

Analysis of DPG for the Poisson problem

Martin Schwalsberger

Supervisor:

A. Univ.-Prof. Dipl.-Ing Dr. Walter Zulehner

December 13, 2017

- 1 Poisson Problem
- 2 Tetrahedral Approximations
- 3 DPG Guideline
- 4 Numerical Results

Poisson Problem

Ω simply connected, Lipschitz boundary

Ω_h a partition into elements K with Lipschitz boundary

$$-\operatorname{div}(\alpha \nabla u) = f \quad \text{on } \Omega \quad (1)$$

$$u = 0 \quad \text{on } \partial\Omega \quad (2)$$

Assumed for presentation $\alpha = 1$, $f \in L^2$

Find $(\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n) \in U = L^2(\Omega) \times L^2(\Omega) \times H_0^{1/2}(\partial\Omega_h) \times H^{-1/2}(\partial\Omega_h)$
such that $\forall (\underline{\tau}, v) \in V = H(\text{div}, \Omega_h) \times H^1(\Omega_h)$:

$$\begin{aligned}(\underline{\sigma}, \underline{\tau})_{\Omega_h} - (u, \text{div} \underline{\tau})_{\Omega_h} + \langle \hat{u}, \text{div} \underline{\tau} \cdot \underline{n} \rangle_{\partial\Omega_h} - (\underline{\sigma}, \nabla v)_{\Omega_h} + \langle v, \hat{\sigma}_n \rangle_{\partial\Omega_h} \\ = (f, v)_{\Omega_h}\end{aligned}$$

With element wise scalar products

For V we need broken/element wise norms:

- $\|(\underline{v}, \underline{q})\|_V^2 = \|\underline{v}\|_{H^1(\Omega_h)}^2 + \|\underline{q}\|_{H(\text{div}, \Omega_h)}^2$
- $\|\underline{v}\|_{H^1(\Omega_h)}^2 = \sum_{K \in \Omega_h} \|\underline{v}\|_{H^1(K)}^2$
- $\|\underline{q}\|_{H(\text{div}, \Omega_h)}^2 = \sum_{K \in \Omega_h} \|\underline{q}\|_{H(\text{div}, K)}^2$

For U we need some trace norms:

- $\|(\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n)\|_U^2 = \|\underline{\sigma}\|_{L^2}^2 + \|u\|_{L^2}^2 + \|\hat{u}\|_{H_0^{1/2}(\partial\Omega_h)}^2 + \|\hat{\sigma}_n\|_{H^{-1/2}(\partial\Omega_h)}^2$
- $\|\hat{u}\|_{H_0^{1/2}(\partial\Omega_h)} = \text{Inf} \{ \|\omega\|_{H^1(\Omega)} \mid \omega \in H_0^1(\Omega), \text{trace}(\omega) = \hat{u} \}$
- $\|\hat{\sigma}_n\|_{H^{-1/2}(\partial\Omega_h)} = \text{Inf} \{ \|q\|_{H(\text{div}, \Omega)} \mid q \in H(\text{div}, \Omega), \text{trace}(q \cdot n) = \hat{\sigma}_n \}$

A Cea-like Lemma

Assume the following conditions for a bilinear form b :

$$\textcircled{1} \quad C_1 \|v\|_V \leq \sup_{u \in U} \frac{b(u, v)}{\|u\|_U} \quad \forall v \in V$$

$$\textcircled{2} \quad \sup_{u \in U} \frac{b(u, v)}{\|u\|_U} \leq C_2 \|v\|_V \quad \forall v \in V$$

$$\textcircled{3} \quad B : U \rightarrow V^* : \text{kern}(B) = \{0\}$$

Then there exists for a linear functional l a unique solution $u \in U$ to:

$$b(u, v) = l(v) \quad \forall v \in V$$

and a solution $u_h \in U_h \subset U$ to

$$b(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h = T(U_h)$$

With an estimate:

$$\|u - u_h\|_U \leq \frac{C_2}{C_1} \inf_{w_h \in U_h} \|u - w_h\|_U \quad (3)$$

We need to proof:

$$(\forall (\underline{\tau}, \mathbf{v}) \in V : b((\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n), (\underline{\tau}, \mathbf{v})) = 0) \implies (\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n) = 0 \quad (4)$$

