

Robust DPG method for convection-dominated diffusion problem

Seminar on Numerical Analysis
Discontinuous Petrov-Galerkin (DPG) Methods

Andreas Schafelner

Johannes Kepler Universität, Linz

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Outline

- Introduction
- An extension to the convection diffusion equation
- Robust DPG Method
- Numerical examples
- Conclusion

References

- [DG11] L. Demkowicz and J. Gopalakrishnan, *Analysis of the DPG method for the Poisson equation*, SIAM J. Numer. Anal. **49** (2011), no. 5, 1788–1809.
- [DH13] L. Demkowicz and N. Heuer, *Robust DPG method for convection-dominated diffusion problems*, SIAM J. Numer. Anal. **51** (2013), no. 5, 2514–2537.

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A model problem

We consider the convection-diffusion ("confusion") problem

$$\begin{aligned}-\alpha \Delta u + \nabla \cdot (\beta u) &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma,\end{aligned}$$

with its first order reformulation

$$\begin{aligned}\alpha^{-1} \sigma - \nabla u &= 0 && \text{in } \Omega, \\ -\nabla \cdot \sigma + \nabla \cdot (\beta u) &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma.\end{aligned}$$

Special case $\nabla \cdot \beta = 0$

Strong form

Note that $\nabla \cdot (\beta u) = \beta \cdot \nabla u + (\nabla \cdot \beta)u$, hence, for $\nabla \cdot \beta = 0$, we obtain

$$\begin{aligned}\alpha^{-1} \sigma - \nabla u &= 0 && \text{in } \Omega, \\ -\nabla \cdot \sigma + \beta \cdot \nabla u &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma.\end{aligned}$$

Special case $\nabla \cdot \beta = 0$

Ultra-weak form

Find $(u, \sigma, \hat{u}, \hat{\sigma}_n) \in U$, s.t.

$$b((u, \sigma, \hat{u}, \hat{\sigma}_n), (v, \tau)) = l(v, \tau),$$

with

$$\begin{aligned} b((u, \sigma, \hat{u}, \hat{\sigma}_n), (\tau, v)) = & (\alpha^{-1} \sigma, \tau)_{\Omega_h} + (u, \nabla \cdot \tau)_{\Omega_h} - \langle [\tau \cdot n], \hat{u} \rangle \\ & + (\sigma - \beta u, \nabla v)_{\Omega_h} - \langle \hat{\sigma}_n, [v] \rangle \end{aligned}$$

where

$$\hat{\sigma}_n = ((\sigma - \beta u) \cdot n)|_{\Gamma_h}$$

Some spaces & norms I

In the following, we need the spaces

$$\begin{aligned} U &:= L_2(\Omega) \times \mathbf{L}_2(\Omega) \times H_0^{1/2}(\Gamma_h) \times H^{-1/2}(\Gamma_h), \\ V &:= H^1(\Omega_h) \times \mathbf{H}(\text{div}, \Omega_h), \end{aligned}$$

where

$$\begin{aligned} H^1(\Omega_h) &:= \{v \in L_2(\Omega) : v|_K \in H^1(K) \quad \forall K \in \Omega_h\}, \\ H_0^1(\Omega_h) &:= \{v \in H^1(\Omega_h) : v|_\Gamma = 0\}, \\ \mathbf{H}(\text{div}, \Omega_h) &:= \{\boldsymbol{\tau} \in \mathbf{L}_2(\Omega) : \boldsymbol{\tau}|_K \in \mathbf{H}(\text{div}, K) \quad \forall K \in \Omega_h\}, \\ H_0^{1/2}(\Gamma_h) &:= H_0^1(\Omega)|_{\Gamma_h}, \\ H^{-1/2}(\Gamma_h) &:= \{\eta : \exists \boldsymbol{\tau} \in \mathbf{H}(\text{div}, \Omega) : (\boldsymbol{\tau} \cdot \mathbf{n})|_{\Gamma_h} = \eta\}. \end{aligned}$$

