

■ LAMÉ'sche Gleichungen im isotropen, homog. Fall:

a) Elastostatik:

Substituieren: (33) \rightarrow (34)_(ii) \rightarrow (32)_{sta}

$$\begin{aligned} (36) \quad f_i(x) &= -\sigma_{ji,j}(x) \stackrel{\downarrow}{=} -\lambda \varepsilon_{kk,i} - 2\mu \varepsilon_{ji,j} \\ &= -\lambda \frac{\partial}{\partial x_i} \left[\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right] - \mu \frac{\partial}{\partial x_j} \left[\frac{\partial u_1}{\partial x_i} + \frac{\partial u_i}{\partial x_j} \right] \\ &= -(\lambda + \mu) \frac{\partial}{\partial x_i} \left[\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right] - \mu \frac{\partial^2 u_i}{\partial x_j \partial x_j}, \text{ d.h.} \end{aligned}$$

$$\begin{aligned} (36)_{sta} \quad & -\mu \left[\frac{\partial^2 u_1}{\partial x_1^2} + \frac{\partial^2 u_1}{\partial x_2^2} + \frac{\partial^2 u_1}{\partial x_3^2} \right] - (\lambda + \mu) \frac{\partial}{\partial x_1} \left[\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right] = f_1 \\ & -\mu \left[\frac{\partial^2 u_2}{\partial x_1^2} + \frac{\partial^2 u_2}{\partial x_2^2} + \frac{\partial^2 u_2}{\partial x_3^2} \right] - (\lambda + \mu) \frac{\partial}{\partial x_2} \left[\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right] = f_2 \\ & -\mu \left[\frac{\partial^2 u_3}{\partial x_1^2} + \frac{\partial^2 u_3}{\partial x_2^2} + \frac{\partial^2 u_3}{\partial x_3^2} \right] - (\lambda + \mu) \frac{\partial}{\partial x_3} \left[\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right] = f_3 \end{aligned}$$

$$(36)_{sta} \quad -\mu \Delta u(x) - (\lambda + \mu) \nabla \operatorname{div} u(x) = f(x), x \in \Omega$$

$$(36)_{sta} \quad -2\mu \operatorname{div} \varepsilon(u) - \lambda \nabla \operatorname{div} u = f \text{ in } \Omega$$

$$\begin{bmatrix} \varepsilon_{1i} \\ \varepsilon_{2i} \\ \varepsilon_{3i} \end{bmatrix}$$

Dazu kommen die RB (1.-4. Art) (↓)

b) Elastodynamik:

$$(36)_{dyn} \quad \rho \frac{\partial^2 u_i}{\partial t^2}(x,t) - \mu \sum_{j=1}^3 \frac{\partial^2 u_i}{\partial x_j^2}(x,t) - (\lambda + \mu) \frac{\partial}{\partial x_i} \sum_{j=1}^3 \frac{\partial u_j}{\partial x_j}(x,t) = f(x,t)$$

$$i = 1, 2, 3 \quad (x,t) \in Q_T = \Omega \times (0,T)$$

+ RB (1.-4. Art) (↓)

+ AB $u_i(x,0) = u_{0,i}(x,0), \frac{\partial u_i}{\partial t}(x,0) = u_{1,i}(x,0), x \in \bar{\Omega}$