V_i)$
- ▶ $\Pi_K^K : V^{K,k} \rightarrow \mathbb{P}_k(K) \subset V^{K,k}$

$$\begin{cases} a^K(\Pi_k^K v, q) = a^K(v, q) & \forall q \in \mathbb{P}_k(K) \\ \overline{\Pi_k^K v} = \bar{v} \end{cases}$$

- ▶ We have $\Pi_k^K q = q \quad \forall q \in \mathbb{P}_k(K)$
- ▶ Choice: $a_h^K(u, v) := a^K(\Pi_h^K u, \Pi_k^K v)$
 - ✓ k-consistency
 - ✗ stability

Discretization: Construction of a_h

- ▶ Chose $S^K(u, v)$ symmetric, positiv, bilinear form such that

$$c_0 a^K(v, v) \leq S^K(v, v) \leq c_1 a^K(v, v) \quad \forall v \in V^{K,k} \text{ with } \Pi_k^K v = 0$$

- ▶ Define

$$a_h^K(u, v) := a^K(\Pi_k^K u, \Pi_k^K v) + S^K(u - \Pi_k^K u, v - \Pi_k^K v)$$

Theorem: Discrete Bilinear-Form

- ✓ k-consistency
- ✓ stability

Discretization: Choice of S_K

Assumption: A0.3

Assume that there is a $\gamma > 0$ such that for all h and each $K \in \mathcal{T}_h$, the distance between any two vertices of K is $\geq \gamma h_K$.

- ▶ In general: S^K depends on problem
- ▶ S^K must scale like a^K on the kernel of Π_k^K
- ▶ $a^K(\varphi_i, \varphi_j) \simeq 1$

$$S^K(\varphi_i - \Pi_k^K \varphi_i, \varphi_j - \Pi_k^K \varphi_j) := \sum_{r=1}^{N^K} \chi_r(\varphi_i - \Pi_k^K \varphi_i) \chi_r(\varphi_j - \Pi_k^K \varphi_j)$$

Discretization: Right-Hand Side

- ▶ Define right-hand side

$$f_h := P_{k-2}^K f \quad \text{on each } K \in \mathcal{T}_h$$

Then:

$$\langle f_h, v_h \rangle = \sum_K \int_K f_h v_h dx = \sum_K \int_K (P_{k-2}^K f) v_h dx = \sum_K \int_K f (P_{k-2}^K v_h) dx$$

- ▶ only need internal moments
- ▶ Furthermore:

$$\mathcal{F}_h \leq Ch^k \left(\sum_K |f|_{k-1,K}^2 \right)^{\frac{1}{2}}$$

Conclusions

- ▶ Optimal order also for L^2 possible
- ▶ Complicated geometries
- ▶ Higher-order continuity
- ▶ Replace Δ in $V^{K,k}$ by second-order elliptic operator
- ▶ Even further: just require that
 - ▶ $\dim V^{K,k} = N^K$
 - ▶ contains polynomials $\leq k$ on e
 - ▶ contains \mathbb{P}_k
 - ▶ unisolvent

... to be continued ...

this December: **"The Hitchhikers Guide to VEM"**

Thank you.



Veiga, L. Beirao da et al. (2013). "Basic Principles of Virtual Element Methods". In: *Mathematical Models and Methods in Applied Sciences* 23.01, pp. 199–214. DOI: [10.1142/S0218202512500492](https://doi.org/10.1142/S0218202512500492).