Some spaces & norms II

Moreover, we need

$$\|v\|_{1/2,\Gamma_h} := \inf_{w \in H_0^1(\Omega), w|_{\Gamma_h} = v} \|w\|_{1,\Omega},$$

$$\|\eta\|_{-1/2,\Gamma_h} := \inf_{\boldsymbol{\tau} \in \mathbf{H}(\text{div},\Omega), (\boldsymbol{\tau} \cdot \mathbf{n})|_{\Gamma_h}} \|\boldsymbol{\tau}\|_{\mathbf{H}(\text{div},\Omega)},$$

and

$$\|[\boldsymbol{\tau} \cdot \mathbf{n}]\|_{\Gamma_h^0} := \sup_{w \in H_0^{1/2}(\Gamma_h)} \frac{\langle [\boldsymbol{\tau} \cdot \mathbf{n}], w \rangle}{\|w\|_{1/2,\Gamma_h}} = \sup_{w \in H_0^1(\Omega)} \frac{\langle [\boldsymbol{\tau} \cdot \mathbf{n}], w \rangle}{\|w\|_{1,\Omega}}$$

$$\|[v]\|_{\Gamma_h} := \sup_{\eta \in H^{-1/2}(\Gamma_h)} \frac{\langle \eta, [v] \rangle}{\|\eta\|_{-1/2,\Gamma_h}} = \sup_{\boldsymbol{\eta} \in \mathbf{H}(\text{div},\Omega)} \frac{\langle \boldsymbol{\eta} \cdot \mathbf{n}, [v] \rangle}{\|\boldsymbol{\eta}\|_{\mathbf{H}(\text{div},\Omega)}}$$

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The optimal test norm

Let U be the trialspace, equipped with the norm $\|\cdot\|_U$. Then the optimal test norm in the DPG frame work is defined as

$$\begin{aligned}\|(v, \boldsymbol{\tau})\|_{V,\text{opt}}^2 &:= \sup_{(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n) \in U} \frac{b((u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n), (v, \boldsymbol{\tau}))}{\|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_U} \\ &= \|\alpha^{-1} \boldsymbol{\tau} + \nabla v\|_{\Omega_h}^2 + \|\nabla \cdot (\boldsymbol{\tau} - \boldsymbol{\beta} v)\|_{\Omega_h}^2 \\ &\quad + \|[v]\|_{\Gamma_h}^2 + \|[\boldsymbol{\tau} \cdot \boldsymbol{n}]\|_{\Gamma_h^0}^2.\end{aligned}$$

An abstract result

Theorem (Abstract theorem, [DG11])

Let u and u_h be the exact and approximate solution, respectively. Assume that $b(\cdot, \cdot)$ is injective and that there are positive constants C_1, C_2 such that

$$C_1\|(v, \tau)\|_V \leq \|(v, \tau)\|_{V,\text{opt}} \leq C_2\|(v, \tau)\|_V \quad \forall v \in V.$$

Then

$$\|u - u_h\|_U \leq \frac{C_2}{C_1} \inf_{w_h \in U_h} \|u - w_h\|_U.$$

For the lower bound, we need two Lemmata.

Lemma ([DG11])

Let $\boldsymbol{\tau}_0 \in \mathbf{H}(\text{div}, \Omega_h)$ and $v_0 \in H^1(\Omega_h)$ satisfy

$$\alpha^{-1}\boldsymbol{\tau}_0 - \nabla v_0 = 0 \quad \text{on } K$$

$$\nabla \cdot (\boldsymbol{\tau}_0 - \beta v_0) = 0 \quad \text{on } K$$

for every element K in Ω_h . Then

$$\|\boldsymbol{\tau}_0\| + \|\nabla v_0\|_{\Omega_h} \leq C(\alpha, \beta) (\|[\boldsymbol{\tau}_0 \cdot \mathbf{n}]\|_{\Gamma_h^0} + \|[v_0]\|_{\Gamma_h})$$

Proof.

