

**Numerical methods in continuum mechanics 1**  
**Tutorial sheet 2: Thu 26 03 2015**

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4. Show that the Navier Stokes equations in convective form,

$$\begin{aligned} \frac{\partial v}{\partial t} - \Delta v + v \cdot \nabla v + \nabla p &= f \\ \operatorname{div} v &= 0, \end{aligned}$$

are equivalent to the Navier Stokes equations in the conservative form

$$\begin{aligned} \frac{\partial v}{\partial t} - \Delta v + \operatorname{div}(vv^T) + \nabla p &= f \\ \operatorname{div} v &= 0, \end{aligned}$$

or in rotation form

$$\begin{aligned} \frac{\partial v}{\partial t} - \Delta v + (\nabla \times v) \times v + \nabla P &= f \\ \operatorname{div} v &= 0, \end{aligned}$$

with  $P = p + \frac{1}{2}v^2$ .

5. Let  $\Omega := (0, L) \times (0, H)$  for  $L > H > 0$  be a rectangular domain. Compute a lower bound for

$$\sup_{v \in H^1(\Omega)^2} \frac{|v|_1^2}{\|\epsilon(v)\|_0^2},$$

by choosing  $v(x, y) = (2xy, -x^2)$ . Is this  $v \in H^1(\Omega)^2$ ? Why does this lower bound cause problems?

6. Have  $A : B = \sum_{i,j} a_{i,j} b_{i,j}$  and  $\operatorname{tr}(A) = \sum_i a_{i,i}$  and  $\operatorname{dev}(A) = A - \frac{1}{n} \operatorname{tr}(A)I$ . Show that

$$\begin{aligned} A : B &= \operatorname{tr}(A^T B), \\ \operatorname{tr}(ABA^{-1}) &= \operatorname{tr}(B) \end{aligned}$$

and

$$\operatorname{tr}(\operatorname{dev} A) = 0$$

holds for all matrices  $A \in \mathbb{R}^{n \times n}$  and  $B \in \mathbb{R}^{n \times n}$ .

7. Consider the linearized elasticity problem: Find  $u \in [H^1(\Omega)]^3$  such that

$$\int_{\Omega} C\epsilon(u) : \epsilon(v) dx = \int_{\Omega} f \cdot v dx + \int_{\Gamma} t_N \cdot v ds \quad \text{for all } v \in [H^1(\Omega)]^3 \quad (1)$$

Assume that there is a solution  $u \in [H^1(\Omega)]^3$ . Show that the right-hand side must satisfy the following conditions:

$$\int_{\Omega} f dx + \int_{\Gamma} t_N ds = 0 \quad \text{and} \quad \int_{\Omega} x \times f dx + \int_{\Gamma} x \times t_N ds = 0. \quad (2)$$

8. Show that each function  $v \in [H^1(\Omega)]^3$  can be rewritten as

$$v = \hat{v} + v_0,$$

where  $\hat{v} \in \hat{H}(\Omega) := \{v \in H^1(\Omega)^3 : \int_{\Omega} v dx = 0, \int_{\Omega} \operatorname{curl} v dx = 0\}$  and  $v_0 \in RM$  (cf. Lemma 2.4 and Remark 2 on page 15).

9. You know that the problem, find  $u \in \hat{H}(\Omega)$  such that

$$\int_{\Omega} C\epsilon(u) : \epsilon(v) dx = \int_{\Omega} f \cdot v dx + \int_{\Gamma} t_N \cdot v ds \quad \text{for all } v \in \hat{H}(\Omega),$$

has a unique solution.

Show that, assuming (2), the solution of this problem, say  $u^*$ , also satisfies (1). Show moreover that (1) is also satisfied for  $u^* + u_0$ , no matter how  $u_0 \in RM$  is chosen.