# WEB-SPLINES

concept by K. Höllig, U. Reif, J. Wipper



#### Michael Hauer 2017/01/20 For the course - Spezialvorlesung: Isogeometric Analysis





# **Classification and chronology**

- attempt to unify CAD/CAM and FEM
- meshless finite element technique
- within the standard Ritz-Galerkin framework
- introduced in 2001 by Höllig, Reif and Wipper (compare IgA by Hughes in 2005)

# Outline

#### Definition

- Weighted splines
- Extended splines
- WEB-splines

#### Approximation properties and stability

**Numerical examples** 

**Further remarks** 



# DEFINITION



# DEFINITION



## **WEIGHTED SPLINES**

# **Meshless method**

FEM-mesh

tensor-product basis functions





# **Meshless method**

FEM-mesh

tensor-product basis functions



# How to fulfill Dirichlet boundary conditions?

# Weight functions

- use tensor product B-splines  $b_k$
- multiply basis functions  $b_k$  by a smoothed version  $\omega$  of the distance function to  $\Gamma_D \subset \partial D$
- obtain subspace

```
\operatorname{span}\{\omega b_k: D \cap \operatorname{supp}(b_k) \neq \emptyset\}
```

which confirms to the BC

■ IDEA: Kantorowitsch and Krylow, 1956

# How to choose appropriate weight functions?

assume boundary is defined in terms of simple algebraic equations

use R-Function Method (RFM) by Rvachev et al. (1995, 2000)

Set operation	Corresponding R-function
Complement: D <sup>c</sup>	$r_c(\omega) = -\omega$
Intersection: $D_1 \cap D_2$	$r_{\cap}(\omega_1,\omega_2) = \omega_1 + \omega_2 - \sqrt{\omega_1^2 + \omega_2^2}$
Union: $D_1 \cup D_2$	$r_{\cup}(\omega_1,\omega_2) = \omega_1 + \omega_2 + \sqrt{\omega_1^2 + \omega_2^2}$

 $\rightarrow$  Example on the blackboard

# Weight functions

- other weight functions might be possible
- R-functions are still complicated
- one does not need to compute the explicite form
- for this application some kind of plateau would be useful



# Weighted B-splines

Problem with stability:

Due to possible small areas near the boundary, coefficients in these areas might become large  $\rightarrow$  system ill conditioned





# DEFINITION



## **EXTENDED SPLINES**

# Notation

 $b_k$ 

 $\lambda_k$  $B_k$ 

$$Q_k$$

$$K = \{k : \Omega \cap \mathsf{supp}(b_k) \neq \emptyset\}$$

$$I = \{i : b_i \text{ contains an inner grid cell}\}$$

$$J = K \setminus I$$

 $I(j) = \{i \in I : Q_j \subset \mathsf{supp}(b_i)\}$  $J(i) = \{j \in J : i \in I(j)\}$ 

 $p_{i,j}$ 

- ... B-splines
- ... dual functionals for  $b_k$
- ... extended B-splines
- ... grid cells in support of  $b_k$
- ... set of indices of basis fcts.
  - . set of inner indices
- ... set of outer indices
- ... related inner indices
- ... related outer indices
- ... polynomial which agrees with  $b_i$  on  $Q_j$

# Stability problem - Example in 1D



# **Extended B-splines - 2D basis supports**



Relevant biquadratic B-splines for a domain D

# **Extended B-splines (eb-splines)**

overcome stability problem by suitably joining outer B-splines to inner B-splines

#### Definition

For  $i \in I, j \in J(i)$  we define the extension coefficients

$$e_{i,j} := \lambda_j p_{i,j}.$$

Then the extended B-splines are

$$B_i := b_i + \sum_{j \in J(i)} e_{i,j} b_j, \quad i \in I.$$



## How do we get the extension coefficients?

uniform grid: via Lagrange interpolation

$$e_{i,j} = \prod_{\substack{\nu=0\\\ell+\nu\neq i}}^{n} \frac{j-\ell-\nu}{i-\ell-\nu}$$

nonuniform grid: more difficult

 $\Box$  generate  $p_{i,j}$  in Taylor form

 $\Box$  expand at an arbitrary point  $\tau_j \in Q_j$ 

□ apply dual funcional (de Boor and Fix)

$$\lambda_k f = \sum_{\ell=0}^n (-1)^{n-\ell} \psi_k^{(n-\ell)}(\tau_k) f^{(\ell)}(\tau_k), \quad \psi_k^{(n-\ell)}(x) = \frac{1}{n!} \prod_{\ell=1}^n (t_{k+\ell} - x)$$

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# **Extended B-splines (eb-splines)**

One can show, that eb-splines inherit the properties

- Iocality
- boundedness
- existence of dual functionals
- polynomial precision

from standard B-splines which are crucial for approximation purposes.