On the blackboard. □

Lemma ([DG11])

Let $\mathbf{G} \in \mathbf{L}_2(\Omega)$ and $F \in L_2(\Omega)$. There is a $\boldsymbol{\tau}_1$ in $\mathbf{H}(\text{div}, \Omega)$ and v_1 in $H_0^1(\Omega)$ satisfying the adjoint problem

$$\begin{aligned}\alpha^{-1}\boldsymbol{\tau}_1 - \nabla v_1 &= \mathbf{G} && \text{in } \Omega, \\ \nabla \cdot (\boldsymbol{\tau}_1 - \beta v_1) &= F && \text{in } \Omega,\end{aligned}$$

and

$$\|\boldsymbol{\tau}_1\| + \|\nabla v_1\| \leq C(\alpha, \beta)(\|\mathbf{G}\| + \|F\|).$$

Proof.

See [DG11].



The final result

Theorem ([DG11])

Suppose u and u_h be the exact and approximate solutions in U and U_h , respectively. Then there is a $C(\alpha) > 0$ independent of U_h and the partition Ω_h , s.t.

$$\mathcal{D} \leq C(\alpha) \mathcal{A},$$

where

$$\mathcal{D} := \|u - u_h\| + \|\boldsymbol{\sigma} - \boldsymbol{\sigma}_h\| + \|\hat{u} - \hat{u}_h\|_{1/2, \Gamma_h} + \|\hat{\sigma}_n - \hat{\sigma}_{n,h}\|_{-1/2, \Gamma_h},$$

$$\mathcal{A} := \inf_{(w_h, \rho_h, \hat{z}_h, \hat{\eta}_{m,h}) \in U_h} \|u - w_h\| + \dots,$$

are the discretization and best approximation error, respectively.

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But what happens if $\alpha = \epsilon \ll 1$ or even $\alpha = \epsilon \rightarrow 0$?

The final result

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But what happens if $\alpha = \epsilon \ll 1$ or even $\alpha = \epsilon \rightarrow 0$?

We need robust (in $\alpha = \epsilon$) estimates!



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A model problem

Recall

$$\begin{aligned}\epsilon^{-1} \boldsymbol{\sigma} - \nabla u &= 0 && \text{in } \Omega, \\ -\nabla \cdot \boldsymbol{\sigma} + \nabla \cdot (\boldsymbol{\beta} u) &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma,\end{aligned}$$

and its ultra-weak formulation with the bilinear form

$$\begin{aligned}b((u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n), (v, \boldsymbol{\tau})) := & (\boldsymbol{\sigma}, \epsilon^{-1} \boldsymbol{\tau} + \nabla v)_{\Omega_h} + (u, \nabla \cdot \boldsymbol{\tau} - \boldsymbol{\beta} \cdot \nabla v)_{\Omega_h} \\ & - \langle [\boldsymbol{\tau} \cdot \mathbf{n}], \hat{u} \rangle - \langle \hat{\sigma}_n, [v] \rangle,\end{aligned}$$

with

$$\hat{\sigma}_n = ((\boldsymbol{\sigma} - \boldsymbol{\beta} u) \cdot \mathbf{n})|_{\Gamma_h}.$$

The main idea

To obtain robust (in ϵ) Cea-like estimates, we will make use of the following fact:

Robustness in the norm relation

$$\|\cdot\|_{U_1} \lesssim \|\cdot\|_E \lesssim \|\cdot\|_{U_2}$$

imply robustness in the estimates

$$\|u - u_h\|_{U_1} \lesssim \inf_{w_h \in U_h} \|u - w_h\|_E, \quad (1)$$

$$\lesssim \inf_{w_h \in U_h} \|u - w_h\|_{U_2}. \quad (2)$$

Preliminaries I

A weight function

Let $\phi \in C^2(\bar{\Omega})$ be a fixed weight function, satisfying

$$0 \leq \phi \leq 1 \text{ in } \Omega, \quad \phi = 0 \text{ on } \Gamma_-,$$

where $\Gamma_- := \{x \in \Gamma : \beta(x) \cdot n < 0\}$ is the inflow boundary.

