# Singular basis functions 

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## Motivating example

One-dimensional BVP:

$$
\begin{aligned}
-\left(a y^{\prime}\right)^{\prime} & =f, \quad x \in(0,1), \\
y(0) & =y(1)=0
\end{aligned}
$$

where

- $a \geq a_{0}>0$ with discontinuity at $x=\xi \quad(0<\xi<1)$
- right-hand side $f$ is piecewise smooth.


## Motivating example

Thence we reformulate the problem: state equation

$$
\begin{align*}
-\left(a y^{\prime}\right)^{\prime} & =f, \quad 0<x<\xi \text { and } \xi<x<1,  \tag{1}\\
y(0) & =y(1)=0
\end{align*}
$$

and continuity conditions

$$
\begin{aligned}
& \lim _{x \rightarrow \xi-0} y(x)=\lim _{x \rightarrow \xi+0} y(x), \\
& \lim _{x \rightarrow \xi-0} a y^{\prime}=\lim _{x \rightarrow \xi+0} a y^{\prime},
\end{aligned}
$$

or, briefly,

$$
\begin{equation*}
[y]_{x=\xi}=0, \quad\left[a y^{\prime}\right]_{x=\xi}=0 \tag{2}
\end{equation*}
$$

## Motivating example

Even for smooth right-hand side $f$, usually the solution $y \notin H^{2}((0,1))$.
Example
Let $\xi=1 / 2, f \equiv 1, a=\left\{\begin{array}{ll}2, & 0 \leq x \leq 1 / 2 \\ 1, & 1 / 2<x \leq 1\end{array}\right.$.
Then the solution is

$$
y=\left\{\begin{array}{ll}
-\frac{x^{2}}{4}+\frac{7}{24} x, & 0 \leq x \leq 1 / 2 \\
-\frac{x^{2}}{2}+\frac{7}{12} x-\frac{1}{12}, & 1 / 2<x \leq 1
\end{array} .\right.
$$

One can see $y \in H^{1}((0,1))$, but $y \notin H^{2}((0,1))$ (since $y^{\prime}$ is discontinuous).

## Motivating example

Multiply the equation

$$
-\left(a y^{\prime}\right)^{\prime}=f, \quad 0<x<\xi \text { and } \xi<x<1,
$$

by an arbitrary function $\phi \in H_{0}^{1}((0,1))$ and integrate on $(0,1)$. Then using integration by parts on $(0, \xi)$ and $(\xi, 1)$ and jump condition from (2), we deduce

$$
\begin{equation*}
\int_{0}^{1} a y^{\prime} \phi^{\prime} d x=\int_{0}^{1} f \phi d x \tag{3}
\end{equation*}
$$

The converse statement is also true: if $y \in H_{0}^{1}((0,1))$ satisfies (3) for any $\phi \in H_{0}^{1}((0,1))$, then it satisfies the system (1) and the conditions (2).

## Variational numerical scheme in 1D

We focus on the variational solution $y$ of the problem (3). Consider a variational scheme based on piecewise linear approximations and corresponding order of approximation.
Also consider on $(0,1)$ a regular mesh $x_{i}=i h, i=1, \ldots, N, h=1 / N$. Approximate solution $\tilde{v} \in V_{h} \subset H_{0}^{1}((0,1))$ satisfies the integral equation

$$
\int_{0}^{1} a \tilde{v}^{\prime} \tilde{\phi}^{\prime} d x=\int_{0}^{1} f \tilde{\phi} d x
$$

for any $\tilde{\phi} \in V_{h}$.
For the approximation error $(y-\tilde{v})$ we have an estimate

$$
\|y-\tilde{v}\|_{1,(0,1)} \leq C\|y-\tilde{y}\|_{1,(0,1)}
$$

where $\tilde{y}$ is a nodal interpolant of $y(x)$.

## Variational numerical scheme in 1D

When the point of discontinuity $\xi$ coincides with one meshnode, the terms of

$$
\|y-\tilde{y}\|_{1,(0,1)}^{2}=\|y-\tilde{y}\|_{1,(0, \xi)}^{2}+\|y-\tilde{y}\|_{1,(\xi, 1)}^{2}
$$

are estimated above by $C h^{2}\|y\|_{2,(0, \xi)}^{2}$ and $C h^{2}\|y\|_{2,(\xi, 1)}^{2}$.
As a result,

$$
\|y-\tilde{v}\|_{1,(0,1)}=O(h) .
$$

## Variational numerical scheme in 1D

When there is no meshnode in $O\left(h^{2}\right)$-neighborhood of singular point $\xi$ :

- for simplicity $\xi=1 / 2$
- $N$ is odd
- closest meshnodes are $x_{L}=1 / 2-h / 2, x_{R}=1 / 2+h / 2$

Then

$$
\|y-\tilde{v}\|_{1,(0,1)}^{2} \geq \int_{x_{L}}^{x_{R}}\left(y^{\prime}-\tilde{v}^{\prime}\right)^{2} d x \geq \min _{\alpha} \int_{x_{L}}^{x_{R}}\left(y^{\prime}-\alpha\right)^{2} d x .
$$