Idea for the proof:

- 1 Compactly supported test function on an element K
- 2 Find: $\nabla u = \operatorname{div} \underline{\sigma} = 0$ in a weak sense
- 3 $u \in H^1(K), \sigma \in H(\operatorname{div}, K)$
- 4 $u = \hat{u}, \underline{\sigma} \cdot \mathbf{n} = \hat{\sigma}_n$ on $\partial\Omega_h$
- 5 $u \in H_0^1(\Omega), \sigma \in H(\operatorname{div}, \Omega)$
- 6 $u = 0$
- 7 Integration by parts: $(\underline{\sigma}, \underline{\sigma})_{\Omega_h} = 0 \implies \underline{\sigma} = 0$

$$C_1 \|v\|_V \leq \sup_{(\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n) \in U} \frac{b((\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n), (\underline{\tau}, v))}{\|(\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n)\|_U} \quad \forall (\underline{\tau}, v) \in V \quad (5)$$

A Decomposition is the essential step:

$$(\underline{\tau}, v) = (\underline{\tau}_0, v_0) + (\underline{\tau}_1, v_1) \quad (6)$$

Into a broken harmonic part and a $H(\operatorname{div}, \Omega) \times H_0^1(\Omega)$ part, each handled in a Lemma.

We need $(\tau_1, \sigma_1) \in H(\operatorname{div}, \Omega) \times H_0^1$ such that:

$$\begin{aligned}\underline{\tau}_1 - \nabla v_1 &= \underline{\tau} - \nabla v \\ \operatorname{div} \underline{\tau}_1 &= \operatorname{div} \underline{\tau}\end{aligned}$$

Then we get a decomposition:

$$\begin{aligned}\underline{\tau} &= \underline{\tau}_1 + \underline{\tau}_0 \\ v &= v_1 + v_0\end{aligned}$$

Existence and estimates follow on the next slides.

Inhomogeneous Part

$$G \in L^2(\Omega)^N, F \in L^2(\Omega)$$

$$\underline{T}_1 - \nabla v_1 = G \quad \text{on } \Omega \quad (7)$$

$$\operatorname{div} \underline{T}_1 = F \quad \text{on } \Omega \quad (8)$$

Then it has a unique solution and:

$$\|\underline{T}_1\|_{L^2(\Omega)} + \|\nabla v_1\|_{L^2(\Omega)} \leq C(\|G\|_{L^2(\Omega)} + \|F\|_{L^2(\Omega)}) \quad (9)$$

Proof: Well known problem, Babuška-Aziz

Broken Harmonic Part

Assume $(\underline{\tau}_0, v_0) \in H(\text{div}, \Omega_h) \times H^1(\Omega_h)$ fulfills element wise:

$$\underline{\tau}_0 - \nabla v_0 = 0 \quad (10)$$

$$\text{div} \underline{\tau}_0 = 0 \quad (11)$$

Then:

$$\|\underline{\tau}_0\|_{L^2(\Omega_h)} = \|\nabla v_0\|_{L^2(\Omega_h)} \leq C(\|[\underline{\tau}_0 \cdot n]\|_{\partial\Omega_h} + \|[v_0 n]\|_{\partial\Omega_h}) \quad (12)$$

Proof: Blackboard

Finishing Inf-sup Proof

Easy manipulations and previous results give:

$$\|\underline{\tau}\|_{L^2(\Omega)} \leq C(\underbrace{\|\underline{\tau} - \nabla v\|_{L^2(\Omega)}}_G + \underbrace{\|\operatorname{div} \underline{\tau}\|_{L^2(\Omega)}}_F + \|\underline{\tau} \cdot n\|_{\partial\Omega_h} + \|[vn]\|_{\partial\Omega_h})$$

$$\|\nabla v\|_{L^2(\Omega)} \leq C(\underbrace{\|\underline{\tau} - \nabla v\|_{L^2(\Omega)}}_G + \underbrace{\|\operatorname{div} \underline{\tau}\|_{L^2(\Omega)}}_F + \|\underline{\tau} \cdot n\|_{\partial\Omega_h} + \|[vn]\|_{\partial\Omega_h})$$

$$\leq 2C \sup_{(\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n) \in U} \frac{b((\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n), (\underline{\tau}, v))}{\|(\underline{\sigma}, u, \hat{u}, \hat{\sigma}_n)\|_U}$$

