

DG - Notations:



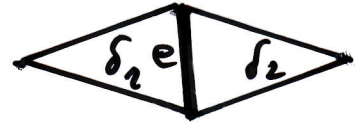
Let  $\mathcal{T}_h = \{\delta_r : r \in \mathbb{R}_h\}$  be a regular triangulation of  $\Omega$ .  
 For  $s > 0$ , we define the broken Sobolev spaces:

$$H^s(\mathcal{T}_h) := \{v \in L_2(\Omega) : v|_\delta \in H^s(\delta) \ \forall \delta \in \mathcal{T}_h\}, \text{ with}$$

$$\|v\|_{H^s(\mathcal{T}_h)}^2 = \sum_{\delta \in \mathcal{T}_h} \|v\|_{H^s(\delta)}^2, \quad (v, u)_{H^s(\mathcal{T}_h)} = \sum_{\delta \in \mathcal{T}_h} (v, u)_{H^s(\delta)}$$

Furthermore, we define

- the jumps (differences):



$$[v]_e := v_1 n_1 + v_2 n_2 = \underbrace{(v_1 - v_2)}_{=: [v]_e} n_e - \text{vector, } e \in E_h$$

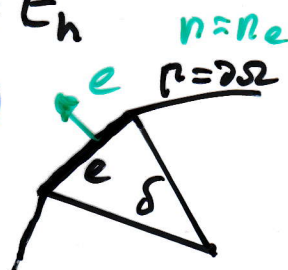
inner edge

- the mean values (averages):

$$\{\nabla v\}_e := \frac{1}{2} (\nabla v_1 + \nabla v_2) - \text{vector, } e \in E_h$$

- $e \in \partial E_h = \bar{E}_h \setminus E_h$  ( $e \in \partial \delta \cap \partial \Omega$ )

$$[v] := v \cdot n, \quad \{\nabla v\}_e := \nabla v$$



DG - Formulation of (1):

- Let  $u \in \tilde{V}_g \subset V = H^1(\Omega)$  be the solution of (1)<sub>VF</sub>, and let  $u, v \in H^s(\mathcal{T}_h)$ ,  $s > 3/2$ , then

$$(2) \quad (f, v)_{0, \Omega} = \sum_{\delta \in \mathcal{T}_h} (f, v)_{\delta} \stackrel{\downarrow f = -\text{div } \nabla u \in L_2(\delta)}{=} \sum_{\delta} (-\text{div } \nabla u, v)_{\delta}$$

$\nabla u \in H(\text{div})!$

$$= \sum_{\delta} [(\nabla u, \nabla v)_{\delta} - (\bar{\nabla} u \cdot n, v)_{\partial \delta}]$$

$L_2(\partial \delta)$  since  $u \in H^s(\mathcal{T}_h)$ ,  $s > 3/2$

$$= \sum_{\delta \in \mathcal{T}_h} (\nabla u, \nabla v)_{\delta} - \sum_{\delta \in \mathcal{T}_h} (\{ \nabla u \}, v \cdot n)_{\partial \delta}$$

$$\int_e (\nabla u_1 n_1 + \nabla u_2 n_2) v ds = 0$$

$n_1 = n_e = n$   
 $n_2 = -n_1$

$\nabla u_1 n_1 = \nabla u_2 n_2$   
 for  $u: (1)_{VF}$

$e \in \partial \delta \cap \Gamma: (\{ \nabla u \}, v \cdot n)_e = (\nabla u \cdot n, v)_e$

$e \in E_h: \{ \nabla u \} \cdot n = \frac{1}{2} (\nabla u_1 \cdot n_1 + \nabla u_2 \cdot n_2) = \nabla u_1 \cdot n_1 = \nabla u \cdot n$