A formal extension of β

In any point of Ω , we extend β to an orthogonal basis $(\beta, \beta_1^\perp, \beta_2^\perp)$ of \mathbb{R}^3 , with

$$\|\beta^\perp \cdot \eta\|^2 := \|\beta_1^\perp \cdot \eta\|^2 + \|\beta_2^\perp \cdot \eta\|^2, \quad \eta \in L_2(\Omega).$$

Preliminaries II

Assumptions on β

We require $\beta \in C^2(\bar{\Omega})$ and $\beta = O(1)$, $\nabla \cdot \beta = O(1)$. Moreover, we might require

- (A1) $\nabla \times \beta = 0$, $0 < C \leq |\beta|^2 + \frac{1}{2}\nabla \cdot \beta$, $C = O(1)$,
- (A2) $\nabla(\phi\beta) + \nabla(\phi\beta)^\top - \nabla \cdot (\phi\beta)\mathbf{I} = O(1)$,
- (A3) $\nabla \cdot \beta = 0$.

Preliminaries III

A dual norm

$$\|(w, \eta)\|_{\Gamma'_h} := \sup_{(v, \boldsymbol{\tau}) \in V \setminus \{0\}} \frac{\langle [\boldsymbol{\tau} \cdot \mathbf{n}], w \rangle + \langle \eta, [v] \rangle}{\|(v, \boldsymbol{\tau})\|_{\Gamma_h}}$$

for all $(w, \eta) \in H_0^{1/2}(\Gamma_h) \times H^{-1/2}(\Gamma_h)$, with $\|(v, \boldsymbol{\tau})\|_{\Gamma_h} := \|\tilde{v}\|$.

Here $(v, \boldsymbol{\tau}) = (v_0, \boldsymbol{\tau}_0) + (\tilde{v}, \tilde{\boldsymbol{\tau}})$ with $(v_0, \boldsymbol{\tau}_0) \in H_0^1(\Omega) \times \mathbf{H}(\text{div}, \Omega)$ solving

$$\epsilon^{-1} \boldsymbol{\tau}_0 + \nabla v_0 = \epsilon^{-1} \boldsymbol{\tau} + \nabla v,$$

$$\nabla \cdot \boldsymbol{\tau}_0 - \boldsymbol{\beta} \cdot \nabla v_0 = \nabla \cdot \boldsymbol{\tau} - \boldsymbol{\beta} \cdot \nabla v.$$

Preliminaries IV

Some test norms

$$\|(v, \boldsymbol{\tau})\|_{V, \text{qopt}}^2 := \|v\|^2 + \|\epsilon^{-1} \boldsymbol{\tau} + \nabla v\|^2 + \|\nabla \cdot \boldsymbol{\tau} - \boldsymbol{\beta} \cdot \nabla v\|^2,$$

$$\begin{aligned} \|(v, \boldsymbol{\tau})\|_{V,0} := & \epsilon \|v\|^2 + \epsilon \|\nabla v\|^2 + \|\boldsymbol{\beta} \cdot \nabla v\|_{\phi+\epsilon}^2 + \frac{1}{\epsilon^2} \|\boldsymbol{\beta} \cdot \boldsymbol{\tau}\|_{\phi+\epsilon}^2 \\ & + \frac{1}{\epsilon} \|\boldsymbol{\tau}\|^2 + \|\nabla \cdot \boldsymbol{\tau}\|_{\phi+\epsilon}^2, \end{aligned}$$

$$\begin{aligned} \|(v, \boldsymbol{\tau})\|_{V,1} := & \epsilon \|v\|^2 + \epsilon \|\nabla v\|^2 + \|\boldsymbol{\beta} \cdot \nabla v\|_{\phi+\epsilon}^2 + \|\boldsymbol{\tau}\|_{\phi+\epsilon}^2 \\ & + \|\nabla \cdot \boldsymbol{\tau}\|_{\phi+\epsilon}^2. \end{aligned}$$

The trial norms

$$\|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{E,*} := \sup_{(v, \boldsymbol{\tau}) \in V} \frac{b((u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n), (v, \boldsymbol{\tau}))}{\|(v, \boldsymbol{\tau})\|_{V,*}}$$

The main result I

Theorem (DPG method with quasi-optimal test norm $\|\cdot\|_{V,\text{qopt}}$, $\|\cdot\|_E = \|\cdot\|_{E,\text{qopt}}$)

