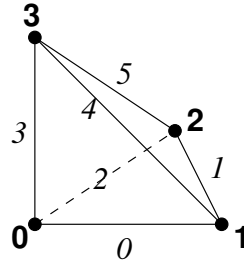


**Programming in C++:**

Let the vertices and edges of the reference tet be numbered according to the figure below.



**25** Write a function

```
void calcCurlCurlElMat (const ElTrans& elTrans,
                        const NedelecTet& fe, Mat<6, 6>& elMat);
```

that computes the element stiffness matrix `elMat` =  $K$  associated to a tet  $T$ , i.e.

$$\begin{aligned} K_{kl} &= \int_T \mathbf{curl} \varphi_k(x) \cdot \mathbf{curl} \varphi_l(x) dx \\ &= \int_{\hat{T}} (J_T^{-1} F_T \mathbf{curl} \hat{\varphi}_k(\xi)) \cdot (J_T^{-1} F_T \mathbf{curl} \hat{\varphi}_l(\xi)) J_T d\xi. \end{aligned}$$

**26** Write a function

```
void calcMassElMat (const ElTrans& elTrans,
                    const NedelecTet& fe, Mat<6, 6>& elMat);
```

that computes the element mass matrix `elMat` =  $M$  associated to a tet  $T$ , i.e.

$$M_{kl} = \int_T \varphi_k(x) \cdot \varphi_l(x) dx.$$

*Hint:* Transform to the reference element as done in the previous exercise.

**27** Show Theorem 3.25 from the lecture (2D): Show that for all  $\mathbf{v} \in H(\mathbf{curl}, \Omega) \cap \mathbf{C}(\Omega)$ :

$$\mathbf{curl} I_\varepsilon^h \mathbf{v} = I_\tau^h \mathbf{curl} \mathbf{v},$$

where  $I_\varepsilon^h : H(\mathbf{curl}, \Omega) \cap \mathbf{C}(\Omega) \rightarrow V^h(\Omega)$  and  $I_\tau^h : L^2(\Omega) \rightarrow S^h(\Omega)$  are the edge and the element interpolator, respectively.

*Hint:* Use Stokes' theorem.