Discontinuity of $y^{\prime}$ at $1 / 2$ yields that

$$
\begin{aligned}
& \min _{\alpha} \int_{x_{L}}^{x_{R}}\left(y^{\prime}-\alpha\right)^{2} d x \geq C h+O\left(h^{2}\right) \\
& \Rightarrow\|y-\tilde{v}\|_{1,(0,1)} \geq C h^{1 / 2}
\end{aligned}
$$

## 2D problem with discontinuous coefficients

In the domain $\Omega \subset \mathbb{R}^{2}$ with smooth boundary $S$ consider the equation

$$
\begin{equation*}
L u \equiv-\frac{\partial}{\partial x_{i}} a_{i j} \frac{\partial u}{\partial x_{j}}+b_{i} \frac{\partial u}{\partial x_{i}}+a u=f \tag{4}
\end{equation*}
$$

with one type of boundary conditions

$$
\begin{gather*}
\left.u\right|_{S}=0  \tag{5}\\
\left.\left(\frac{\partial u}{\partial N}+\sigma u\right)\right|_{S}=0 \tag{6}
\end{gather*}
$$

## 2D problem with discontinuous coefficients

Conditions on the data:

- coefficients $b_{1}, b_{2}, a$ and right-hand side $f$ are bounded piecewise smooth functons
- coefficients $a_{i j}$ have discontinuities along smooth closed curve $\Gamma \subset \Omega$
- $a_{i j}$ are bounded and continuous on $\Omega_{1}$ (bounded by $\Gamma$ ) and $\Omega_{2}=\Omega \backslash \bar{\Omega}_{1}$
- $\frac{\partial a_{i j}}{\partial x_{k}}$ are bounded and piecewise smooth on $\Omega_{1}$ and $\Omega_{2}$


## 2D problem with discontinuous coefficients

For the problem (4), (5) or (4), (6) we require on the curve $\Gamma$

$$
\begin{equation*}
\left.[u]\right|_{\Gamma}=0,\left.\quad\left[\frac{\partial u}{\partial N}\right]\right|_{\Gamma}=0, \tag{7}
\end{equation*}
$$

where

$$
\left.\left[\frac{\partial u}{\partial N}\right]\right|_{\Gamma}=a_{i j}^{+} \frac{\partial u^{+}}{\partial x_{i}} \cos \left(\nu, x_{j}\right)-a_{i j}^{-} \frac{\partial u^{-}}{\partial x_{i}} \cos \left(\nu, x_{j}\right) .
$$

Classical solution satisfies

- $u(x) \in C(\bar{\Omega}) \cap C^{1}\left(\Omega_{i}\right), i=1,2$
- $u(x) \in C^{2}\left(\Omega_{i}\right), i=1,2$
- $L u=f$ on $\Omega_{1} \cup \Omega_{2}$


## 2D problem with discontinuous coefficients

Define generalized solution for (4), (5), (7) with $f \in L^{2}(\Omega): u \in H_{0}^{1}(\Omega)$ satisfies

$$
L_{\Omega}(u, \varphi)=\int_{\Omega}\left[a_{i j} \frac{\partial u}{\partial x_{i}} \frac{\partial \varphi}{\partial x_{j}}+b_{i} \frac{\partial u}{\partial x_{i}} \varphi+a u \varphi\right] d \Omega=\int_{\Omega} f \varphi d \Omega
$$

for any $\varphi \in H_{0}^{1}(\Omega)$.

## 2D problem with discontinuous coefficients

Define generalized solution for (4), (5), (7) with $f \in L^{2}(\Omega): u \in H_{0}^{1}(\Omega)$ satisfies

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$$

for any $\varphi \in H_{0}^{1}(\Omega)$.
If $u \in H^{2}\left(\Omega_{i}\right), i=1,2$, then (integrating by parts)

$$
\int_{\Omega}(L u-f) \varphi d \Omega+\int_{\Gamma} \varphi\left[\frac{\partial u}{\partial N}\right] d s=0
$$

hence

$$
\begin{aligned}
& L u=f, \\
& {\left.\left[\frac{\partial u}{\partial N}\right]\right|_{\Gamma}=0 .}
\end{aligned}
$$

## 2D problem with piecewise smooth boundary

Again consider in $\Omega \subset \mathbb{R}^{2}$ the equation

$$
L u \equiv-\frac{\partial}{\partial x_{i}} a_{i j} \frac{\partial u}{\partial x_{j}}+b_{i} \frac{\partial u}{\partial x_{i}}+a u=f
$$

with 1st, 3rd types of $B C$, or

$$
\begin{equation*}
\left.u\right|_{S_{1}}=0,\left.\quad\left(\frac{\partial u}{\partial N}+\sigma u\right)\right|_{S_{2}}=0 \tag{8}
\end{equation*}
$$

where $S=S_{1} \cup S_{2}$.
Coefficients and RHS of the equation satisfy regularity conditions (A). But for mixed BC (8) in general $u \notin H^{2}(\Omega)$.

## 2D problem with piecewise smooth boundary

Generalized solution for mixed $B C: u \in H_{S_{1}}^{1}(\Omega)$ satisfies
$L_{\Omega, S_{2}}(u, \varphi) \equiv \int_{\Omega}\left[a_{i j} \frac{\partial u}{\partial x_{i}} \frac{\partial \varphi}{\partial x_{j}}+b_{i} \frac{\partial u}{\partial x_{i}} \varphi+a u \varphi\right] d \Omega+\int_{S_{2}} \sigma u \varphi d s=(f, \varphi)_{\Omega}$ for any $\varphi \in H_{S_{1}}^{1}(\Omega)$.

