

- [22] Let \mathcal{T}_h be an equidistant subdivision of $(0, 1)$. Show (analogously to the L^2 -estimate the lecture) that there exists a constant $C_1 > 0$ independent of h , such that

$$|v - I_h v|_{H^1(0,1)} \leq C_1 h \|v''\|_{L^2(0,1)} \quad \forall v \in C^2[0, 1]. \quad (5.1)$$

- [23] Show that all expressions in (5.1) are continuous with respect to the H^2 -norm.
Hint: Show that the expressions are Lipschitz-continuous.
Then (5.1) follows for all $v \in H^2(0, 1)$ due to the density of $C^2[0, 1]$ in that space (closure principle).

- [24] Let \mathcal{T}_h be an equidistant subdivision of $(0, 1)$, let V_{0h} be the space of continuous piecewise affine linear functions that vanish at 0, and let K_h denote the stiffness matrix corresponding to our model problem. Show that there exists a constant $C_2 > 0$ independent of h such that

$$\kappa(K_h) \geq C_2 h^{-2}.$$

Hint: Use the Rayleigh quotient for the special vector $\underline{v}_h = (1, 0, \dots, 0)^\top$ in order to obtain a lower bound for $\lambda_{\max}(K_h)$. For an upper bound of $\lambda_{\min}(K_h)$ use $\underline{v}_h = (h, 2h, 3h, \dots, 1)^\top$.

- [25] Let \mathcal{T}_h be an equidistant subdivision of $(0, 1)$ and let V_{0h} be the space of continuous piecewise affine linear functions vanishing at 0. Let M_h denote the mass matrix for our model problem. Show that there exists a constant $C_3 > 0$ independent of h such that

$$\kappa(M_h) \leq C_3.$$

Programming

- [26] Write a function `ImplementDirichletBC(↓i, ↓g, ↑matrix, ↑vector)` to implement the Dirichlet boundary condition

$$u(x_i) = g_D(x_i)$$

for a given value $\mathbf{g} = g_D(x_i)$ at the boundary node x_i identified by the index $\mathbf{i} = i$. The function `ImplementDirichletBC` must update the stiffness matrix `matrix` and the load vector `vector`, after applying

```
AssembleStiffnessMatrix
AssembleLoadVector
ImplementRobinBC
```

Here, instead of *deleting* rows or columns from the matrix, we stay with the $(n_h + 1) \times (n_h + 1)$ matrix using the following technique. Suppose that applying `AssembleStiffnessMatrix`, `AssembleLoadVector` and `ImplementRobinBC` yields the linear system

$$\begin{pmatrix} K_{00} & K_{01} & K_{02} & K_{03} \\ K_{10} & K_{11} & K_{12} & K_{13} \\ K_{20} & K_{21} & K_{22} & K_{23} \\ K_{30} & K_{31} & K_{32} & K_{33} \end{pmatrix} \begin{pmatrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \end{pmatrix}$$

and that we want to impose the Dirichlet boundary condition $u_0 = u(x_0) = g_D(x_0) = g_0$. Then, we can replace the first equation by $K_{00} u_0 = K_{00} g_0$ and substitute u_0 by g_0 in the remaining equations. The modified system reads

$$\begin{pmatrix} K_{00} & 0 & 0 & 0 \\ 0 & K_{11} & K_{12} & K_{13} \\ 0 & K_{21} & K_{22} & K_{23} \\ 0 & K_{31} & K_{32} & K_{33} \end{pmatrix} \begin{pmatrix} u_0 \\ u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} K_{00} g_0 \\ f_1 - K_{10} g_0 \\ f_2 - K_{20} g_0 \\ f_3 - K_{30} g_0 \end{pmatrix}.$$

Implement this in an efficient way.

- 27** Implement an efficient Gauss/Thomas type solver for our system $K_h u_h = \underline{f}_h$.
Hint 1: Exploit the tridiagonal structure (and maybe also the symmetry).

Hint 2: If you are lazy, take your inspiration from

http://en.wikipedia.org/wiki/Tridiagonal_matrix_algorithm

- 28*** (BONUS exercise)

Solve the model problem

$$\begin{aligned} -u''(x) &= f(x) & \forall x \in (0, 1), \\ u(0) &= g_D \\ u'(1) &= \alpha (g_R - u(1)), \end{aligned}$$

with $f(x) = 8$, $g_D = -1$, $\alpha = 1$, $g_R = 1$ for different (equidistant) meshes ($h = 1/10$, $h = 1/20$, $h = 1/100$ etc.) and visualize the solution (e. g., using **gnuplot**, **matlab**, etc.).