If β satisfies (A1), then the norm relations (1) and (2) hold with

$$\|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{U_1} = \|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{U_2} := (\|u\|^2 + \|\boldsymbol{\sigma}\|^2 + \|(\hat{u}, \hat{\sigma}_n)\|_{\Gamma'_h}^2)^{1/2}.$$

If β satisfies (A1) and (A3), then the first norm relation (1) holds with

$$\|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{U_1} := (\|u\|^2 + \|\boldsymbol{\sigma}\|^2 + \epsilon^2 \|\hat{u}\|_{1/2, \Gamma_h}^2 + \epsilon \|\hat{\sigma}_n\|_{-1/2, \Gamma_h})^{1/2}.$$

The main result II

Theorem (DPG method with weighted test norm $\|\cdot\|_{V,0}, \|\cdot\|_E = \|\cdot\|_{E,0}$)

The second norm relation (2) holds with

$$\begin{aligned} \|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{U_2} := & (\|u\|_{1/(\phi+\epsilon)}^2 + \|\boldsymbol{\beta} \cdot \boldsymbol{\sigma}\|_{1/(\phi+\epsilon)}^2 \\ & + \frac{1}{\epsilon} \|\boldsymbol{\beta}^\perp \cdot \boldsymbol{\sigma}\|^2 + \frac{1}{\epsilon} \|\hat{u}\|_{1/2, \Gamma_h}^2 + \frac{1}{\epsilon} \|\hat{\sigma}_n\|_{-1/2, \Gamma_h}^2)^{1/2}. \end{aligned}$$

If $\boldsymbol{\beta}$ satisfies (A1), (A2) and (A3), then the norm relation (1) holds with

$$\|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{U_1} := (\|u\|^2 + \|\boldsymbol{\sigma}\|^2 + \epsilon^2 \|\hat{u}\|_{1/2, \Gamma_h}^2 + \epsilon \|\hat{\sigma}_n\|_{-1/2, \Gamma_h}^2)^{1/2}.$$

The main result III

Theorem (DPG method with weighted test norm $\|\cdot\|_{V,1}, \|\cdot\|_E = \|\cdot\|_{E,1}$)

The second norm relation (2) holds with

$$\begin{aligned} \|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{U_2} := & \left(\|u\|_{1/(\phi+\epsilon)}^2 + \frac{1}{\epsilon^2} \|\boldsymbol{\sigma}\|_{1/(\phi+\epsilon)}^2 \right. \\ & \left. + \frac{1}{\epsilon} \|\hat{u}\|_{1/2, \Gamma_h}^2 + \frac{1}{\epsilon} \|\hat{\sigma}_n\|_{-1/2, \Gamma_h}^2 \right)^{1/2}. \end{aligned}$$

If β satisfies (A1), (A2) and (A3), then the norm relation (1) holds with

$$\|(u, \boldsymbol{\sigma}, \hat{u}, \hat{\sigma}_n)\|_{U_1} := \left(\|u\|^2 + \|\boldsymbol{\sigma}\|^2 + \epsilon^2 \|\hat{u}\|_{1/2, \Gamma_h}^2 + \epsilon \|\hat{\sigma}_n\|_{-1/2, \Gamma_h}^2 \right)^{1/2}.$$

Proof.

Very technical, depends on the stability of the adjoint problem, see [DH13]. □



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Numerical examples I

Consider the model problem

$$-\epsilon \Delta u + \beta \cdot \nabla u = f \quad \text{in } \Omega = (0, 1)^2, \quad u = u_0 \quad \text{on } \Gamma$$

with $\beta = \nabla(e^x \sin y)$ and f, u_0 such that

$$u(x, y) = \arctan\left(\frac{1 - |(x, y)|}{\epsilon}\right).$$

Here, (A1) and (A3) are satisfied, but not (A2). Moreover, the inflow boundary is at $x = 0$ and $y = 0$, and the weight function is $\phi(x, y) = xy/(x + y)$.