## 2D problem with piecewise smooth boundary

Consider $\omega$ - the sector of unit circle with angle $\beta$, and corresponding Dirichlet problem for Poisson equation:

$$
\begin{equation*}
-\Delta u=f,\left.\quad u\right|_{S}=0 \tag{9}
\end{equation*}
$$

Function

$$
\Psi=\zeta(r) r^{\lambda} \sin \lambda \theta
$$

is a generalized solution of (9), where $\lambda=\pi / \beta$ and
$\zeta=\left\{\begin{array}{ll}1, & 0 \leq r \leq 1 / 3 \\ 0, & 2 / 3 \leq r \leq 1\end{array}\right.$ is monotone and smooth.
One can verify that $\psi \in H_{0}^{1}(\omega)$.

## 2D problem with piecewise smooth boundary

Using

$$
\triangle u=\frac{\partial^{2} u}{\partial r^{2}}+\frac{1}{r} \frac{\partial u}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} u}{\partial \theta^{2}}
$$

one can show that $\Delta \Psi \in L^{2}(\omega)$.
Notice that
$\|\Psi\|_{2, \omega}^{2} \geq \int_{\omega}\left(\frac{\partial^{2} \Psi}{\partial r^{2}}\right)^{2} r d r d \theta \geq \int_{0}^{1 / 2} \int_{0}^{\beta} \lambda^{2}(\lambda-1)^{2} r^{2 \lambda-3} \sin ^{2} \lambda \theta d r d \theta$.
When $\pi<\beta<2 \pi$, we have $1 / 2<\lambda<1$ and $\Psi \notin H^{2}(\omega)$.

## 2D problem with piecewise smooth boundary

Using

$$
\Delta u=\frac{\partial^{2} u}{\partial r^{2}}+\frac{1}{r} \frac{\partial u}{\partial r}+\frac{1}{r^{2}} \frac{\partial^{2} u}{\partial \theta^{2}},
$$

one can show that $\Delta \Psi \in L^{2}(\omega)$.
Notice that
$\|\Psi\|_{2, \omega}^{2} \geq \int_{\omega}\left(\frac{\partial^{2} \Psi}{\partial r^{2}}\right)^{2} r d r d \theta \geq \int_{0}^{1 / 2} \int_{0}^{\beta} \lambda^{2}(\lambda-1)^{2} r^{2 \lambda-3} \sin ^{2} \lambda \theta d r d \theta$.
When $\pi<\beta<2 \pi$, we have $1 / 2<\lambda<1$ and $\Psi \notin H^{2}(\omega)$.
Singular points on the boundary:

- corner points with inner angles $\pi<\beta<2 \pi$
- points of switching the boundary condition: $\bar{S}_{1} \cap \bar{S}_{2}$


## 2D problem with piecewise smooth boundary

## Theorem

Any solution of the stated problem with $f \in L^{2}(\Omega)$ can be expressed as

$$
u=\sum_{j} \gamma_{j} \Psi_{j}+w
$$

where $w \in H^{2}(\Omega), \gamma_{j}$ are constant, $\Psi_{j} \in H^{1}(\Omega)$ are independent of $f$ and

1. $L \Psi_{j} \in L^{2}(\Omega)$
2. each singular point generates one or two functions $\Psi_{j}$; if $B C$ is not switched, then exactly one function $\Psi_{j}$
3. $\Psi_{j}$ is non-zero only near the corresponding singular point
4. $\left.\Psi_{j}\right|_{S_{1}}=0$

In addition,

$$
\sum_{j}\left|\gamma_{j}\right|+\|w\|_{2, \Omega} \leq C\|f\|_{0, \Omega} .
$$

## 2D problem with piecewise smooth boundary

Exact representation of $\Psi_{j}$ : find $u$

$$
\begin{aligned}
-\triangle u & =0 \text { in } \omega \\
u(r, 0) & =u(r, \beta)=0
\end{aligned}
$$

in the form $u=r^{\mu} \Phi(\theta)$.
We have

$$
\frac{d^{2} \Phi}{d \theta^{2}}+\mu^{2} \Phi=0
$$

Since $\Phi(0)=\Phi(\beta)=0$, non-trivial solution exists for $\mu_{n}=n \lambda$ $(\lambda=\pi / \beta)$ :

$$
\begin{aligned}
& \Phi_{n}=\sin n \lambda \theta, \quad n=1,2, \ldots \\
& \Rightarrow \quad u_{n}=r^{n \lambda} \sin n \lambda \theta
\end{aligned}
$$

Since $u_{n}(r, \theta) \in H^{2}(\omega)(n>1)$, but $u_{1}(r, \theta) \notin H^{2}(\omega)$, a singular function has a form

$$
\Psi=\zeta(r) u_{1}(r, \theta)=\zeta(r) r^{\lambda} \sin \lambda \theta
$$

2D problem with piecewise smooth boundary Other cases of BC:

1. $\left.\frac{\partial u}{\partial n}\right|_{\theta=0}=\left.\frac{\partial u}{\partial n}\right|_{\theta=\beta}=0, \pi<\beta<2 \pi$

$$
\Rightarrow \Psi=\zeta(r) r^{\lambda} \cos \lambda \theta, \quad \lambda=\pi / \beta
$$

