Stability of Petrov-Galerkin discretizations: Application to the space-time weak formulation for parabolic equations Talk No. 2

Felix Scholz

24.01.2017

#### The Space-Time Weak Formulation of parabolic equations

Choice of spaces and verification of the first assumption

Discretisation and Verification of the second assumption

## The Space-Time Weak Formulation of parabolic equations

### The parabolic equation

Let V and H be Hilbert spaces with embedding with dense embedding  $V \hookrightarrow H$ . By identifying H with H', we obtain the Gelfand triple

$$V \hookrightarrow H \hookrightarrow V'.$$

Now let for any  $t \in [0, T]$ 

be a linear operator. We assume that

- ▶ for all  $v, w \in V$  the mapping  $t \mapsto \langle A(t)v, w \rangle$  is measurable.
- for  $t \in [0,1]$  the operator A(t) is bounded fulfils

$$\langle A(t)v,v \rangle + \lambda \|v\|_{H}^{2} \ge \alpha \|v\|_{V}^{2}$$
 for  $v \in V$ .

### Weak formulation of the parabolic problem

Given a right hand side  $f \in L^2(0, T; V')$  and an initial condition  $u_0 \in H$  find a solution  $u(t) \in V$  such that

$$\frac{du}{dt}(t) + A(t)u(t) = f(t) \qquad \text{in } V'$$
$$u(0) = u_0 \qquad \text{in } H.$$

Space-time weak formulation of the parabolic problem

Multiplying with a test function exin  $H^1(0, T; V)$  and applying partial integration yields the space-time formulation: Find

$$u\in X=L^2(0,\,T;\,V)$$

such that for all

$$q \in Y = L^2(0, T; V) \cap H^1_{\{T\}}(0, T; V')$$

we have

$$\begin{split} &-\int_0^T \left\langle u(t), \frac{\mathrm{d}q(t)}{\mathrm{d}t} \right\rangle_{V \times V'} \mathrm{d}t + \int_0^T \left\langle A(t)u(t), q(t) \right\rangle_{V' \times V} \mathrm{d}t \\ &= \int_0^T \left\langle f(t), q(t) \right\rangle_{V' \times V} \mathrm{d}t + (u_0, q(0))_H \end{split}$$

or equivalently

$$\langle Bu,q\rangle_{Y'\times Y}=\ell(q).$$

### Norms on X and Y

On the spaces X and Y we define norms by

$$||u||_X^2 = ||u||_{L^2(0,T;V)}^2$$

and

$$\|q\|_{Y}^{2} = \|q\|_{L^{2}(0,T;V)}^{2} + \|q\|_{L^{2}(0,T;V')}^{2} + \|\frac{\mathrm{d}q}{\mathrm{d}t}\|_{L^{2}(0,T;V')}^{2}.$$

Now

$$B \in \mathcal{L}(X, Y')$$

is boundedly invertible.

### Choice of spaces and verification of the first assumption

We choose

 $H = L^2(\Omega),$  $V = H^1(\Omega)$ 

which leads to

$$egin{aligned} X &= L^2(0,1;H^1(\Omega)), \ Y &= L^2(0,1;H^1(\Omega)) \cap H^1_{\{T\}}(0,T;(H^1(\Omega))'). \end{aligned}$$

Additionally we choose  $X'_+ \hookrightarrow X'$  and  $Y_+ \hookrightarrow Y$  to be

$$\begin{aligned} X'_{+} &= L^{2}(0, T; L^{2}(\Omega)) \\ Y_{+} &= L^{2}(0, T; H^{2}(\Omega)) \cap H^{1}_{\{T\}}(0, T; L^{2}(\Omega)) \end{aligned}$$

If we have Dirichlet boundary conditions then they need to be included into the space V.

### Verification of the first assumption

For this choice of spaces and under the assumption that  $\partial\Omega$  is smooth and that A(t) has smooth coefficients, the operator Bfulfils the first assumption, i.e. the regularity condition

$$(B')^{-1} \in \mathcal{L}(X'_+, Y_+).$$

# Discretisation and Verification of the second assumption

#### Tensor product discretisation

The function spaces on the space-time are discretised with a tensor product structure. We choose sequences of discrete subspaces

$$egin{aligned} S^x_{j_0} \subset S^x_{j_0+1} \subset \ldots \subset H^1(\Omega), \ S^t_{j_0} \subset S^t_{j_0+1} \subset \ldots \subset L^2(0,T) \end{aligned}$$

and

$$\begin{aligned} & Q_{l_0}^{\mathsf{x}} \subset Q_{l_0+1}^{\mathsf{x}} \subset \ldots \subset H^2(\Omega) \\ & Q_{l_0}^t \subset Q_{l_0+1}^t \subset \ldots \subset H^1_{\{T\}}(0,T). \end{aligned}$$

and define the discrete space-time spaces as

$$\begin{split} S_j &= S_j^r \otimes S_j^x \subset L^2(0,T;H^1(\Omega)) = X\\ Q_l &= Q_l^t \otimes Q_l^x \subset L^2(0,T;H^2(\Omega)) \cap H^1_{\{T\}}(0,T;L^2(\Omega)) = Y_+ \end{split}$$

### Assumptions on the spatial and time spaces

- In the sequel we are going to see which assumptions have to be made on S<sup>x</sup><sub>j</sub>, S<sup>t</sup><sub>j</sub>, Q<sup>t</sup><sub>l</sub>, Q<sup>x</sup><sub>l</sub> for their tensor product spaces to fulfil the second assumption of the main theorem.
- We will for now set S
  <sub>j</sub> = S<sub>j</sub> but this can be generalised to other choices of {S<sub>j</sub>} ⊂ X and {S
  <sub>j</sub>} ⊂ X'<sub>+</sub>.
- The Jackson and Bernstein inequalities on the tensor product space follow from the respective inequalities for each direction.