Numerical examples II

The test norm

$$\begin{aligned}\|(v, \boldsymbol{\tau})\|_{V,2}^2 := & \left\| \min \left\{ \frac{\epsilon}{h_1 h_2}, 1 \right\} v \right\|^2 + \|\underline{\beta} \cdot \nabla v\|_{\phi+\epsilon}^2 + \epsilon \|\underline{\beta}^\perp \cdot \nabla v\|^2 \\ & + \min \left\{ \frac{1}{\epsilon}, \frac{1}{h_1 h_2} \right\} \|\boldsymbol{\tau}\|_{\phi+\epsilon}^2 + \|\nabla \cdot \boldsymbol{\tau}\|_{\phi+\epsilon}^2,\end{aligned}$$

with $\underline{\beta} := \beta / |\beta|$.

Numerical examples III

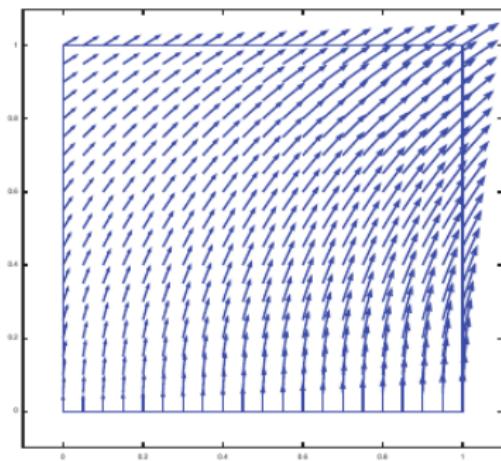
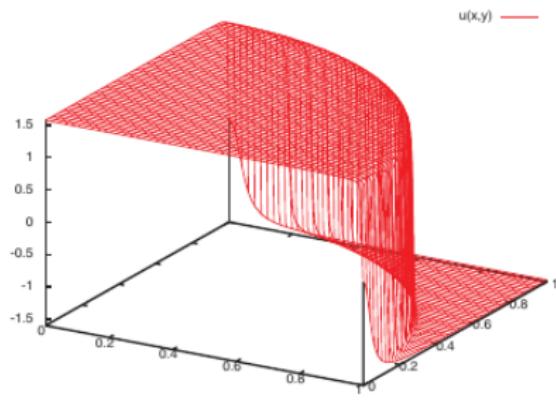


Figure: Solution u and β , for $\epsilon = 10^{-3}$.

Numerical examples IV

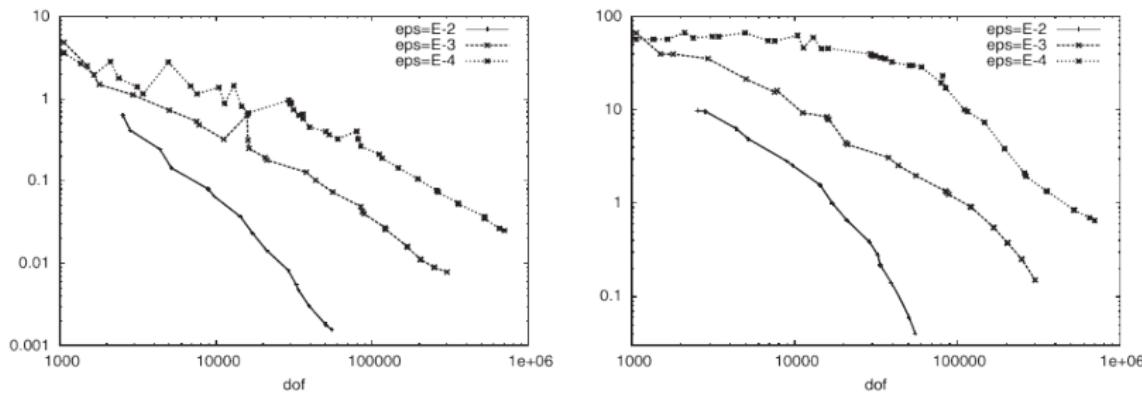


Figure: Left: convergence of the energy norm error. Right: convergence in relative L_2 -norm for the fields variables.