2. $\left.\frac{\partial u}{\partial n}\right|_{\theta=0}=\left.u\right|_{\theta=\beta}=0, \pi / 2<\beta<2 \pi$

$$
\Rightarrow \Psi_{1}=\zeta(r) r^{\lambda_{1}} \cos \lambda_{1} \theta, \quad \lambda_{1}=\pi / 2 \beta \quad \text { for } \pi / 2<\beta \leq 3 \pi / 2
$$

and also

$$
\Psi_{2}=\zeta(r) r^{\lambda_{2}} \cos \lambda_{2} \theta, \quad \lambda_{2}=3 \pi / 2 \beta \quad \text { for } 3 \pi / 2<\beta<2 \pi
$$

3. $\left.u\right|_{\theta=0}=\left.\frac{\partial u}{\partial n}\right|_{\theta=\beta}=0, \pi / 2<\beta<2 \pi$

$$
\Rightarrow \Psi_{1}=\zeta(r) r^{\lambda_{1}} \sin \lambda_{1} \theta, \quad \lambda_{1}=\pi / 2 \beta \quad \text { for } \pi / 2<\beta \leq 3 \pi / 2
$$

and also

$$
\Psi_{2}=\zeta(r) r^{\lambda_{2}} \sin \lambda_{2} \theta, \quad \lambda_{2}=3 \pi / 2 \beta \quad \text { for } 3 \pi / 2<\beta<2 \pi
$$

## 2D problem with piecewise smooth boundary

Defining singular functions for general operator $L$ with piecewise linear boundary around corner points:

1. change of variables

$$
\eta_{1}=x_{1}+\mu x_{2}, \quad \eta_{2}=\nu x_{2}
$$

to obtain $\tilde{L}=-\triangle_{\eta}+\tilde{b}_{j} \frac{\partial}{\partial \eta_{j}}+\tilde{a}$
2. for sufficiently small $\varepsilon>0$ the example of singular function is (in polar coordinates $(\rho, \kappa)$ )

$$
\Psi=\zeta(\rho / \varepsilon) \rho^{\lambda} \sin \lambda \kappa
$$

## Singularities for intersection of discontinuity curve with boundary

Arising singularity functions depend only on

- coefficients $a_{i j}$ for 2nd derivatives at intersection points
- angles between discontinuity curve and jointed parts of the boundary


## Singularities for intersection of discontinuity curve with boundary

Arising singularity functions depend only on

- coefficients $a_{i j}$ for 2nd derivatives at intersection points
- angles between discontinuity curve and jointed parts of the boundary Model problem:

$$
\left\{\begin{array}{l}
a^{+} \triangle u^{+}=f^{+} \quad \text { in } \Omega_{+} \\
a^{-} \triangle u^{-}=f^{-} \quad \text { in } \Omega_{-} \\
\left.u\right|_{S}=0 \\
\left.u^{+}\right|_{x_{\mathbf{2}}=0}=\left.u^{-}\right|_{x_{\mathbf{2}}=0},\left.\quad a^{+} \frac{\partial u^{+}}{\partial n^{+}}\right|_{x_{\mathbf{2}}=0}=\left.a^{-} \frac{\partial u^{-}}{\partial n^{+}}\right|_{x_{\mathbf{2}}=0}
\end{array}\right.
$$

where $u=\left\{\begin{array}{l}u^{+} \text {in } \Omega_{+}, \\ u^{-} \text {in } \Omega_{-},\end{array} \quad f=\left\{\begin{array}{l}f^{+} \text {in } \Omega_{+}, \\ f^{-} \text {in } \Omega_{-},\end{array} \quad, \Omega_{-}=\Omega \backslash \bar{\Omega}_{+}\right.\right.$,
$\Omega_{+} \cap \Omega_{-} \subset\left\{x: x_{2}=0\right\}$.

## Singularities for intersection of discontinuity curve with boundary

Theorem
In the given problem for any $f \in L^{2}(\Omega)$ there exists a generalized solution $u \in H_{0}^{1}(\Omega)$ which can be written as

$$
u=\sum_{j} \gamma_{j} \Psi_{j}+w
$$

where $\psi_{j} \in H^{1}(\Omega)$ are independent of $f, w \in B^{2}(\Omega)$, $a^{+} \triangle \Psi_{j} \in L^{2}\left(\Omega_{+}\right)$, $a^{-} \triangle \Psi_{j} \in L^{2}\left(\Omega_{-}\right)$. Number of $\Psi_{j}$ is not greater than 2 .

