# TUTORIAL

## "Computational Mechanics"

### to the lecture

## "Numerical Methods in Continuum Mechanics 1"

**Tutorial 09** Friday, May 28, 2010 (Time :  $10^{15} - 11^{00}$ , Room : HS 14)

#### 4.3 Solvers for Mixed Finite Element Equations

32 Let  $A \in \mathbb{R}^{n \times n}$ ,  $B \in \mathbb{R}^{m \times n}$ , and  $C \in \mathbb{R}^{m \times m}$  such, that  $A = A^T$ , A > 0,  $C = C^T$ ,  $C \ge 0$ , and Rank  $B = \min\{m, n\}$ . Show that

- 1. the matrix  $\begin{pmatrix} A & B^T \\ B & -C \end{pmatrix}$  is symmetric but indefinite, and 2. if C > 0, then the matrix  $\begin{pmatrix} A & B^T \\ -B & C \end{pmatrix}$  is positive definite !
- 33 Let  $A \in \mathbb{R}^{n \times n}$ ,  $B \in \mathbb{R}^{m \times n}$ , and  $C \in \mathbb{R}^{m \times m}$  such, that  $A = A^T$ , A > 0,  $C = C^T$ ,  $C \ge 0$ , and Rank  $B = \min\{m, n\}$ . Show that the dual Schur complement matrix  $S = BA^{-1}B^T + C$  is symmetric and positive definite (SPD) !
- $34^*$  Show that the best (largest) discrete LBB-constant is given by the relation

$$\tilde{\beta}_1^2 = \lambda_{\min}(G_{\Lambda}^{-1}(BG_X^{-1}B^T)), \qquad (4.60)$$

i.e.  $\tilde{\beta}_1^2 = \lambda_{min}(G_{\Lambda}^{-1}(BG_X^{-1}B^T))$  is the minimal eigenvalue of the generalized EVP

$$BG_X^{-1}B^T\underline{\mu} = \lambda G_{\Lambda}\underline{\mu},\tag{4.61}$$

where the Gram matrices  $G_X$  and  $G_{\Lambda}$  are defined by the identities

$$(G_X \underline{u}_h, \underline{v}_h)_{\mathbf{R}^{n_h}} = (u_h, v_h)_X \quad \forall \underline{u}_h, \underline{v}_h \leftrightarrow u_h, v_h \in X_h \quad \text{and}$$

 $(G_{\Lambda}\underline{\lambda}_{h},\underline{\mu}_{h})_{\mathbf{R}^{m_{h}}} = (\lambda_{h},\mu_{h})_{\Lambda} \quad \forall \underline{\lambda}_{h},\underline{\mu}_{h} \leftrightarrow \lambda_{h},\mu_{h} \in \Lambda_{h}, \quad \text{respectively.}$ 

*Hint:* Use the Rayleigh-quotient representation of the minimal eigenvalue of the generalized EVP (4.61) !

35 Write down the Uzawa–CG–Method, i.e., the CG–Method for the Schur-Complement-System

Given 
$$\underline{f} \in \mathbf{R}^n$$
 and  $\underline{g} \in \mathbf{R}^m$ . Find  $\underline{\lambda} \in \mathbf{R}^m$ :  $(BA^{-1}B^T + C) \underline{\lambda} = BA^{-1}\underline{f} - \underline{g}$   
in an algorithmic form !