Numerical examples V

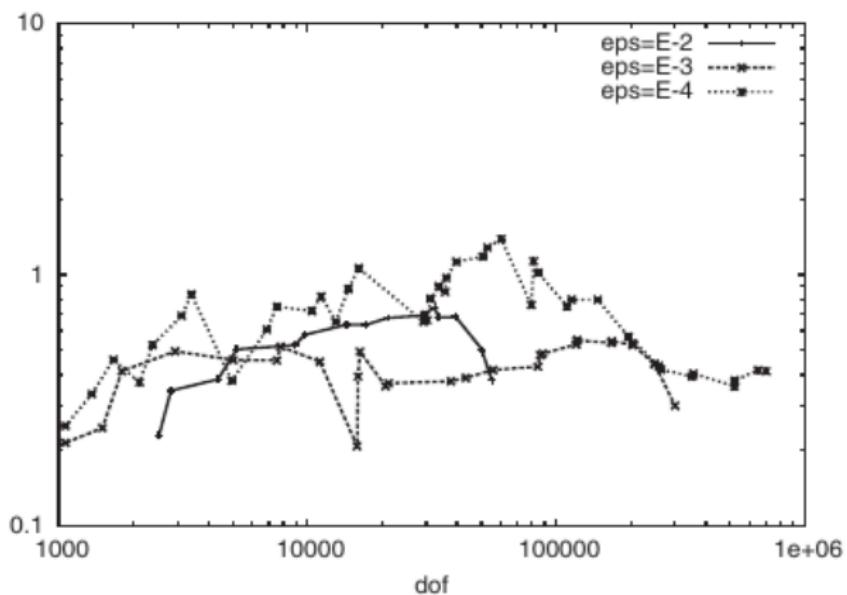


Figure: Norm ratio between L_2 - and energy norm.

Numerical examples VI

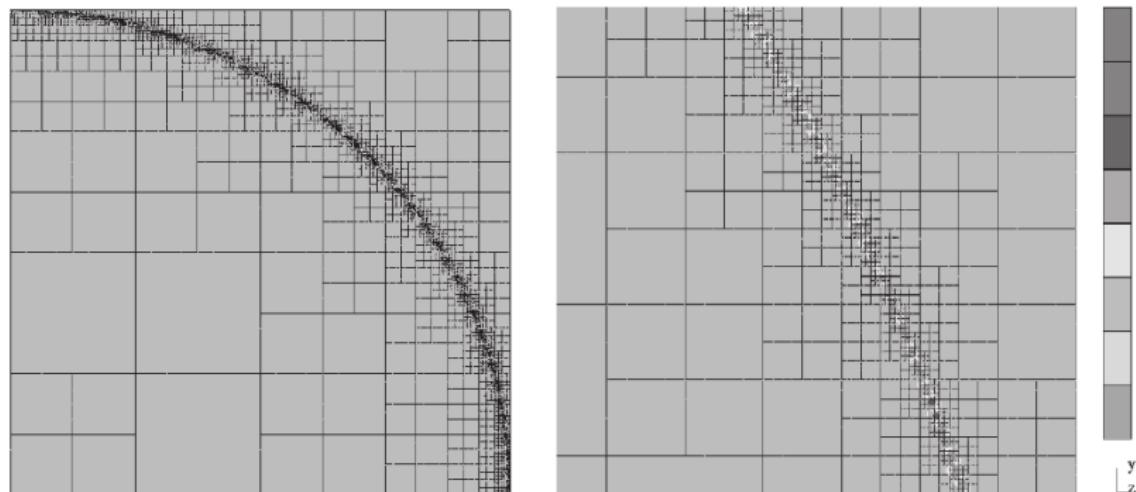


Figure: FE mesh and a zoom to the boundary layer after 35 refinement cycles.



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Conclusions

- analysis of the "*confusion*" problem is a simple extension of the results for the Poisson equation,
- however, for *robustness* wrt the diffusion ϵ , a more involved analysis is required,
- with this frame work, we have robustness for three test norms,
- the quasi-optimal test norm is not practical,
- the rescaled test norm $\|\cdot\|_{V,1}$ is a *optimal* compromise between robustness and practicality.

Thank you!