Singularities for intersection of discontinuity curve with boundary

Determining the functions $\Psi_{j}$ : solve the homogeneous problem in polar coordinates in the form $u=r^{\mu} \Phi(\theta)$, where $\Phi(\theta)= \begin{cases}\Phi^{+}(\theta), & 0<\theta<\beta_{+}, \\ \Phi^{-}(\theta), & -\beta_{-}<\theta<0 .\end{cases}$
Boundary conditions:

$$
u^{+}\left(r, \beta_{+}\right)=u^{-}\left(r,-\beta_{-}\right)=0 .
$$

The state equation reads as

$$
a(\theta) \Phi^{\prime \prime}(\theta)+a(\theta) \mu^{2} \Phi(\theta)=0
$$

where $a(\theta)= \begin{cases}a^{+}, & 0<\theta<\beta_{+}, \\ a^{-}, & -\beta_{-}<\theta<0 .\end{cases}$

Singularities for intersection of discontinuity curve with boundary

Due to $\operatorname{BC} \Phi^{+}\left(\beta_{+}\right)=\Phi^{-}\left(-\beta_{-}\right)=0$ we obtain

$$
\Phi^{+}=C_{+} \sin \mu\left(\beta_{+}-\theta\right), \quad \Phi^{-}=C_{-} \sin \mu\left(\beta_{-}+\theta\right)
$$

Compatibility conditions yield that

$$
\begin{aligned}
C_{+} \sin \mu \beta_{+} & =C_{-} \sin \mu \beta_{-} \\
-a^{+} C_{+} \mu \cos \mu \beta_{+} & =a^{-} C_{-} \mu \cos \mu \beta_{-}
\end{aligned}
$$

This system has a non-trivial solution wrt $C_{+}, C_{-}$, if the determinant

$$
D(\mu) \equiv a^{-} \mu \sin \mu \beta_{+} \cos \mu \beta_{-}+a^{+} \mu \sin \mu \beta_{-} \cos \mu \beta_{+}=0
$$

One can show that the equation has at most two solutions on $(0,1)$. Finally,

$$
\Psi_{j}(r, \theta)=\zeta(r) r^{\mu_{j}} \begin{cases}\sin \mu_{j}\left(\beta_{+}-\theta\right), & 0<\theta<\beta_{+} \\ \sin \mu_{j}\left(\beta_{-}+\theta\right), & -\beta_{-}<\theta<0\end{cases}
$$

where $0<\mu_{j}<1$ are roots of $D(\mu)$.

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## Accuracy of variational schemes for piecewise smooth boundary

Consider piecewise linear approximations on nonregular mesh. Let a singular point on $\partial \Omega$ be the origin, and corresp. singular function $\psi=\zeta(r / \varepsilon) r^{\lambda} \sin \lambda \theta, 0<\lambda<1$. Then solution in this neighborhood has a form $u=\gamma \Psi+w, w \in H^{2}(\Omega)$.

## Accuracy of variational schemes for piecewise smooth boundary

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Consider a triangle $\triangle$ from the mesh lying at a distance $O(h)$ from the origin. For approximate solution $\tilde{v}$

$$
\begin{aligned}
& \|u-\tilde{v}\|_{1, \Omega} \geq\|\gamma \Psi+w-\tilde{v}\|_{1, \Delta} \geq\|\gamma \Psi+\tilde{w}-\tilde{v}\|_{1, \Delta}-\|w-\tilde{w}\|_{1, \Delta} \\
& \geq \min _{\tilde{\phi} \in V_{h}}|\gamma|\|\Psi-\tilde{\phi}\|_{1, \triangle}-\|w-\tilde{w}\|_{1, \triangle}
\end{aligned}
$$

Since $\nabla \tilde{\phi}$ is constant on $\triangle$,

$$
\|\gamma \Psi+w-\tilde{v}\|_{1, \Delta} \geq|\gamma| \min _{\tilde{a} \in \mathbb{R}^{2}}\|\nabla \Psi-\vec{a}\|_{0, \Delta}-\|w-\tilde{w}\|_{1, \Delta} .
$$

Accuracy of variational schemes for piecewise smooth boundary

Assume that origin is one of triangle vertices. Then (see Appendix)

$$
\min _{\vec{a} \in \mathbb{R}^{2}}\|\nabla \Psi-\vec{a}\|_{0, \Delta} \geq C h^{\lambda} .
$$

Since $\|w-\tilde{w}\|_{1, \Delta} \leq C h$, for $\gamma \neq 0$ and sufficiently small $h$ an upper bound

$$
\|u-\tilde{v}\|_{1, \Omega} \geq C h^{\lambda}
$$

holds.

## Variational schemes for problems with discontinuous coefficients

Consider elliptic problems with smooth boundary $S$ and pure 1st or 3rd type of BC . Here the curve of discontinuity $\Gamma$ is closed and smooth, $\Gamma \cap S=\varnothing$.

## Variational schemes for problems with discontinuous coefficients

Consider elliptic problems with smooth boundary $S$ and pure 1st or 3rd type of $B C$. Here the curve of discontinuity $\Gamma$ is closed and smooth, $\Gamma \cap S=\varnothing$.
We build the mesh $\Omega_{e x}^{h}$ for piecewise linear approximations using non-regular triangulations, s.t.

$$
\exists \Gamma^{h} \subset \Omega_{2} \quad \text { constructed of the sides of the triangles, }
$$

$$
\operatorname{dist}\left(\Gamma^{h}, \Gamma\right)=O\left(h^{2}\right) .
$$

Note that

$$
\|u-\tilde{v}\|_{1, \Omega} \leq C\|u-\tilde{u}\|_{1, \Omega} \Omega_{e x}^{h},
$$

where $\tilde{u}$ is a nodal interpolant of $u \in B^{2}(\Omega)$.
Denote by $\Omega_{1}^{h}$ the area bounded by the curve $\Gamma^{h}$. Approximation property:

$$
\|u-\tilde{u}\|_{1, \Omega_{e x}^{h} \backslash \Omega_{1}^{h}} \leq C h\|u\|_{2, \Omega_{2}} .
$$