$\|\operatorname{div} \underline{\tau}\|_{\Omega_h}$ is part of the right side

$$\|v\|_{L^2(\Omega)} \leq C(\|\nabla v\|_{\Omega_h} + \|[vn]\|_{\partial\Omega_h})$$

This proves the inf-sup condition

We need to proof:

$$\begin{aligned} \|\mathcal{I} - \nabla v\|_{L^2(\Omega)}^2 + \|\operatorname{div} \mathcal{I}\|_{L^2(\Omega)}^2 + \|[\mathcal{I} \cdot n]\|_{\partial\Omega_h}^2 + \|[vn]\|_{\partial\Omega_h}^2 \\ \leq C_2^2 (\|\mathcal{I}\|_{H(\operatorname{div}, \Omega_h)}^2 + \|v\|_{H^1(\Omega_h)}^2) \end{aligned}$$

First two terms are obvious, other two follow from element-wise integration by parts.

All conditions for the Cea-like Lemma have been proven

Approximation for Tetrahedrons

We now have:

$$\|u - u_h\|_U \leq \frac{C_2}{C_1} \inf_{w_h \in U_h} \|u - w_h\|_U$$

$U_h \subset U$ contains piecewise polynomials of some degree,
only \hat{u} is approximated with continuous polynomials

Approximation estimates on a tetrahedral mesh for degree p on each variable:

- 1 $\inf_{w_h} \|u - w_h\|_{L^2} \leq Ch^s p^{-s} |u|_{H^s(\Omega)} \quad (s \leq p + 1)$
- 2 Same for \underline{u}
- 3 $\inf_{\hat{z}_h} \|\hat{u} - \hat{z}_h\|_{H_0^{1/2}(\partial\Omega_h)} \leq C \ln(p)^2 h^s p^{-s} |u|_{H^s(\Omega)} \quad (s \leq p)$
- 4 $\inf_{\hat{\eta}_{n,h}} \|\hat{\sigma}_n - \hat{\eta}_{n,h}\|_{H^{-1/2}(\partial\Omega_h)} \leq C \ln(p)^2 h^s p^{-s} |\sigma|_{H^s(\Omega)} \quad (s \leq p + 1)$

Sufficient regularity, degree $p + 1$ for \hat{u} , p for the rest

$\implies h^{p+1}$ convergence

Optimal test space norm:

$$\|v\|_{opt,V} := \sup_{u \in U} \frac{b(u, v)}{\|u\|_U} \quad (13)$$

Injective trial to test operator $T : U \rightarrow V$:

$$(Tw, v)_V = b(w, v) \quad \forall v \in V \quad (14)$$

For $U_h \subset U$, $V_h = T(U_h)$

Symmetric positive definite system:

$$b(u_h, v_h) = l(v_h) \quad \forall v_h \in V_h \quad (15)$$

The inf-sup condition and boundedness can be interpreted as:

$$C_1 \|v\|_V \leq \|v\|_{opt,V} \leq C_2 \|v\|_V \quad \forall v \in V \quad (16)$$

Replacing $\| * \|_V$ by $\| * \|_{opt,V}$ to compute T would be optimal, but is not feasible.

No conclusions about approximating T in this paper, however the numerical results already use an approximated T operator

