

■ Result: Primal Variational Formulation
 = principle of virtual displacement (work)

(2)

Find $u \in V_0 = \{v \in V = [H^1(\Omega)]^3 : v = 0 \text{ on } \Gamma_u\}$:

$$a(u, v) = \langle F, v \rangle \quad \forall v \in V_0,$$

where

$$\langle F, v \rangle := \int_{\Omega} f_i v_i dx + \int_{\Gamma_t} t_i v_i ds = \int_{\Omega} f^T v dx + \int_{\Gamma_t} t^T v ds$$

$$a(u, v) := \int_{\Omega} \sigma_{ij}(u) \epsilon_{ij}(v) dx = \int_{\Omega} \sigma(u) \cdot \epsilon(v) dx$$

HOOK

$$= \int_{\Omega} D_{ijkl} \epsilon_{kl}(u) \epsilon_{ij}(v) dx = \int_{\Omega} \epsilon^T(u) D \epsilon(v) dx$$

matrix of
elastic constants

$$\begin{aligned} & \text{isotropic} \\ & (\text{mmS}) = \int_{\Omega} \left\{ \lambda \underbrace{\sum_{k=1}^3 \epsilon_{kk}(u)}_{\text{div } u} \underbrace{\sum_{i=1}^3 \epsilon_{ii}(v)}_{\text{div } v} + 2\mu \sum_{i,j=1}^3 \epsilon_{ij}(u) \epsilon_{ij}(v) \right\} dx \end{aligned}$$

$$= \int_{\Omega} \{ \lambda \text{div } u \cdot \text{div } v + 2\mu \epsilon^T(u) \epsilon(v) \} dx$$

with given

- $f = (f_1, f_2, f_3)^T \in [L_2(\Omega)]^3$, $t = (t_1, t_2, t_3)^T \in [L_2(\Gamma_t)]^3$,
- $D_{ijkl} \in L_\infty(\Omega)$: $0 < \lambda_{\min}(D) \leq \lambda(D(x)) \leq \lambda_{\max}(D)$ a.e. in Ω , resp. $\lambda, \mu \in L_\infty(\Omega)$: $0 < \lambda \leq \lambda(x) \leq \bar{\lambda}$, $0 < \mu \leq \mu(x) \leq \bar{\mu}$

■ PVF \equiv Minimization Problem ($a(\cdot, \cdot)$ sym. and $a(v, v) \geq 0$)

(3)

Find $u \in V_0$: $J(u) = \inf_{v \in V_0} J(v)$,

with

$$J(v) = \frac{1}{2} \underbrace{\int_{\Omega} \sigma_{ij}(v) \epsilon_{ij}(v) dx}_{\text{deformation energy}} - \underbrace{\left(\int_{\Omega} f_i v_i dx + \int_{\Gamma_t} t_i v_i ds \right)}_{\text{potential energy of ext. forces}}$$