# DEFINITION



## **WEB-SPLINES**

# Combine wb-splines and eb-splines

#### Definition

For  $i \in I$ ,  $j \in J(i)$  let the extension coefficients  $e_{i,j}$  be as before. Further let  $\omega$  be a positive weight function, smooth on D and equivalent to some power of the boundary distance function

 $\omega(x) \asymp \mathsf{dist}(x, \partial D)^r.$ 

Then the extended B-splines are

$$B_i := \frac{\omega}{\omega(x_i)} \left( b_i + \sum_{j \in J(i)} e_{i,j} b_j \right), \quad i \in I,$$

where  $x_i$  is the center of the interior grid cell  $Q_i$ .

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# **Different types**

uniform grid, nonuniform grid, hierarchical bases (Kraft), ...



# APPROXIMATION PROPERTIES AND STABILITY



# Some useful remarks

extension coefficients are uniformly bounded

 $|e_{i,j}| \preceq 1$ 

 support of web-splines is larger BUT only a small strip of inner cells is effected, consequently

 $\operatorname{supp}(B_i) \preceq h$ 

web-splines are linearly independent and have the dual functional

$$\Lambda_k = \frac{\omega(x_k)}{\omega} \lambda_k, \quad k \in I$$

# Stability

web-splines and the dual functional are uniformly bounded and biorthogonal

$$||B_i||_0 \leq 1 \quad ||\Lambda_k||_0 \leq 1 \quad \int_D B_i \Lambda_k = \delta_{i,k}$$



# Stability

For a weight function of order  $\gamma$  linear combinations of web-splines satisfy

$$\left|\left|\sum_{i\in I}c_iB_i\right|\right|_0 \asymp h^{m/2}||C||,$$

where the constants depend on D,  $\omega$  and n.



# **Quasi-interpolant**

standard projector

$$P_h u = \sum_{i \in I} \left( \int \lambda_i u \right) B_i$$

if  $\omega$  is an  $\ell\text{-regular}$  weight function of order  $\gamma$ 

$$||P_h u||_{\nu,Q\cap D} \le \operatorname{const}(D,\omega,n)h^{-\nu}||u||_{0,Q'}, \quad \nu \le \min(\ell,n)$$

where Q' is the union of the supports of all web-splines which are nonzero on  $Q \cap D$ .

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# Approximation order

if  $\omega$  is an  $\ell\text{-regular}$  weight function of order  $\gamma$  and v=u/w is smooth on  $\bar{D},$  then

$$||u - P_h u||_{\nu} \leq \operatorname{const}(D, \omega, u, n)h^{n+1-\nu}$$

for  $\nu \leq \min(\ell, n)$ 

 $\rightarrow$  optimal approximation order.

# NUMERICAL EXAMPLES



# Heat conduction problem



# $\begin{array}{lll} \Delta u &= 0 & & \mbox{in } D \\ u &= u_0 & & \mbox{on } \Gamma \\ \partial_\perp u &= -\gamma(u-u_1) & & \mbox{on } \Gamma_0 \\ \partial_\perp u &= 0 & & \mbox{on } \Gamma_a \end{array}$



# Heat conduction problem





Relative errors for hat-functions ( $\diamond$ ) and Web-spline approximations of degree n = 1, 2, 3, 4, 5 (markers  $*, \diamond, \Delta, \Box, \star$ ) as a function of the dimension *d*.

# Further examples in the papers

- linear elasticity
- thin plates
- scattered data approximation



# **FURTHER REMARKS**



# **Multigrid methods**

for uniform B-spline basis:

grid transfer of web-splines (lecture: prolongation matrix)

 $\tilde{B}_{\ell} \dots$  grid width 2h  $B_{\ell} \dots$  grid width h

$$P_h \tilde{B}_\ell = \sum_{i \in I} p_{i,\ell} B_i, \quad p_{i,\ell} = \frac{\omega(x_i)}{\omega(\tilde{x}_\ell)} \left( s_{i-2\ell} + \sum_{j \in \tilde{J}(\ell)} \tilde{e}_{\ell,j} s_{i-2j} \right)$$

where *s* are the coefficients from multivariate B-spline subdivision

# **Application in IgA**

competitor to IgA?



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competitor to IgA?

- Yes: alternative approach, closer to FEM, mathematical insights stability/ approximation properties similarly proven as for FEM
  - No: combination possible (e.g. trimmed surfaces, surfaces with holes ...), chance to use advantages of both methods

# **Advantages and Difficulties**

Advantages stated by the authors

- no mesh generation
- homogeneous BC matched exactly
- accurate solutions with low-dimensional subspaces
- smoothness and approximation order can be chosen arbitrarly
- hierarchical basis permit adaptive refinement
- parallelization and multigrid possible



# **Advantages and Difficulties**

#### Difficulties

tradeoff between difficulties

□ FEM: meshing

□ web-splines: weight functions

□ IgA: parameterization of domain

deciding whether grid cell is completely inside the domain

most of the advantages are valid for IgA as well

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