### Jackson inequality

First, on each of the individual spaces we need the Jackson inequality: For a fixed number  $\omega>1$ 

$$\begin{split} \inf_{\substack{u_{j}^{x} \in S_{j}^{x} \\ u_{j}^{t} \in Q_{j}^{t}}} \|u^{x} - u_{j}^{x}\|_{L^{2}(\Omega)} &\lesssim \omega^{-sj} \|u^{x}\|_{H^{s}(\Omega)} \text{ for } u^{x} \in H^{s}(\Omega), \qquad 0 \leq s \leq d_{s} \\ \inf_{\substack{u_{j}^{t} \in S_{j}^{t} \\ q_{i}^{t} \in Q_{i}^{x}}} \|u^{t} - u_{j}^{t}\|_{L^{2}(0,T)} &\lesssim \omega^{-sj} \|u^{t}\|_{H^{s}(0,T)} \text{ for } u^{t} \in H^{s}(0,T), \qquad 0 \leq s \leq d_{s} \\ \inf_{\substack{q_{i}^{x} \in Q_{i}^{x} \\ q_{i}^{t} \in Q_{i}^{t}}} \|q^{x} - q_{i}^{x}\|_{L^{2}(\Omega,T)} &\lesssim \omega^{-sl} \|q^{x}\|_{H^{s}(\Omega,T)} \text{ for } q^{x} \in H^{s}(\Omega), \qquad 0 \leq s \leq d_{q} \\ \end{split}$$

for constants  $d_{S^{\times}}$ ,  $d_{S^{t}}$ ,  $d_{Q^{\times}}$  and  $d_{Q^{t}}$ , which remain to be determined.

Second, we need the Bernstein inequality on each space:

$$\begin{split} \|u_j^{\mathsf{x}}\|_{H^s(\Omega)} &\lesssim \omega^{sj} \|u_j^{\mathsf{x}}\|_{L^2(\Omega)} \text{ for } u_j^{\mathsf{x}} \in S_j^{\mathsf{x}}, \quad 0 \leq s < \gamma_{S^{\mathsf{x}}}, \\ \|u_j^t\|_{H^s(0,T)} &\lesssim \omega^{sj} \|u_j^t\|_{L^2(0,T)} \text{ for } u_j^t \in S_j^t, \quad 0 \leq s < \gamma_{S^t}, \\ \|q_l^{\mathsf{x}}\|_{H^s(\Omega)} &\lesssim \omega^{sl} \|q_l^{\mathsf{x}}\|_{L^2(\Omega)} \text{ for } q_l^{\mathsf{x}} \in Q_l^{\mathsf{x}}, \quad 0 \leq s < \gamma_{Q^{\mathsf{x}}}, \\ \|q_l^t\|_{H^s(0,T)} &\lesssim \omega^{sl} \|q_l^t\|_{L^2(0,T)} \text{ for } q_l^t \in Q_l^t, \quad 0 \leq s < \gamma_{Q^t}. \end{split}$$

### Choice of the constants

The last assumptions to be made are those on the constants  $d_F$ ,  $\gamma_F$  in the Bernstein and Jackson inequalities. We assume

$$egin{aligned} &\gamma_{\mathcal{S}^{ imes}}, d_{\mathcal{S}^{ imes}} > 1, \ &\gamma_{\mathcal{S}^{t}}, d_{\mathcal{S}^{t}} > 0, \ &\gamma_{\mathcal{Q}^{ imes}}, d_{\mathcal{Q}^{ imes}} > 2 \ &\gamma_{\mathcal{Q}^{t}}, d_{\mathcal{Q}^{t}} > 1. \end{aligned}$$

For example, these assumptions can be fulfilled for hierarchical (h-refined) spline spaces

### Conclusion

- If each direction of a tensor product discretisation fulfils the Jackson and Bernstein inequalities with the given constants γ<sub>F</sub> and d<sub>F</sub>, then also the tensor product fulfils the Jackson and Berstein inequalities.
- ► The assumptions of the main theorem for S<sub>j</sub> = S<sub>j</sub> are thus fulfilled in this case.
- If we want to choose S<sub>j</sub> ≠ Š<sub>j</sub> ⊂ X'<sub>+</sub>, we need an additional stability assumption as well as the Jackson and Berstein inequalities for Š<sup>x</sup><sub>j</sub> and Š<sup>t</sup><sub>j</sub>.