## Variational schemes for problems with discontinuous coefficients

Denote by $u_{1}$ the continuation of $u$ from $\Omega_{1}$ to $\Omega_{2}$, s.t. $u_{1} \in H^{2}(\Omega)$. Note that

$$
\|u-\tilde{u}\|_{1, \Omega_{1}^{h}} \leq\left\|u-u_{1}\right\|_{1, \Omega_{1}^{h}}+\left\|u_{1}-\tilde{u}_{1}\right\|_{1, \Omega_{1}^{h}}+\left\|\tilde{u}_{1}-\tilde{u}\right\|_{1, \Omega_{1}^{h} .} .
$$

Evidently, $\left\|u-u_{1}\right\|_{1, \Omega_{1}^{h}}=\left\|u-u_{1}\right\|_{1, \Omega_{1}^{h} \backslash \Omega_{1}}$.
$\Omega_{1}^{h} \backslash \Omega_{1}$ is a strip of width $O\left(h^{2}\right)$. Then due to a corresp. theorem

$$
\begin{aligned}
& \left\|u-u_{1}\right\|_{1, \Omega_{1}^{h} \backslash \Omega_{\mathbf{1}}} \leq C h\left\|u-u_{1}\right\|_{2, \Omega_{2}} \\
& \leq C h\left(\|u\|_{2, \Omega_{\mathbf{2}}}+\left\|u_{1}\right\|_{2, \Omega_{\mathbf{2}}}\right) \leq C h\left(\|u\|_{2, \Omega_{\mathbf{2}}}+\|u\|_{2, \Omega_{\mathbf{1}}}\right)
\end{aligned}
$$

Estimating other two terms, we obtain

$$
\begin{aligned}
& \left\|u_{1}-\tilde{u}_{1}\right\|_{1, \Omega_{1}^{h}} \leq C h\|u\|_{2, \Omega_{1}} \\
& \left\|\tilde{u}_{1}-\tilde{u}\right\|_{1, \Omega_{1}^{h}} \leq C h\left(\|u\|_{2, \Omega_{1}}+\|u\|_{2, \Omega_{2}}\right)
\end{aligned}
$$

## Variational schemes for problems with discontinuous coefficients

Summarizing, one derives

$$
\|u-\tilde{u}\|_{1, \Omega_{e x}^{h}} \leq C h\left(\|u\|_{2, \Omega_{1}}+\|u\|_{2, \Omega_{2}}\right)
$$

hence

$$
\|u-\tilde{v}\|_{1, \Omega} \leq C h\left(\|u\|_{2, \Omega_{1}}+\|u\|_{2, \Omega_{2}}\right)
$$

## Variational schemes with additive selection of singular

 functionsAssume that domain $\Omega$ has two corner points on $S$ with angles $\beta_{j}>\pi$. Then solution can be written as

$$
u=\gamma_{1} \Psi_{1}+\gamma_{2} \Psi_{2}+w .
$$

Approximate solution for the regular mesh $\Omega_{e x}^{h}$ we will seek in the form

$$
v=\kappa_{1} \Psi_{1}+\kappa_{2} \Psi_{2}+\tilde{p},
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where $\tilde{p}$ is a piecewise linear function from $V_{h}$.

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$$

where $\tilde{p}$ is a piecewise linear function from $V_{h}$.
We seek $v$ as a solution of the integral identity

$$
L_{\Omega, S}(v, \phi)=(f, \phi)_{\Omega}
$$

for any $\phi=\mu_{1} \Psi_{1}+\mu_{2} \Psi_{2}+\tilde{\theta}, \tilde{\theta} \in V_{h}$.
In this case Galerkin system contains basis functions of $V_{h}$ and $\Psi_{1}, \Psi_{2}$.
The following estimate holds:

$$
\|u-v\|_{1, \Omega} \leq C \min _{\phi}\|u-\phi\|_{1, \Omega}
$$

## Variational schemes with additive selection of singular functions

Taking $\phi=\gamma_{1} \Psi_{1}+\gamma_{2} \Psi_{2}+\tilde{w}$, where $\tilde{w}$ is a nodal interpolant of $w$, we obtain

$$
\|u-v\|_{1, \Omega} \leq C\|w-\tilde{w}\|_{1, \Omega}
$$

Results of approximation theorem in 2D:

$$
\begin{aligned}
& \|w-\tilde{w}\|_{1, \Omega} \leq C h\|w\|_{2, \Omega} \\
& \|w-\tilde{w}\|_{0, \Omega} \leq C h^{2}\|w\|_{2, \Omega}
\end{aligned}
$$

together with the inequality $\sum_{j}\left|\gamma_{j}\right|+\|w\|_{2, \Omega} \leq C\|f\|_{0, \Omega}$ yield

$$
\begin{aligned}
\|u-v\|_{1, \Omega} & \leq \tilde{C} h\|f\|_{0, \Omega} \\
\|u-v\|_{0, \Omega} & \leq \tilde{C} h^{2}\|f\|_{0, \Omega}
\end{aligned}
$$

## Solution of Galerkin system with singular basis functions

Matrix $L$ of the system

$$
\begin{aligned}
& L_{\Omega, S}\left(v, \Psi_{1}\right)=\left(f, \Psi_{1}\right)_{\Omega}, \\
& L_{\Omega, S}\left(v, \Psi_{2}\right)=\left(f, \Psi_{2}\right)_{\Omega}, \\
& L_{\Omega, S}\left(v, \phi_{k_{i}}\right)=\left(f, \phi_{k_{i}}\right)_{\Omega} .
\end{aligned}
$$

is dense at 1st and 2 nd rows.