Numerical results uniform h-refinement

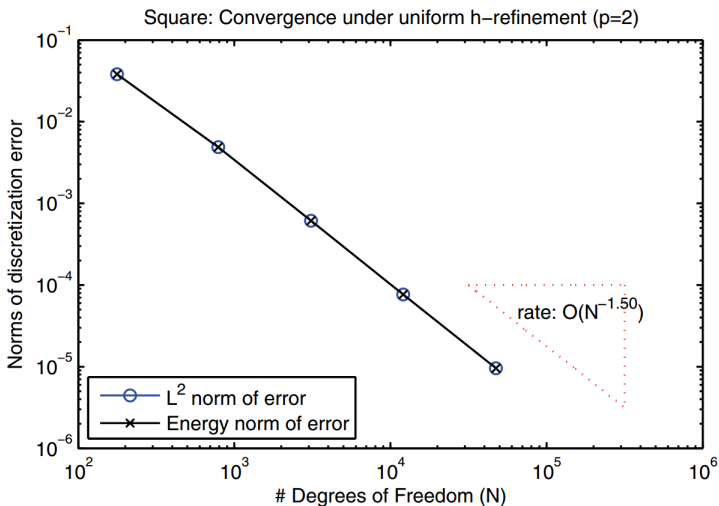


Figure: Square Case

Uniform h-refinement

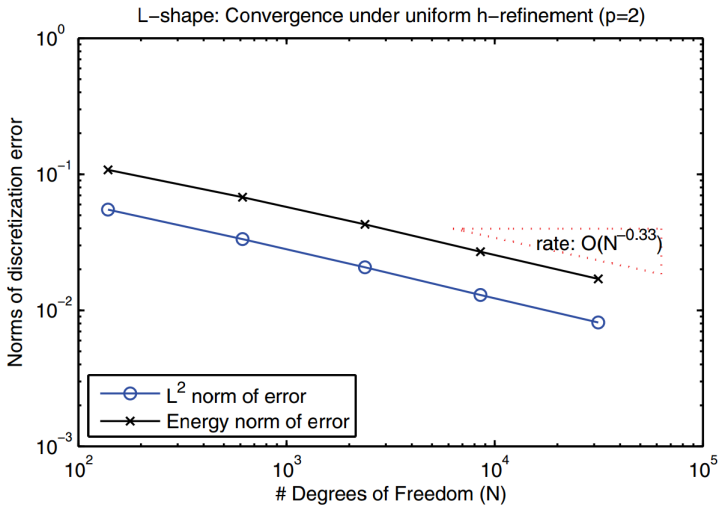
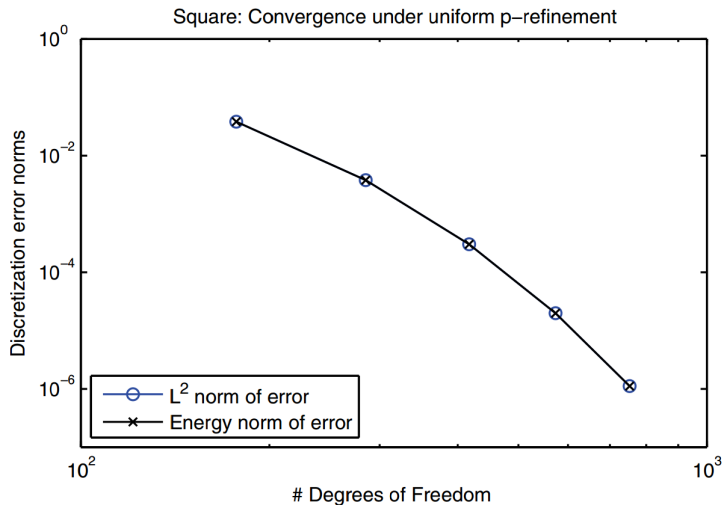
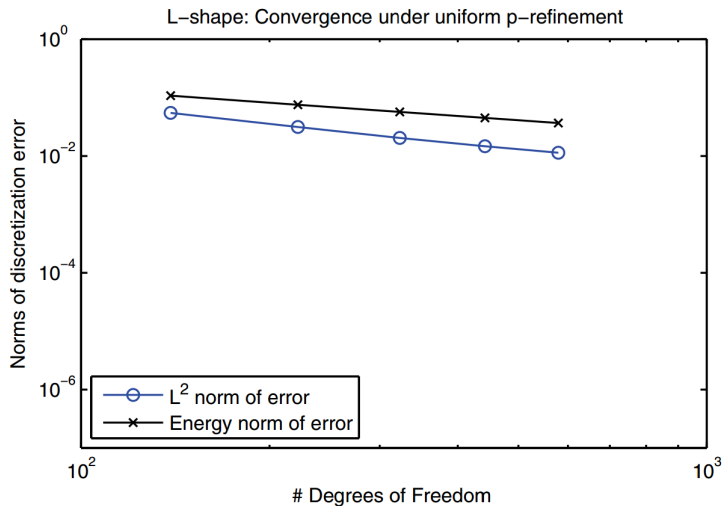


