

■ Goal-orientated a-posteriori error estimators:

In practice, instead of the solution $u \in V_g$ (or $u \in V_0$ after homogenization), we are often interested in the value $l(u) \in \mathbb{R}$ of a linear functional $l \in V_0^*$ on the solution $u \in V_0$, i.e. we need an a-posteriori error estimator of the error:

$$(46) \quad |l(u) - l(u_h)| \leq ?$$

Examples:

$$1) \quad l(v) := \frac{(u - u_h, v)_0}{\|u - u_h\|_0} : l(u) - l(u_h) = \|u - u_h\|_0$$

$$2) \quad l(v) := \int_{\Omega_0} v(x) dx : \text{average of } v \text{ over } \Omega_0 \subset \Omega$$

$$3) \quad l(v) := \int_{\Omega} \delta_{\varepsilon}(x-y) v(y) dx : l(u) - l(u_h) \approx u(y) - u_h(y)$$

$$4) \quad l(v) := \int_{\Gamma_0} \frac{\partial v}{\partial N} ds : \text{Flux of } v \text{ through } \Gamma_0 \subset \Gamma = \partial\Omega ?$$

etc.

To derive a-posteriori error estimates for (46), similar to the a priori L_2 -estimate, we use a duality argument, i.e. we consider the auxiliary adjoint variational problem:

$$(47) \quad \text{Find } w \in V_0 : a(v, w) = l(v) \quad \forall v \in V_0$$

Now, take $v = u - u_h \in V_0$:

$$l(u) - l(u_h) = l(u - u_h) = a(u - u_h, w)$$

$$\begin{aligned} (\uparrow) \quad &= a(u - u_h, w - w_h) \quad \forall w_h \in V_{0h} \\ &= \langle F_1, w - w_h \rangle - a(u_h, w - w_h) \\ &\quad \uparrow \quad \uparrow \quad \quad \quad \uparrow \quad \uparrow \end{aligned}$$