

- Under these assumptions, we conclude

$$B = \begin{pmatrix} B_1(x_1, x_2) \\ B_2(x_1, x_2) \\ 0 \end{pmatrix}, \quad x = (x_1, x_2) \in \Omega$$

↑
BH-relation (2)_{BH}

$$0 = B_3 = (\nabla \times A)_3 = \partial_2 A_1 - \partial_1 A_2 = 0$$

↑
 $B = \text{curl } A = \nabla \times A$

This condition is fulfilled with the ansatz

$$A(x) = A(x_1, x_2) = \begin{pmatrix} 0 \\ 0 \\ A_3(x_1, x_2) \end{pmatrix}$$

Furthermore, we automatically have the so-called COLUMB gauge:

$$\text{div } A = \nabla \cdot A = 0,$$

and

$$B = \nabla \times A = \begin{pmatrix} \partial_2 A_3 \\ -\partial_1 A_3 \\ 0 \end{pmatrix}$$

$$|B| = |\nabla \times A| = |\nabla A_3|, \quad \nabla = \begin{pmatrix} \partial_1 \\ \partial_2 \end{pmatrix},$$

$$\begin{aligned} \text{curl} \left(\underbrace{\nu(|\text{curl } A|)}_{\text{scalar}} \text{curl } A \right) &= \begin{pmatrix} 0 \\ 0 \\ -\partial_1 [\nu \partial_1 A_3] - \partial_2 [\nu \partial_2 A_3] \end{pmatrix} \\ &= \begin{pmatrix} H_1(x_1, x_2) \\ H_2(x_1, x_2) \\ 0 \end{pmatrix} = \begin{pmatrix} \nu B_1(x_1, x_2) \\ \nu B_2(x_1, x_2) \\ 0 \end{pmatrix} \\ &\quad \parallel \\ &\quad \begin{pmatrix} 0 \\ 0 \\ -\text{div}(\nu(|\nabla A_3|) \nabla A_3) \end{pmatrix} \end{aligned}$$