

58 Prove formula (19) from the lecture, i.e. show that

$$\|\psi_{j+1}(u)\| \leq \int_{t_j}^{t_{j+1}} \|u''(t)\| dt$$

holds for $j = 0, \dots, m-1$ and for $u \in C^2([0, T], \mathbb{R}^n)$.

59 Assume that f fulfills the Lipschitz condition (13), i.e.

$$\|f(t, v) - f(t, w)\| \leq L \|v - w\| \quad \forall t \in [0, T] \quad \forall v, w \in \mathbb{R}^n.$$

Furthermore, let the sequences (u_j) and (v_j) be given according to the (perturbed) explicit Euler method:

$$\left. \begin{aligned} u_{j+1} &= u_j + \tau_j f(t_j, u_j) \\ v_{j+1} &= v_j + \tau_j [f(t_j, v_j) + y_{j+1}] \end{aligned} \right\} \quad \forall j = 0, \dots, m-1,$$

and $v_0 = u_0 + y_0$ for given (but arbitrary) values u_0 and $y_0, \dots, y_m \in \mathbb{R}^n$. Show that then,

$$\|u_j - v_j\| \leq e^{(t_j - t_0)L} \|y_0\| + \frac{1}{L} \left(e^{(t_j - t_0)L} - 1 \right) \max_{k=1, \dots, j} \|y_k\|$$

for all $\tau > 0$.

Hint: Show and use $e^{(t_j - t_k)L} \tau_{k-1} \leq \int_{t_{k-1}}^{t_k} e^{(t_j - s)L} ds$.

60 Recall that the definitions of consistency, stability, and convergence depend on the norms $\|\cdot\|_{X_\tau}$ and $\|\cdot\|_{Y_\tau}$. In this exercise, we replace $\|\cdot\|_{Y_\tau}$ by $\|\cdot\|_{X_\tau}$.

Use Exercise **59** to show an estimate of the form

$$\|e_\tau\|_{X_\tau} \leq C \|\psi_\tau(u)\|_{X_\tau}$$

for the explicit Euler method with a stability constant C independent of τ .

Furthermore, show that for exact solutions $u \in C^2([0, T], \mathbb{R}^n)$,

$$\|\psi_\tau(u)\|_{X_\tau} \leq K \tau$$

with $K = \max_{s \in [0, T]} \|u''(s)\|$.

61 Consider the general explicit 2-stage Runge-Kutta method

$$\begin{aligned} g_1 &= u_j \\ g_2 &= u_j + \tau_j a_{2,1} f(t_j, g_1) \\ u_{j+1} &= u_j + \tau_j [b_1 f(t_j, g_1) + b_2 f(t_j + c_2 \tau_j, g_2)] \end{aligned}$$

with coefficients $a_{2,1}$, b_1 , b_2 and c_2 for the approximate solution of the initial value problem to find $u : [0, T] \rightarrow \mathbb{R}$ such that

$$\begin{aligned} u'(t) &= f(t, u(t)) \quad \forall t \in (0, T), \\ u(t) &= u_0, \end{aligned}$$

where $u_0 \in \mathbb{R}$ is given and $f : [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ is sufficiently smooth.

A Taylor series expansion of the *local error* of the form

$$d_\tau(t + \tau) = A_0 + A_1 \tau + A_2 \tau^2 + A_3 \tau^3 + \mathcal{O}(\tau^4),$$

with the expressions A_0, \dots, A_3 depending only on $a_{2,1}$, b_1 , b_2 , c_2 , f , and its derivatives, but not on τ , is provided in the KUSSS-system.

Find necessary conditions on the coefficients $a_{2,1}$, b_1 , b_2 , and c_2 such that the consistency order of the method is at least 2, i.e. such that for all sufficiently smooth functions f ,

$$A_0 = A_1 = A_2 = 0.$$

Is it possible to get consistency order 3?

62 Consider the classical Runge-Kutta method of order 4,

0				
1/2	1/2			
1/2	0	1/2		
1	0	0	1	
	1/6	1/3	1/3	1/6

Show that this method has the stability function

$$R(z) = 1 + z + \frac{1}{2} z^2 + \frac{1}{6} z^3 + \frac{1}{24} z^4.$$

63 Apply the Explicit Euler method with a given stepsize τ to the following differential equation:

$$u'(t) = -50 u(t) \quad u(0) = 1$$

You may use a programming language of your choice (like Mathematica or Matlab). Plot the solutions for $\tau = \frac{1}{60}, \frac{1}{30}, \frac{1}{26}, \frac{1}{24}$ on $[0, T] = [0, 1]$. How do the results relate to observations in the lecture?

Remark: You will not need to reuse or expand your code in future tutorials. Just make sure you get the results and think about them!