Figure: L-Shape Case

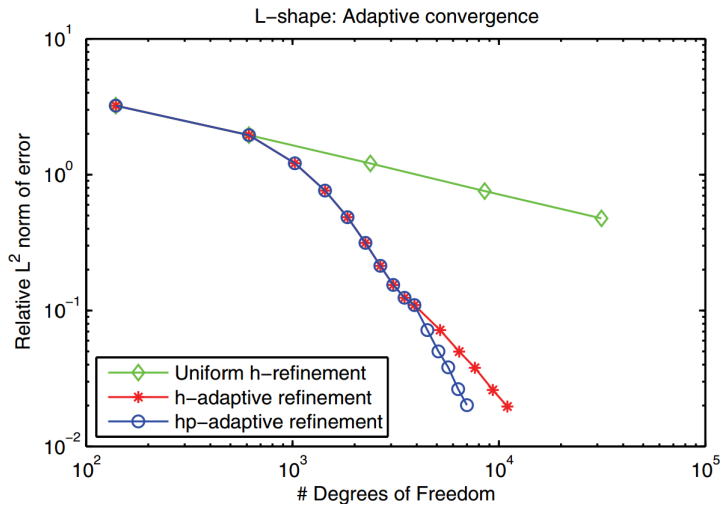
Uniform p-refinement



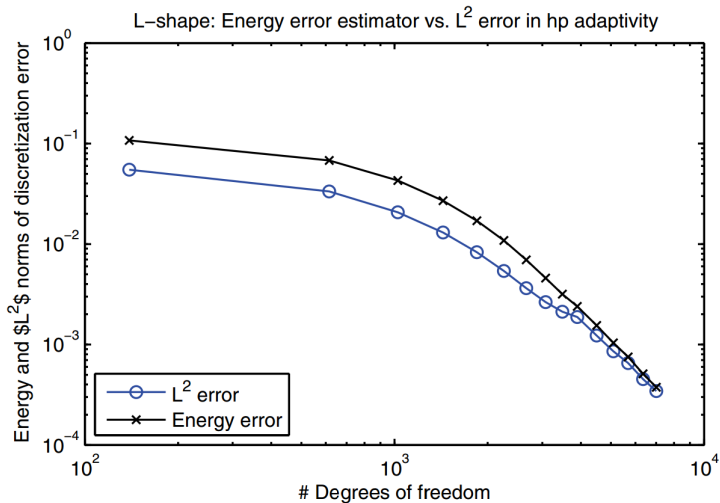
Uniform p-refinement



Adaptive refinement



Error Estimator



Effect of trace degrees

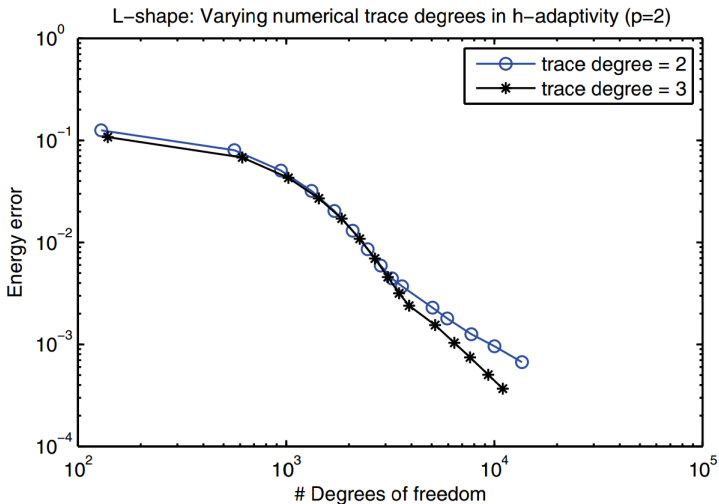


Figure: Choosing inappropriate trace degree impacts approximation

- L. Demkowicz and J. Gopalakrishnan. Analysis of the DPG method for the Poisson equation. *SIAM J. Numer. Anal.*, 49(5):1788-1809, 2011.

Thank you for your attention!