## Solution of Galerkin system with singular basis functions

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\end{aligned}
$$

is dense at 1st and 2nd rows.
We apply orthogonal factorization:

$$
v=\tilde{w}_{0}+k_{1} w_{1}+k_{2} w_{2},
$$

where $L_{\Omega, s}\left(w_{1}, \tilde{w}_{0}\right)=L_{\Omega, s}\left(w_{2}, \tilde{w}_{0}\right)=L_{\Omega, s}\left(w_{2}, w_{1}\right)=0$.

## Solution of Galerkin system with singular basis functions

Let $w_{1} \equiv \Psi_{1}-\tilde{q}_{1}$, where $\tilde{q}_{1} \in V_{h}$ solves the equation

$$
\begin{equation*}
L_{\Omega, S}\left(\Psi_{1}-\tilde{q}_{1}, \tilde{\theta}\right)=0 \tag{10}
\end{equation*}
$$

for any $\tilde{\theta} \in V_{h}$.

## Solution of Galerkin system with singular basis functions

Let $w_{1} \equiv \Psi_{1}-\tilde{q}_{1}$, where $\tilde{q}_{1} \in V_{h}$ solves the equation

$$
\begin{equation*}
L_{\Omega, s}\left(\Psi_{1}-\tilde{q}_{1}, \tilde{\theta}\right)=0 \tag{10}
\end{equation*}
$$

for any $\tilde{\theta} \in V_{h}$.
Then define $w_{2} \equiv \Psi_{2}+\mu w_{1}-\tilde{q}_{2}$, s.t.

$$
\begin{equation*}
L_{\Omega, S}\left(\tilde{q}_{2}, \tilde{\theta}\right)=L_{\Omega, S}\left(\Psi_{2}, \tilde{\theta}\right) \tag{11}
\end{equation*}
$$

for any $\tilde{\theta} \in V_{h}$, and

$$
\mu=-\frac{L_{\Omega, S}\left(\Psi_{2}-\tilde{q}_{2}, w_{1}\right)}{L_{\Omega, S}\left(w_{1}, w_{1}\right)}
$$

to satisfy $L_{\Omega, s}\left(w_{2}, w_{1}\right)=0$.

## Solution of Galerkin system with singular basis functions

3rd equation is to find $\tilde{w}_{0} \in V_{h}$ :

$$
\begin{equation*}
L_{\Omega, S}\left(\tilde{w}_{0}, \tilde{\theta}\right)=(f, \tilde{\theta})_{\Omega} \tag{12}
\end{equation*}
$$

for any $\tilde{\theta} \in V_{h}$.
Coefficients $k_{1}, k_{2}$ can be found from the expressions

$$
\begin{gathered}
k_{1}=\frac{\left(f, w_{1}\right)_{\Omega}-L_{\Omega, S}\left(\tilde{w}_{0}, w_{1}\right)}{L_{\Omega, S}\left(w_{1}, w_{1}\right)}, \\
k_{2}=\frac{\left(f, w_{2}\right)_{\Omega}-L_{\Omega, S}\left(\tilde{w}_{0}, w_{2}\right)-k_{1} L_{\Omega, S}\left(w_{1}, w_{2}\right)}{L_{\Omega, S}\left(w_{2}, w_{2}\right)} .
\end{gathered}
$$

## Solution of Galerkin system with singular basis functions

Assembling matrices for (10), (11), (12) requires the computation of $L_{\Omega, S}(\Psi, \Psi), L_{\Omega, S}\left(\Psi, \phi_{k_{i}}\right),(f, \Psi)_{\Omega}$.
On the mesh triangles in the neighborhood of the corner points one has to evaluate the integrals of the form

$$
\int_{\triangle} \alpha\left(\frac{\partial \Psi}{\partial x_{1}}\right)^{i_{1}}\left(\frac{\partial \Psi}{\partial x_{2}}\right)^{i_{2}} d \Omega
$$

where $\alpha$ is a linear function, $1 \leq i_{1}+i_{2} \leq 2$.
Since in the polar coordinates $\psi=\zeta(r) r^{\lambda} \cos \lambda \theta$, this double integrals reduce to multiple integrals of the terms as

$$
r^{\nu} \cos ^{m_{1}} \lambda \theta \sin ^{m_{2}} \lambda \theta \cos ^{n_{1}} \theta \sin ^{n_{2}} \theta
$$

