

- [35] Let  $A \in \mathbb{R}^{n \times n}$  be a symmetric matrix. Show that for  $M_\tau = I - \tau A$  with  $\tau \in \mathbb{R}$ :

$$\|M_\tau\|_{\ell_2} = \max_{\lambda \in \sigma(A)} |1 - \tau \lambda| = q(\tau),$$

where  $q(\tau) = \max(|1 - \tau \lambda_{\max}(A)|, |1 - \tau \lambda_{\min}(A)|)$ .

- [36] Let  $A \in \mathbb{R}^{n \times n}$  be a symmetric matrix with at least one negative and one positive eigenvalue ( $A$  is indefinite). Show that

$$\max_{\lambda \in \sigma(A)} |1 - \tau \lambda| > 1 \quad \forall \tau \neq 0.$$

- [37] Let  $A \in \mathbb{R}^{n \times n}$  be a symmetric matrix and let  $\lambda_- < 0$  and  $\lambda_+ > 0$  be two eigenvalues with the corresponding eigenvectors  $e_-$  and  $e_+$ , respectively. Show that there is *no choice* for the parameter  $\tau \in \mathbb{R}$  such that the following Richardson's method (with special initial value) converges.

$$\begin{aligned} x_0 &= x + e_- + e_+ \\ x_{k+1} &= x_k + \tau(b - Ax_k) \quad \text{for } k = 0, 1, \dots \end{aligned}$$

Here  $x = A^{-1}b$  is the exact solution.

- [38] In the lecture, we showed for the CG method that

$$x_k \in x_0 + \mathcal{K}_k(A, r_0) \quad \text{and} \quad r_k \perp \mathcal{K}_k(A, r_0),$$

where  $\perp$  means orthogonality in the corresponding inner product.

We consider now the GMRES method, which can also be applied to indefinite matrices. There, the iterates are constructed such that

$$x_k \in x_0 + \mathcal{K}_k(A, r_0) \quad \text{and} \quad \|b - Ax_k\|_{\ell_2} = \min_{y \in x_0 + \mathcal{K}_k(A, r_0)} \|b - Ay\|_{\ell_2}.$$

Show that in this case

$$r_k \perp A\mathcal{K}_k(A, r_0),$$

where  $\perp$  means  $\ell_2$ -orthogonality.

*Hint:* Rewrite the above minimization problem as an equivalent variational problem.

### Programming:

- [39] Write a function `CG(↓A, ↑x, ↓b, ↓C, ↑max_iter, ↑tol)` to solve the linear system

$$A\bar{x} = \bar{b}$$

with the preconditioned CG method. The parameter specification is the same as in Exercise [33] (Richardson's method).

*Hint:* Use `cg.hh` (download or see next page) and rewrite it for your own purposes.

- [40] Solve the problem given in Exercise [28\*] (see Tutorial 5) with the Jacobi-preconditioned CG method. Try different equidistant meshes ( $h = 1/10$ ,  $h = 1/20$ ,  $h = 1/100$ , etc.) and report the number of iterations to reach the relative accuracy  $\varepsilon = 10^{-6}$ .

*File* cg.hh

```
#ifndef __CG_H
#define __CG_H

// Iterative template routine -- CG
//
// RICHARDSON solves the symmetric positive definite linear
// system Ax=b using the preconditioned conjugate gradient methd.
// The returned value indicates convergence within
// max_iter iterations (return value 0)
// or no convergence within max_iter iterations (return value 1)
// Upon successful return (0), the output arguments have the
// following values:
//      x: computed solution
// mat_iter: number of iterations to satisfy the stopping criterion
//      tol: residual after the final iteration

template <class MATRIX, class VECTOR, class PRECONDITIONER, class REAL>
int
CG (const MATRIX & A, VECTOR & x, const VECTOR & b,
    const PRECONDITIONER & M, int & max_iter, REAL & tol)
{
    REAL resid;
    VECTOR p(b.size ());
    VECTOR z(b.size ());
    VECTOR q(b.size ());
    REAL alpha, beta, rho, rho_1;
    REAL normb = norm (b);
    VECTOR r = b - A * x;

    if (normb == 0.0) normb = 1;
    resid = norm (r) / normb;

    if (resid <= tol)
    {
        tol = resid;
        max_iter = 0;
        return 0;
    }

    for (int i=1; i<=max_iter; i++)
    {
        z = M.solve (r);
        rho = inner_product (r, z);

        if (i==1)
        {
            p = z;
        }
        else
        {
            beta = rho / rho_1;
            p = z + beta * p;
        }
    }
}
```

```

    }

    q = A * p;
    alpha = rho / inner_product (p, q);

    x += alpha * p;
    r -= alpha * q;

    resid = norm(r) / normb;

    if (resid <= tol)
    {
        tol = resid;
        max_iter = i;
        return 0;
    }

    rho_1 = rho;
}

tol = resid;
return 1;
}

```