

In the lecture, the coercivity of the bilinear form

$$a(w, v) = \int_0^1 [a(x) w'(x) v'(x) + b(x) w'(x) v(x) + c(x) w(x) v(x)] dx, \quad (3.1)$$

on the space $V_0 = \{v \in H^1(0, 1) : v(0) = 0\}$ has been shown for the special case $a \equiv 1$, $b \equiv 0$, $c \equiv 0$. In the following three exercises, we consider more general situations. In all situations, you will need the estimate

$$a(v, v) \geq a_0 |v|_{H^1(0,1)}^2 + \int_0^1 b(x) v'(x) v(x) dx + c_0 \|v\|_{L_2(0,1)}^2, \quad (3.2)$$

where $a_0 := \inf_{x \in (0,1)} a(x)$ and $c_0 := \inf_{x \in (0,1)} c(x)$.

- 10** Show the coercivity of $a(\cdot, \cdot)$ on $V_0 = \{v \in H^1(0, 1) : v(0) = 0\}$ under the assumptions

$$a_0 > 0, \quad C_F \|b\|_{L_\infty(0,1)} < a_0, \quad c_0 \geq 0,$$

where C_F is the constant in Friedrichs' inequality.

Hint: Use Cauchy's inequality to show the estimate

$$\int_0^1 b(x) v'(x) v(x) dx \geq -\|b\|_{L_\infty(0,1)} |v|_{H^1(0,1)} \|v\|_{L_2(0,1)}$$

and use it in (3.2).

- 11** Show the coercivity of $a(\cdot, \cdot)$ on the whole space $H^1(0, 1)$ under the assumptions

$$a_0 > 0, \quad \|b\|_{L_\infty(0,1)} < 2\sqrt{a_0 c_0}, \quad c_0 > 0.$$

Hint: Show that

$$a(v, v) \geq q(|v|_{H^1(0,1)}, \|v\|_{L_2(0,1)}),$$

with

$$q(\xi, \eta) := a_0 \xi^2 - \|b\|_{L_\infty(0,1)} \xi \eta + c_0 \eta^2.$$

Finally, show and use that

$$q(\xi, \eta) \geq a_0 C \xi^2, \quad \text{and} \quad q(\xi, \eta) \geq c_0 C \eta^2,$$

with $C = 1 - \frac{\|b\|_{L_\infty(0,1)}^2}{4 a_0 c_0}$.

- 12** Show the coercivity of $a(w, v)$ on the space $V_0 = \{v \in H^1(0, 1) : v(0) = 0\}$ under the assumptions

$$a_0 > 0, \quad b(x) = b_0 \geq 0, \quad c_0 \geq 0,$$

where b_0 is a constant.

Hint: Show and use that

$$\int_0^1 v'(x) v(x) dx = \frac{1}{2} v(x)^2 \Big|_0^1 \geq 0 \quad \forall v \in V_0.$$

- 13 Prove Lemma 1.29 from the lecture: Let V be a Hilbert space, $a(\cdot, \cdot) : V \times V \rightarrow \mathbb{R}$ a bilinear form that is symmetric and non-negative on V . Let $V_0 \subset V$ and $V_g = g + V_0$ with $g \in V$. Then

$$\text{find } u \in V_g : \quad a(u, v) = \langle F, v \rangle \quad \forall v \in V_0$$

is equivalent to

$$\text{find } u \in V_g : \quad J_a(u) = \inf_{v \in V_g} J_a(v),$$

with $J_a(v) = \frac{1}{2}a(v, v) - \langle F, v \rangle$.

Hint: Follow the proof of Lemma 1.24.

- 14 Consider our 1D model problem from the lecture with $g_0 = 0$, i.e.

$$\text{Find } u \in V_0 : \quad \underbrace{\int_0^1 u' v' dx}_{=:\langle Au, v \rangle} = \underbrace{\int_0^1 f v dx + g_1 v(1)}_{=:\langle F, v \rangle} \quad \forall v \in V_0,$$

where $V_0 = \{v \in H^1(0, 1) : v(0) = 0\}$.

Specify precisely the boundary value problem for $w_k \in V_0$ which corresponds to

$$w_k = \mathcal{R}(F - A u_k),$$

where $\mathcal{R} : V_0^* \rightarrow V_0$ is the Riesz isomorphism.

Hint: Follow the steps at the end of Section 1.1 in the lecture notes (“integration by parts backwards”)

- 15 Consider the system of linear equations,

$$\underbrace{\begin{pmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}}_{=:A} \underbrace{\begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}}_{=:u} = \underbrace{\begin{pmatrix} ? \\ f_2 \\ f_3 \end{pmatrix}}_{=:f}.$$

with the side-condition $u_1 = 3$. There are two approaches to the solution:

- (1) *Direct approach:*

Substitute u_1 by the given value in the 2nd and 3rd equation, and reduce the system to a 2-by-2 system for u_2 and u_3 .

- (2) *Variational approach:*

Find $\underline{u} \in \mathbb{R}^3, u_1 = 3$ such that

$$\underbrace{\underline{v}^T A \underline{u}}_{=:a(\underline{u}, \underline{v})} = \underbrace{\underline{v}^T \underline{f}}_{=:f(\underline{v})} \quad \forall \underline{v} \in \mathbb{R}^3, v_1 = 0.$$

Is (2) a variational formulation? Show (1) \Leftrightarrow (2).

Then, consider the following questions:

- Can the condition $v_1 = 0$ be dropped?
- Can more conditions on \underline{v} be introduced?