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Appendix

## Appendix

Now we prove that

$$
\min _{\vec{a} \in \mathbb{R}^{2}}\|\nabla \Psi-\vec{a}\|_{0, \triangle} \geq C h^{\lambda}
$$

where $\Psi=\zeta(r / \varepsilon) r^{\lambda} \sin \lambda \theta, 0<\lambda<1$.
Note that for sufficiently small $h>0$ we have $\Psi=r^{\lambda} \sin \lambda \theta$.
Differentiating the function $\|\nabla \Psi-\vec{a}\|_{0, \triangle}^{2}$ w.r.t. $\vec{a}$, one obtains the minimum for

$$
\vec{a}_{*}=\frac{1}{\int_{\triangle} 1 d x}\left(\int_{\triangle} \frac{\partial \Psi}{\partial x_{1}} d x, \int_{\triangle} \frac{\partial \Psi}{\partial x_{2}} d x\right)
$$

Further we use the relations

$$
\begin{aligned}
& \frac{\partial \Psi}{\partial x_{1}}=\cos \theta \frac{\partial \Psi}{\partial r}-\frac{1}{r} \sin \theta \frac{\partial \Psi}{\partial \theta} \\
& \frac{\partial \Psi}{\partial x_{2}}=\sin \theta \frac{\partial \Psi}{\partial r}+\frac{1}{r} \cos \theta \frac{\partial \Psi}{\partial \theta}
\end{aligned}
$$

## Appendix

For convenience we will also consider circle sectors $\sigma \subset \triangle \subset \bar{\sigma}$. Then

$$
\int_{\bar{\sigma}} F(x) d x \geq \int_{\triangle} F(x) d x \geq \int_{\sigma} F(x) d x
$$

for any $F(x) \geq 0$ and, switching to polar coordinates, we have
$\int_{\sigma} F(x) d x=\int_{0}^{c h} d r \int_{\theta_{1}}^{\theta_{2}} d \theta r F(r, \theta), \int_{\bar{\sigma}} F(x) d x=\int_{0}^{\bar{c} h} d r \int_{\theta_{1}}^{\theta_{2}} d \theta r F(r, \theta)$.
for some $0<c<\bar{c}$.

## Appendix

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$\int_{\sigma} F(x) d x=\int_{0}^{c h} d r \int_{\theta_{1}}^{\theta_{2}} d \theta r F(r, \theta), \int_{\bar{\sigma}} F(x) d x=\int_{0}^{\overline{c h}} d r \int_{\theta_{1}}^{\theta_{2}} d \theta r F(r, \theta)$.
for some $0<c<\bar{c}$.
Expressions for $\frac{\partial \psi}{\partial x_{1}}, \frac{\partial \Psi}{\partial x_{2}}$ allow us to estimate

$$
\left|\int_{\Delta} \frac{\partial \Psi}{\partial x_{1}} d x\right| \leq \int_{\bar{\sigma}}\left|\frac{\partial \Psi}{\partial x_{1}}\right| d x \leq C_{\bar{\sigma}}^{0} \int_{0}^{c h} r^{\lambda} d r \leq C_{\bar{\sigma}} h^{\lambda+1}
$$

as well as for $\frac{\partial \psi}{\partial x_{2}}$.

## Appendix

Taking into account that $\int_{\triangle} 1 d x=O\left(h^{2}\right)$, last inequality means:
$\left|\vec{a}_{*}\right|=O\left(h^{\lambda-1}\right)$.
Expressions for $\frac{\partial \Psi}{\partial x_{1}}, \frac{\partial \Psi}{\partial x_{2}}$, which can be expressed as $G_{i}(\theta) r^{\lambda-1}, i=1,2$ with certain trigonometric functions $G_{i}(\theta)$, also yield that on a fixed circle sector $\sigma_{1} \subset \sigma$ (with polar angles $\theta \in\left(\theta_{1}, \theta_{2}\right)$ away from the roots of $G_{i}(\theta)$ and radius $\underline{c} h$ for some $0<\underline{c}<c$ ) the estimates

$$
\left|\frac{\partial \Psi}{\partial x_{1}}\right| \geq c_{0} r^{\lambda-1},\left|\frac{\partial \Psi}{\partial x_{2}}\right| \geq c_{0} r^{\lambda-1}
$$

hold.
Then due to the estimate for $\left|\vec{a}_{*}\right|$ one can choose such a circle sector $\sigma_{2} \subset \sigma_{1}$ (with radius $\alpha h$ for some $\alpha>0$ ) that for a given $c_{1}<c_{0}$ :

$$
\left|\nabla \Psi-\vec{a}_{*}\right|_{2} \geq c_{1} r^{\lambda-1}
$$

## Appendix

Finally, we obtain

$$
\begin{aligned}
& \left\|\nabla \Psi-\vec{a}_{*}\right\|_{0, \triangle}^{2} \geq\left\|\nabla \Psi-\vec{a}_{*}\right\|_{0, \sigma_{2}}^{2} \\
& =\int_{0}^{\alpha h} d r \int_{\theta_{\mathbf{1}}}^{\theta_{\mathbf{2}}} d \theta r\left|\nabla \Psi-\vec{a}_{*}\right|_{2}^{2} \\
& \geq \int_{0}^{\alpha h} d r \int_{\theta_{\mathbf{1}}}^{\theta_{2}} d \theta r c_{1}^{2} r^{2 \lambda-2} \geq c_{3} \int_{0}^{\alpha h} r^{2 \lambda-1} d r=C^{2} h^{2 \lambda}
\end{aligned}
$$

which proves the required lower estimate for $\left\|\nabla \Psi-\vec{a}_{*}\right\|_{0, \Delta}$.

